

A review of high impact weather for aviation meteorology

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A Review Of High Impact Weather For Aviation Meteorology

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Abstract

This review paper summarizes current knowledge available for aviation operations related to meteorology and provides suggestions for necessary improvements in the measurement and prediction of weather-related parameters, new physical methods for numerical weather predictions (NWP), and next-generation integrated systems. Severe weather can disrupt aviation operations on the ground or in-flight. The most important parameters related to aviation meteorology are wind and turbulence, fog visibility (Vis) and ceiling, rain and snow amount and rates, icing, ice microphysical parameters, convection and precipitation intensity, microbursts, hail, and lightning. Measurements of these parameters are also functions of sensor response times and measurement thresholds in extreme weather conditions. In addition to these, airport environments can play an important role leading to intensification of extreme weather conditions or high impact weather events, e.g., anthropogenic ice fog. To observe meteorological parameters, new remote sensing platforms, namely wind LIDAR, sodars, radars, and geostationary satellites, and in-situ observations at the surface and in the cloud, as well as aircraft and Unmanned Aerial Vehicles (UAV) mounted sensors, are becoming more common. Because of prediction issues at smaller time and space scales (e.g., <1 km), meteorological forecasts from NWP models need to be continuously improved. Aviation weather forecasts also need to be developed to provide information that represents both deterministic and statistical approaches. In this review, we present available resources and issues for aviation meteorology and evaluate them for required improvements related to measurements, nowcasting, forecasting, and climate change, and emphasize future challenges.

Keywords: Fog and precipitation visibility, Aviation Meteorology, Ice microphysics, Wind shear and Gust, Nowcasting and Forecasting

1. Introduction

Numerous studies have shown that weather severely impacts both civilian and defense aviation operations (e.g., Cook et al. 2009, Rudra et al., 2015, Gultepe et al. 2014; 2017a). The impact of atmospheric processes on aviation has been recognized since the 1900s. For example, Dines (1917) stated that “*thus it appears that the demand of the airman on the meteorologist is that he shall be able to forecast wind and fog, and to less extent clouds, on the route, the airman is proposing to follow.*” Presently, his comments on aviation-related parameters such as wind speed (U_h) and visibility (Vis) are still valid. Weather conditions that cause or contribute to the aviation accidents include wind, visibility/ceiling, high density altitude, turbulence, carburetor icing, updrafts/downdrafts, precipitation, icing, thunderstorms, wind shear, thermal lift, temperature (T) extremes, and lightning (NTBS 2010). Figure 1a shows a bar plot of the statistics of weather-related conditions from 1994 to 2003 that affect near-surface aviation operations; they are mostly wind and visibility (NTSB 2010). In Figure 1a, Vis, ceiling height (h_c), and precipitation related conditions occurred 485 times, wind and turbulence 1381 times, and icing and engine icing 150 times. This work suggested that from 2003 through 2007, there were 8,657 aviation related accidents and weather was a factor in 1,740 of these accidents. Figure 1b shows these parameters in percentiles also for 1994-2003 period; wind and visibility are still the most critical parameters. For small, non-commercial aircraft (Part 91 class) the primary cause of weather-related accidents from 2000-2011 was adverse winds, followed by low ceilings (h_c) (Figure 1c). At cruising levels of commercial jet aircraft (Part 121 class), this picture

is different, with over 70% of weather-related accidents from 2000-2011 being related to turbulence (Figure 1d) (e.g., Sharman and Lane 2016).

FIGURE 1

Delays and damage to aircraft during landing, taking off and high-level cruise due to hazardous weather can often occur. Gultepe et al. (2007) stated that a three-days freezing fog event in the UK resulted in about 50M US\$ in financial losses for businesses. Kessinger et al. (2006) also stated that aviation hazards for oceanic flights could impact both safety, economic efficiency, and productivity that lead to a total cost of about 62.7M US\$ per year. Cook et al. (2009) quantified the impact of weather factors on flight delays and find the contributing factors are highly airport dependent. Because of its importance to aviation, the National Oceanic and Atmospheric Administration (NOAA) National Weather Service (NWS) operationally provides forecasts of volcanic ash, cloud-top height, turbulence, lightning detection, precipitation, icing, and low clouds and fog. These forecasts are available to the public through their website (<https://www.aviationweather.gov/>).

Strong wind regions within jet streams called jet streaks (JS) can also affect aircraft operations (Uccellini and Johnson 1979; Uccellini 1980). They studied transverse circulations in the left exit and right entrance regions of jet streaks (which are the divergence regions) using Numerical Weather Prediction (NWP) models. Rose et al. (2004) detailed the interactions between upper and lower level jets, and the development of severe convective system. They stated that *"in the (jet) exit region, the geometry of this adjustment, combined with warm, moist, lower tropospheric air to the right and ahead of the jet streak and cool, dry air at the jet streak level, produced the differential advections that convectively destabilized the atmosphere."* Results of their work

suggest that development of severe convective storms can be influenced by mass and momentum fluxes along the propagation of an upper tropospheric jet streak. The development of a low-level jet (LLJ) usually was not considered for convection development in regard to synoptic-scale processes (Uccellini 1980). He stated that a systematic upper level flow pattern led to leeside cyclogenesis or a leeside trough, and that produced the strong pressure gradient forces needed for the development of LLJs. These studies suggested that improved knowledge of the relationships between JS and LLJ are important for understanding aviation weather hazards. Clear-air turbulence (CAT) and eddies related to jet streams can also be extremely important for mountainous and high-level flights near jet streams (e.g., Ellrod and Knapp 1992).

Reduced Vis, commonly caused by fog and precipitation (Gultepe et al. 2009), is also caused by dust and ash (Fig. 2). The transport of fine-grained dust by strong winds can occur over a broad range of time and spatial scales (Hadley et al. 2004) and impact not only Vis but have also been associated with engine failure.

FIGURE 2

Another critical hazard for aviation is aircraft icing (Isaac and Schemenauer, 1979; Guttman and Jeck 1987; Politovich 1989; Tafferner et al., 2003; Vivekanandan et al. 2001). Prediction of icing and deicing conditions (at the airports) is important for flight safety (Rasmussen et al. 2001; Black and Mote 2015). The accumulation of ice on aircraft before takeoff has long been recognized as one of the most significant safety hazards affecting the aviation industry. As little as 0.1 mm of clear ice over 2 minutes on a wing surface can increase drag and reduce airplane lift by 25-30% and reduce critical angle of attack by 8 degrees (https://aircrafticing.grc.nasa.gov/1_1_3_2.html; TC 2004)

Recently it has been realized that prevention of aircraft engine power losses due to high ice water content (HIWC) at higher elevations is essential for safe aviation operations (Leroy et al. 2016; 2017). The HIWC conditions, typically associated with deep convection, can cause engine power loss and air data events (affecting altitude and airspeed measurements) on commercial aircraft and need to be better characterized (Mason et al., 2006).

Improvements in aviation nowcasts and forecasts require better measurements and predictions of atmospheric parameters such as T, RH, wind and turbulence, icing, and Vis. These parameters are also related to climatic change over various scales. Therefore, for future research, the impact of climate change on meteorological parameters needs to be evaluated. For example, state-of-the-art research done by Goodman and Griswold (2017) suggest that temperature and pressure are important for aviation applications because they can impact aircraft drag and lift. Their work suggested suggests that aviation related impacts due to climate change need to be evaluated.

In another example, state-of-the-art global climate models were used in the Coupled Model Inter-comparison Project Phase 5 (CMIP5) simulating climate extreme indices described by the Expert Team on Climate Change Detection and Indices (ETCCDI) (Sillmann et al. 2001; 2013). In their work, the climatic indices based on daily T and precipitation amounts and rates were calculated using multi-model simulations. They found that the duration of cold and warm spells changed significantly since the 1950s. These works also suggest that climate change issues related to aviation operations are needed be evaluated in depth.

Global and regional weather prediction systems are needed to characterize the atmospheric state with the detail required to diagnose aviation related meteorological parameters.

Accurate predictions of the most dangerous processes related to Vis, turbulence, icing, convection and icing are essential to reduce in-flight injuries, structural damage, ground preparations for flights, and flight delays (e.g., Mecikalski et al. 2007, Sharman et al. 2012; Sharman and Lane 2016; Karstens et al 2018). Therefore, forecasting and nowcasting of aviation related meteorological parameters require a better understanding of the underlying meteorological processes. In this respect, knowledge of dynamics of upper-level and low-level jets, gusts, eddies, large-amplitude gravity waves, wind shear (including low level wind shear (LLWS)) and physics of cloud, fog, and precipitation can be very important for aviation mission planning and reducing financial losses (Uccellini and Johnson 1979; Zhou et al., 2004; NWSPD 2004; FAA 1988 Thobois et al 2018).

The goal of this review is to provide a summary of meteorological parameters, processes, and their prediction issues that are critical for aviation operations and that create challenges for forecasters. The critical parameters, processes, and analysis techniques of importance for aviation meteorology over various scales can be listed as

- Weather physics
 1. *Clouds and fog*
 2. *Ice and droplet microphysics*
 3. *Precipitation type and rate*
 4. *Freezing precipitation*
 5. *Icing, and ground deicing*
 6. *Frost*
 7. *Visibility and ceiling*
 8. *Blowing snow*
 9. *Convective activities and high ice water content*
 10. *Lightning*
 11. *Ash and dust*

12. Physical parameterizations

- *Weather Dynamics*

1. *Turbulence*
2. *Wind gusts*
3. *Waves*
4. *Jet streak intensity*
5. *Low Level Wind Shear (LLWS)*
6. *Microburst and tornados*
7. *Temperature and RH (relative humidity)*

- *Weather Forecasting (Multi-scale)*

1. *NWP time and space scale issues*
2. *Data integration*
3. *Artificial intelligence*
4. *Deterministic versus probabilistic methods for nowcasting*
5. *Integrated systems*
6. *Climate change modeling for aviation applications*
7. *Contrails and climate change*
8. *Reporting systems for aviation meteorological applications*

Considering the above items, NWP and climate change models play an important role on their own or integrated with observations to improve nowcasting and long-term forecasting of high impact weather events. Weather-related events such as fog, precipitation, clear-air and in-cloud turbulence, wind shear, gust, or icing may be related to changing climate conditions; if this is the case, for the next 50 years and beyond, aircraft flying conditions need to be considered to improve future aviation operations in response to extreme weather conditions.

In this overview, observations will first be summarized in the next sections and followed by discussions of NWP issues. Then, integrated methods will be introduced for aviation operation applications. In the final section, future issues and possible challenges related to observations, NWP, and climate change will be provided.

2. Observations

Observations are needed to discern and monitor meteorological parameters required for safe and efficient aviation operations. These are clearly needed in the terminal area of major airports and at cruise levels along flight routes, but also over wide areas to support a range of operational activities at smaller airfields and other remote locations. Helicopter air ambulance operation in remote areas, for example, represents a particular aviation weather need but one which creates significant forecasting challenges. Observations are important since some parameters are poorly diagnosed by NWP models at the scales needed by the aviation community. Clearly, observations are critical for providing monitoring and nowcasting related to aviation meteorological parameters for operations, and that cannot be predicted accurately with NWPs alone for lead times less than a few hours.

a) Ground based in-situ observations

The Aviation Automated Weather Observation System (AV-AWOS) originally suggested by Mandel (1975) provides meteorological parameters critical for aviation operations. Their proposed AWOS included additional parameters such as Vis and sky conditions. Later, Wade (2003) used the ASOS (Automated Surface Observing Systems) with a the light-emitting diode weather identifier (LEDWI) sensor to discriminate drizzle from other particles because precipitation rate from drizzle is usually less than 0.25 mm hr^{-1} . AWOS and ASOS were designed for unattended locations and use multi-sensor based algorithms (Ramsay et al 1999). Presently, these types of systems are continuously being improved by adding ultrasonic 3D wind systems, fog and precipitation sensors, as well as a portable ceilometer and a microwave radiometer (Ware et al., 2010; Gultepe et al., 2018). In addition to individual ground based in-

situ sensors, compact meteorological platforms were also developed for visibility, icing, fog, and precipitation type studies and applications such as Landolt et al. (2010) and), Rasmussen and Landolt (2008)), and Gultepe et al. (2018). Sims et al. (2000) used an integrated icing diagnostic algorithm (IIDA) that extensively utilized ground based in-situ systems with other observational and prediction systems. Similarly, supersites having various high-resolution ground based in-situ sensors (see next subsection) were also designed and used for operations.

b) Meteorological Supersites

Meteorological supersites with various sensors can be designed for specific goals related to atmospheric-hydrologic-oceanographic applications. Presently, these supersites with extensive ground based in-situ and remote sensing platforms have been used by researchers (Rasmussen et al. 2012, Gultepe et al. 2018, 2015; Ralph et al. 2014; Song et al., 2018). They were designed for aviation and forecasting validations/operations and included mainly observations representing Vis, U_h , turbulence, fog (FG), precipitation amount (PA) and intensity (PR), h_c , and cloud base height (h_b), and atmospheric profiling of meteorological parameters. Although usually located at a single point representing a small area around it, Gultepe et al. (2018) used their supersites with satellite (smaller weather observing sites) meteorological sites located within a 1 km perimeter radius. These observations provided statistical advantages to evaluate the scale issues related to measurements (Gultepe et al. 2018). The fact that most accidents occur around airports emphasizes that high resolution observations and areal representation of observations as done in above work are needed to improve aviation operations/NWP simulations.

c) Aviation Weather reports

Detailed airport observations can be used for making flight decisions by pilots and airport authorities, and for verifying forecasts. These observations usually are reported at 30-min or 60-min intervals as METARs (Meteorological Aviation Routine Weather Reports). At some airports, observations are also performed by using weather sensors autonomously (Gultepe et al. 2017). Weather forecasts for aviation operations are provided 2 hrs in advance based on trend-type forecasts (TRENDS) and over 2 hrs as terminal aerodrome forecasts (TAFs) (Jacobs and Maat 2004). Both TAFs and TRENDS contain information on U_h , Vis, cloud amount (C_a), h_b , and PR in the vicinity of the airport (Lynn 1997). The TAF can be issued as often as 12 times a day, including eight short TAFs with lead times from 1 to 10 h, and four long TAFs with lead times from 8 to 26 h (Jacobs and Maat 2004). In fact, most aircraft landing and takeoff decisions are made based on Vis and h_b , as well as wind conditions at the airports (Thobias et al 2018).

PIREPS (voice-transmitted pilot reports) are commonly used for to report icing and turbulence validations conditions and they are easily available but the PIREP reporting system was not proposed to be used for research or forecasting applications (Schultz and Politovich 1992a, 1992b; Kelsch and Wharton 1996; Schwartz 1996). They stated that inspection of PIREPS on turbulence and icing conditions reveal serious shortcomings that limit their usefulness. Lately, Bernstein et al. (2004) also stated that icing algorithms developed by many others overestimated icing amounts compared to PIREPS. These works suggest that the PIREP reporting system need to be improved, and Shultz and Politovich (1992a; 1992b) suggested that the FAA should consider creating a standard PIREPS system similar to the standard airways report made by surface weather reporting stations.

The TAFs and TRENDS are a good source of meteorological short time predictions and provide important support for forecasters. The TAF and TREND guidance and the AUTOTAF encoding software have been developed and implemented in close cooperation with the German company Meteo Service Weather Research (Knüppfer 1997; Jacobs and Maat 2004). Automated TAFs (Lynn 1997; Kilpinen 1994) use both direct NWP model outputs and model observation soundings (MOS; Glahn and Lowry 1972; Hart et al. 2004). The MOS-based methods usually use local data as in Jacobs and Matt (2004). In their work, an approach using observations from upstream locations and local data were used. Recently, blended algorithms for aviation operations have been suggested for improving short term forecasts (Bailey et al. 2016). A combined physical–statistical approach is often applied to low clouds and Vis predictions because of NWP short-term prediction issues. Herzegh et al. (2015) developed an expert system for Vis and cloud base (h_b) forecasts based on blended numerical model and observational data. They used current and historical METARs, GOES observations, NWP output from the Rapid Update Cycle (RUC), NCEP (National Center for Environment Prediction), and GFS (global forecasting system) runs, MOS forecasts and observational based rule methods for short term predictions.

d) Aircraft in-situ observations for icing

Research aircraft observations have been used for meteorological research extensively and here we only provided icing related research that generated significant improvements for icing measurements and predictions (Politovich 1989; Cooper et al. 1984; Sand et al. 1984; Isaac et al. and Schemenauer 1979; Isaac et al. 2005; Reehorst et al. 2005). For example, icing research

using aircraft platforms has been done by NASA Glenn, Canadian NRC (National Research Council) and EC (Environment Canada), NCAR, and University of Wyoming (Politovich 1989, 1996; Isaac et al. 2005; Serke et al. 2008; Reehorst et al. 2005). Bernstein et al. (2005) developed a Current Icing Algorithm (CIP) that utilized satellite, radar, surface, lightning and PIREPS observations together with 3D model hourly diagnostics to retrieve icing and SLD potentials. Figure 3a shows the conceptual diagram of their CIP algorithm that was adapted by FAA to be used operationally. Figure 3b shows an example of the splintering mechanism which generated many small droplets which then quickly froze during a wet snow case at $T=-3^{\circ}\text{C}$ on March 15 2013 during SAAWSO project took place over St. Johns' area, NL, Canada.

FIGURE 3

Based on aircraft in-situ observations of cloud microphysical parameters from aircraft, super cooled large droplets (SLD) impact on aviation certification was also emphasized by Politovich (1989), Isaac et al. (2005), and Bernstein et al. (2005). Politovich (1989) noted that substantial loss in rate of climb capability occurs in less than 10 mins when droplet number concentration, $N_d < 0.1-1 \text{ cm}^{-3}$ and mean volume diameter (MVD) at about 30-400 μm . Various icing types occurring at the surface of aircraft (Politovich 1996; Levis 1947; 1978) can significantly impact aircraft lift and drag forces that can lead to aircraft accidents. Lately, high ice water content is also found to be an important factor for aircraft engine icing (Leroy et al. 2016; Haggerty et al. 2018) and that needs to be further researched for operational applications.

e) Satellite Observations

Observations from passive radiometric imagers on operational satellites, such as the Geostationary Operational Environmental Satellites (GOES), are used extensively for evaluation

of meteorological events, nowcasting, and assimilation into NWP modeling systems. Both imager and sounder spectral radiances and relevant parameters derived from those radiances have been used extensively for these purposes. Examples of these products and potential applications are discussed below and in following sections.

In addition to passive radiometric imagers on satellites, active remote sensing platforms are also starting to be used on the satellites such as Cloudsat (Sun-Mack 2017; Deng et al. 2010) and CALIPSO (Smith 2014). The EarthCARE satellite mission is planned for 3D weather predictions by blending data from satellite based active sensors together with simulations from a 3D NWP model (Miller et al. 2014; Illingworth et al. 2015; Barker et al. 2011). The use of active sensors on these satellite platforms can provide insight information on cloud vertical structure, cloud top properties, and both microphysics and precipitation that can be blended with NWP simulations and ground based remote sensing platform data, and these can be used for aviation applications.

A variety of cloud properties are retrieved in near-real time using the Satellite Clouds and Radiation Property retrieval System (SatCORPS; <https://satcorps.larc.nasa.gov>) applied to global geostationary and polar orbiting satellite imager data (Minnis et al. 2008; Minnis et al. 2016) using adaptations of the algorithms of Minnis et al. (2011). The parameters retrieved include, among others, the scene identification of the pixel as either cloudy or clear, cloud top phase, cloud top and height temperatures and altitudes, cloud optical depth, and cloud particle effective radius. Recent additions include multi-layered cloud detection and properties, aerosol concentration over ocean, and convective cloud overshooting top identification (e.g., Bedka et al., 2017). These products are currently used for a number of aviation applications such as

aircraft icing (Bernstein et al. 2006; Smith et al. 2012), engine icing (Yost et al. 2018), cloud ceiling, and aviation and severe weather NWP assimilation (Benjamin et al. 2016; Jones et al. 2016). They retain significant potential for additional use by aviation systems. Improvements and enhancements in the retrieved products will expand that potential. For example, determining the separation between multilayer clouds (Sun-Mack et al. 2018) will improve chances of flying in clear air in multilayered conditions, while knowing the thickness of an icing layer, even when a thick ice cloud lies above the supercooled clouds (e.g., Smith 2014), will provide more choices for pilots faced with a hazard and few options.

Another source of cloud information is the algorithm developed by Sieglaff et al. (2011), which classifies each GOES pixel into groups of clear, liquid water, supercooled liquid water, mixed phase, opaque ice, non-opaque ice, and multilayered ice cloud (ice cloud is the highest cloud layer). These groups are described in the work of Pavolonis and Heidinger (2004) and Pavolonis et al. (2005). Details of the algorithm can be found in Pavolonis (2010a,b) and Heidinger (2010). Similarly, Liu et al. (2009) also defined cloud types based on China's FY-2C multichannel images and a neural network method. The satellite cloud analyses utilize clear-sky background correction, satellite zenith angle, and sensor spectral response functions. These were then used for the cloud mask and type algorithms to be portable to many sensors. The cloud-type algorithm relies on an upfront cloud mask algorithm to determine which pixels contain cloud Heidinger (2010). The satellite observations can usually lead to detection of cloud phase, fog, icing, and turbulence from spectral radiance measurements (Minnis et al. 2011; Pavolonis et al. 2010a, 2010b, Pavolonis and Heidinger 2004; Smith et al. 2012, Gultepe et al. 2007; Ellrod and Pryor 2018). Integrated systems based on in-situ observations, NWP model output, as well as GOES

satellite products can improve monitoring fog conditions that include fog area and its intensity (defined by optical depth).

A number of efforts have focused on detecting and analyzing overshooting tops using GOES products from VIS (Visible) and IR (Infrared) imagery (Nair et al. 1998; Mecikalski et al. 2007; Bedka et al. 2010). In addition to garnering information directly from the VIS reflectance and IR brightness temperatures, and their differences with other channels to detect overshooting tops, texture analyses have allowed the discrimination of convective cloud features within a shield of stratus-like clouds that often cover a convective complex. Figure 4a,b,c show the texture-based clustering analysis results based on Mecikalski et al. (2007). In this figure, large-scale convective structures are visible, along with smaller cumulus and stratiform clouds. Figure 4d shows a cloud-top pressure product developed through the combination of height estimates from the CO₂ ratio technique for the upper clouds and from the older "IR window" technique for lower clouds (Schreiner et al. 1993; Donovan et al. 2007). The IR window technique uses the 11 μ m thermal IR temperature to estimate T at cloud top, and combines it with an atmospheric sounding to get T to a corresponding pressure and height. The isolated overshooting cumulus tops were also detected as in red. Improvements on this technique have been reported by Bedka and Khlopenkov (2016).

FIGURE 4

The reasons for recent advances in aviation safety due to meteorological satellites are their ability to provide critical information of weather conditions, the enhanced speeds of data transmission and computer analysis, better calibrated high-resolution satellites, algorithm maturity, and more reliable validation data. Therefore, hazards, such as turbulence, in-flight

icing, convective storms, and volcanic ash, can be diagnosed from satellite-based observations, and are used extensively in national aviation forecasting systems (Mecikalski et al. 2007). The algorithms are always subject to improvement based on validation studies using in-situ observations, passive (e.g., microwave) and active (radar and lidar) remote sensing, and integrated observations.

The aviation products in NOAA NWS operations include volcanic ash, cloud-top height, turbulence, lightning detection, precipitation, icing, and low clouds and fog (Schmit et al. 2017; Goodman et al. 2012). Recently, with the introduction of GOES-16 (16th Geostationary Operational and Environmental Satellite) products, lightning detection for aviation applications will also be possible. New sensors available on GOES-16 include total lightning detection and mapping of in-cloud and cloud-to-ground flashes (from the Geostationary Lightning Mapper (GLM; Goodman et al. 2012; Goodman et al. 2011). It is expected that the use of GLM data for severe weather research can improve aviation weather forecasts.

Airborne ash from volcanic eruptions can also be a major threat to aviation safety (Casadevall 1994; Miller and Casadevall 2000; Hufford et al. 2000; Simpson et al. 2000). VIS satellite imagery can be used to detect ash clouds, but not to discriminate ash particles from natural water and ice clouds. Ash detection and discrimination is accomplished via multispectral infrared image analysis. The multispectral technique uses a strong 12- μm absorption signature (e.g., Prata 1989; Hufford et al. 2000; Mecikalski et al. 2007), leading to a negative value of the 11-12 μm brightness temperature difference. As discussed by Ellrod et al. (2003), this technique is often termed as the reverse-absorption method. Volcanic eruptions usually release high concentrations

of SO₂ having strong absorption bands at 7.3 and 8.6 μm that can aid the ash detection algorithms. SO₂ absorption channels are presently available on the high-resolution Moderate Resolution Imaging Spectroradiometer (MODIS) imager and the Atmospheric Infrared Sounder (AIRS) sounding instrument in polar orbit on NASA's Earth Observing System (EOS) satellites, and with the next-generation operational geostationary satellites (e.g., Himawari-8, GOES-16) (Goodman et al. 2010; Hutchison et al. 2008; Mecikalski et al. 2007; Schmit et al. 2005).

The National Aeronautics and Space Administration (NASA) developed an Advanced Satellite Aviation-Weather Products (ASAP) system that transfers new satellite-observing products into operational use based on a collaborative effort with the FAA's existing Aviation Weather Research Program (AWRP) (Mecikalski et al. 2002; 2007). The ASAP ash detection algorithms are currently being developed at UW-CIMSS. The standard reverse absorption technique (Prata 1989) that uses channel differencing between 11-12 μm BBT (Black Body Temperature), is supplemented with VIS at 0.65 μm and near-IR at 3.75 μm channels for volcanic ash detection (Pavolonis et al. 2006). This new algorithm does not depend on a negative value of 11-12 μm brightness temperature difference because this difference is often absent in tropical eruptions and it is used globally

Hadley et al. (2004) studied the rare resuspension of volcanic ash and dust from the Katmai area volcanic eruption by strong winds on 20–21 September 2003 and found that the ash/dust cloud created severe disruptions to aviation operations while aircraft were attempting to avoid dust/ash clouds. Another volcanic ash event occurred from Mount Cleveland, Alaska when it erupted on 19 February 2009 and led to several severe disruptions of commercial aircraft traffic. The use of

satellites for ash detection has recently become very common but issues with data analysis are still important, and more work needs to be done. Simpson et al. (2000) also suggested that detailed volcanic ash PIREPs are needed to improve real-time awareness for aviation routing.

Two major regions of dust originate from Asia (Gobi and Mongolian deserts) and Africa (Sahara Desert). Dust events usually occur when surface winds exceeding 5 m s^{-1} (Hadley et al. 2004) loft the dust particles into the atmosphere where they can travel across either the North Pacific or the tropical Atlantic Oceans, respectively (Gillette 1978). Dust can also affect radiative forcing and world climate (Myhre and Stordal 2001), as well as aviation safety (Simpson et al. 2003).

Satellite-based wind vectors can be used to infer wind shear, turbulence, and convective activity (Mecikalski et al. 2007;). In the northern latitudes, polar winds are needed for better aviation flight planning because of lack of other observations and issues with NWP through assimilation of observations (Key et al. 2003). Polar winds from satellite based retrievals (Turner and Warren 1989; Herman 1993) can be highly effective for aviation management because of the lack of airport availability after long flight times over Arctic regions. Santek et al. (2010), using the National Centers for Environmental Prediction (NCEP) Global Forecast System (GFS), ran an experiment during August and September 2004, with and without the Terra satellite based MODIS (Moderate Resolution Imaging Spectroradiometer) Polar winds. From the five cases examined, it was determined that the addition of the polar winds modifies the mass balance in synoptic-scale waves near the polar jet streams that can affect flight planning.

f) LIDAR observations

LIDAR-based observations are related to wind components based on motion of air particles, thin fog and clouds, backscattering ratio, and depolarization. Excluding deep and heavy in-cloud water content conditions, they can provide 3D wind components for terminal weather forecasts when they are used in specific scanning modes such as low elevation angles. They can also provide wind profiles to analyze turbulence, gust, and aerosol loading at higher levels.

LIDAR-based wind retrievals using the Doppler concept became important in the 1980s. Bilbro and Vaughan (1978) and Bilbro et al. (1984) used a coherent Doppler system to obtain 2-D wind components from an installation onboard the NASA Convair 990. For a recent overview of the use of LIDARs in atmospheric research see Reitebuch (2012). Recently, LIDARs have been used for aviation research and operations (Gultepe et al 2017; Fuertes et al 2014; Tucker et al 2009, and Sathe et al. 2011). Tucker et al. (2009) used a High Resolution Dial LIDAR (HRDL) at 2.022 μm to study mixing height, turbulence, shear, and aerosol profiles. The HRDL velocity and backscattered signal measurements collected during a ship-based field campaign were used in wind analysis. In their work, wind air velocity variance profiles were used for mixing height estimation. This was a significant development of LIDAR use in the aviation research. Their results are shown in Figure 5 which shows time-height cross sections of σ_w^2 (vertical air velocity variance) and h_o (a), horizontal wind shear height (h_{spd}) (b), and multiple products related to shear and mixing height (c). Their work also suggested that a motion-stabilized scanning coherent Doppler LIDAR can perform azimuth scans, elevation scans, and zenith stares to obtain

the velocity field in three dimensions from a moving platform and that can improve aviation forecasts over the coastal regions.

FIGURE 5

Lately, Doppler Lidar wind measurements have been used for aircraft operations at airports (Thobois et al. 2018; Chan and Shao 2007; Chan et al. 2006) to diagnose wind shear, gust, microburst, and aerosol loading, which can be serious issues for aviation operations (Sharman et al., 2012, Kessinger et al. 2006, Wong et al. 2013, Kim et al. 2015, 2016, and Gultepe et al. 2018). But, presently Doppler lidars are used mostly in an experimental mode at the airports. Among Doppler LIDARs commercially available are 1) Halo LIDAR (Gultepe et al 2016), 2) Leosphere Cube LIDAR (Thobois et al 2018), and 3) Lockheed Martin Coherent Technologies (LMCT) LIDAR (<http://www.lockheedmartin.com>). These LIDARS provide Doppler wind measurements in various scanning modes. The Halo LIDAR observations were used to obtain backscatter ratio and VAD winds, and compared to CL51 ceilometer backscatter ratio observations during an ice fog event occurred nearby Heber City, UT, are shown in Figs. 6a and 6b, respectively. The Cube Doppler LIDAR from Leosphere Inc is designed specifically for aviation applications and provides related aviation wind and turbulence parameters continuously (Tobia et al., 2018). Examples of turbulence estimation from LIDARs can be found in e.g., Frehlich and Cornman (2002), Hill et al. (2010), Chan (2016), and Vrancken (2016).

FIGURE 6

LMCT LIDAR at 2 μm (latest one at 1.6 μm) uses pulsed laser light to detect particles and varying weather conditions in the atmosphere (Bluestein et al 2010; De Wekker et al. 2012; Bluestein et al 2014). The company has developed a pulsed coherent 2 limiting diode-pumped solid-state LIDAR receiver on an injection-seeded, Q-switched, 2 micron laser that meets Navy

requirements for remote sensing, moderate range, high spatial resolution wind field measurements around air stations and aircraft carriers.

g) Sodar observations

The SONic Detection And Ranging (SODAR) is often used for atmospheric profiling. SODAR uses the Doppler concept to estimate 3D wind profiles from the propagation characteristics of high frequency sound waves to investigate the atmospheric boundary layer and has been used since 1980s. For example, SODAR data were used to investigate the boundary layer dynamics in detail by Motta, et al. (2005) , Sumner and Masson (2006), Gottschall and Peinke (2008), and Van den Berg (2008). In these works, atmospheric stability, wind shear, and turbulence intensity were analyzed for wind energy production. Gerz et al. (2009) and Chan (2014) used SODAR observations specifically for nowcasting applications to investigate aviation related meteorological events, such as fog, gust, and wind shear, at the Frankfurt International Airport and at the Hong Kong International Airport, respectively. Silva et al. (2016) developed a conceptual model to investigate wind profile changes using 234 runway cases that utilized a SODAR and surface meteorological station data from the Guarulhos International Airport (GIA) São Paulo, Brazil. França et al. (2018) also used SODAR data for training a neural network model for nowcasting the low level wind profiles at the lead times of 45 mins for the GIA Airport.

h) Radar observations

Doppler and dual-polarized radars (and connectional ones) such as X (8-12GHz), C(4-8 GHz), and S (2-4GHz) band radars have been used to detect convective activity and intensity, as well as

icing conditions within clouds to identify particle microphysical characteristics (Merritt, 1969; Rasmussen et al 1992; Ryzhkov et al. 2002; Schuur et al. 2012; Smith et al 2016; Hubbert et al 2018). Storm precipitation type and intensity are related to Vis, icing levels, and convective intensity, and these are all important for aviation operations. Smith et al. (2016) developed the Multi-Radar Multi-Sensor (MRMS) system that is operational at the National Centers for Environmental Prediction (NCEP). The MRMS system consists of the Warning Decision Support System–Integrated Information (WDSS-II; Lakshmana et al. 2007) suite. The severe weather and aviation products, as well as the quantitative precipitation estimation (QPE) products, are created by the National Mosaic and Multi-Sensor QPE (NMQ; Zhang et al. 2011) system.

Dual polarized Doppler radars such as the Weather Surveillance Radar-1988 (WSR-88D) radar and radars with dual polarization capabilities such as S-band radars (S-Pol) can improve rainfall estimates, discriminate ice and rain, identify hail cores and updraft regions, and as a result in general increase data quality (Hubbert et al. 2017, 2018; Chandrasekar et al. 2013; Kumjian 2012 and 2013a,b). Hubbert et al stated that the Weather Surveillance Radar-1988 Doppler polarimetric (WSR-88DP) is not able to scan along vertical planes (RHIs), and although this may be acceptable for operational purposes, it does limit research objectives. The S-Pol has increased range resolution using 1- μ s transmit pulse length that corresponds to 150-m compared to WSR-88DP's 250-m resolution. The result is that S-Pol is able to obtain high-resolution, high-data-quality measurements related to storm structure and microphysics. In the end improved storm physics and dynamical information can further be used for aviation operations that concern with

wind and turbulence, gust, icing, high IWC, and low visibilities, as well as lightning and particle type and phase.

Dual polarized radars can effectively be used for melting layer and particle phase and type detection (Schuur et al. 2012; Ryzhkov et al. 2002, 2013; Van Den Broeke 2016; Hubbert et al 2018). The sensitivity of this radar decreases with reducing particle size. Particle phase and 3D wind structure can improve forecasting and nowcasting algorithms related to gust and low Vis. Van Den Broeke et al. (2016) stated that quasi-vertical profiles of the polarimetric radar variables could improve short term forecasts in winter. Hubbert et al. (2018) summarized polarimetric variables used in S-Pol data interpretation. Figure 7 shows range-height plots of related polarization, reflectivity, and Doppler velocities from a convective storm. Using Z (indicates core of storms), Z_{DR} defined as differential reflectivity (reflectivity weighted particle mean axis ratio of particle distribution), V_D (particle motion), and Φ_{DP} defined as differential phase (particle microphysics), LDR defined as linear depolarization ratio (particle shape), K_{DP} defined as specific differential phase (particle type and shape), ρ_{HV} defined as co-polar correlation coefficient (particle type and phase) ρ_{co-x} (cloud electrification). A combination of these variables can be used for storm physics and dynamics as suggested by Hubbert et al. (2018) that can further be used for operation applications.

FIGURE 7

Doppler radar applications for fog and Vis work can be used to provide accurate nowcasting products for aviation weather. Hamazu et al. (2003) used a 35-GHz scanning Doppler radar (Ka band, 27-40 GHz) for fog observations and prediction. They used the three-dimensional structure of reflectivity and velocity field in a fog event for short term predictions. The characteristics and

performance of an 8.6-mm-wavelength Doppler radar were described in observing sea fog. The Doppler radar measurements were also used for eddy dissipation rate predictions. Aircraft based turbulence measurements with well-coordinated Doppler radar spectral width measurements were used to estimate energy dissipation rates within thunderstorms anvils (Meischner et al. 2001; Cohn 1995). The lower limit detectable dissipation rate with the C-band Doppler radar is found to be about $10^{-3} \text{ m}^2 \text{ s}^{-3}$. Techniques for deriving Doppler radar estimates of energy dissipation rate has also been described by Williams and Meymaris (2016), and comparisons to in situ aircraft measurements are provided in Dehghan et al. (2014). Doppler spectrum width as measured by operational weather radars was used for both turbulence and wind shear estimation and could possibly be used for severe weather warnings (e.g., Hocking and Hocking 2018).

The K-band radars (Ku (12-18GHz), K(18-27 GHz), Ka (27-40 GHz) (Matrosov 1995; Loffler-Mang et al. 1999), and W-band radars (40-300 GHz, Gossard et al. 1997; Mead et al., 1989) have been used for cloud microphysical structure but usually they are not used operationally for Aviation operations. When large water mass content exists within clouds, these radar beams can be attenuated significantly. Presently, Ku and Ka band radars are part of active sensors used on GPM satellite that focuses on precipitation from the space (Skofronick-Jackson et al. 2017). These cloud radars can provide specific information for cloud and fog properties, as well as precipitation information but they are operationally expensive and mostly they are used for experimental research.

i) Atmospheric thermodynamic profiling

1) Water vapor and temperature profiling

Water vapor profiling is critical for weather forecasting because of the detail it can provide about cloud formation, nucleation processes, and storm development. Ferrare et al. (1995) provided a

summary of water vapor measurements that included satellite-based retrievals (Soden et al. 1994), microwave (Han et al. 1994), differential absorption LIDAR (DIAL) (Ismail and Browell 1994), and Raman LIDAR (Ansman et al. 1997; Whiteman et al. 1992). The difference between the Raman LIDAR and DIAL LIDAR is that the former measures only vapor mixing ratio (q_v) and the latter measures both q_v and T . Recent overviews of the DIAL can be found in Wirth (2012), and Fix (2012). The work of Wulfmeyer (1998) used a DIAL system developed at the MaxPlanck Institute (MPI) in Hamburg for the measurement of absolute humidity profiles and this has been improved through the work of many others (Wulfmeyer et al. 1995, Wulfmeyer and Bosenberg 1996; Wulfmeyer 1998', and Wulfmeyer and Bosenberg 1998).

The radar–RASS system (Radio Acoustic Sounding System) was developed at the University of Hamburg for measuring wind profiles in the lower troposphere and virtual temperature profiles in the boundary layer (Peters et al. 1988; Peters 1990). The turbulent variables measured with the DIAL system and the radar–RASS include vertical profiles of water vapor and vertical wind variance and latent heat flux that uses the eddy correlation technique. Neely and Thayer (2011) also used a similar method to study high level moisture profiles over Greenland, which can be used to detect thermal and dynamical instabilities leading to particle formation and eventually cloud formation.

The main competitor to the use of Raman systems for water vapor profiling is the differential absorption LIDAR method (DIAL). In this method, two wavelengths of laser light are used. One wavelength is absorbed by the molecule of interest; one is not. Because the two wavelengths are nearly the same, their atmospheric transmission is similar, except for absorption by water vapor

molecules (e.g., Fix 2012). Eichinger et al. (1999) used a Raman LIDAR to study ABL vapor profiles. The DIAL systems have some inherent advantages over Raman LIDARs profiles. The DIAL systems are generally smaller, lighter, and use considerably less energy than Raman LIDAR systems. They can be used for aircraft based research because atmospheric backscatter increases with a range in a downward-looking system, and thus partially compensates the decrease in signal strength with range. Because of the strong atmospheric attenuation of both UV and near-UV light channels, DIAL systems in the near-IR are better suited for deep atmospheric water vapor sounding profiles.

The Profiling microwave radiometers (PMWRs) have been also used for measuring q_v and T , as well as Liquid Water Content (LWC) which can be important for supercooled droplet detection and icing conditions (Solheim et al. 1998; Gultepe et al. 2014). The Radiometrics Inc. MP-3000A profiling radiometer is used to retrieve the profiles of T , RH with respect to water (RH_w), and LWC over Whistler Mountain (Ware et al., 2013; Gultepe et al 2014). The MP-3000A observes 21 K-band (22–30 GHz) and 14 V-band (51–59 GHz) microwave channels at multiple elevation angles, one zenith infrared (9.6–11.5 μm) channel, and surface temperature, humidity and pressure sensors. The atmosphere is semi-transparent in the K-band and lower V-band channels during non-precipitating conditions, receiving emission from the atmosphere in addition to cosmic background radiation. The PMWR provides T , q_v , RH_w , and LWC in the vertical (Bianco et al., 2005) but it needs to be validated using in-situ observations; this may be a challenge for stratiform clouds because of a weak signal from cloud water content compared to convective clouds' water content. Integrated liquid water retrieval from microwave radiometer observations near the 22.2 GHz water vapor molecular resonance is well established (Westwater,

1978; Turner et al., 2007). Integration of above remote sensing platforms can cover atmospheric thermodynamic conditions over the airports, and when they are combined with LIDAR and Radar observations, as well as with surface in-situ observations, both clear air and cloud regions nearby airports can be analyzed for aviation hazards.

Atmospheric thermodynamic profiling for operational icing research is important to prevent aviation accidents. Serke et al (2008; 2014) developed a compact small platform attachable to a radiosonde balloon that is similar to the radiosonde unit. With this system they were able to measure liquid water content profile within the clouds. This state-of-the-art icing platform promises to develop future balloon based systems to be used for icing and thermodynamic profiling.

In Arctic regions, profiles of water vapor can be important for aviation nowcasting applications, such as fog and low clouds, and storm development. The Arctic LIDAR Technology (ARCLITE) facility, having a Rayleigh/Mie/Raman LIDAR system, has been in operational use since 1993 at the Sondrestrom Upper Atmospheric Research Facility, Kangerlussuaq, Greenland (Neely and Thayer 2011). In their research, molecular and aerosol backscatter is measured at 532 nm to retrieve T profiles, and a Raman channel for molecular nitrogen (608 nm) to determine aerosol extinction values. A Raman water vapor channel at 661 nm was used to measure water vapor mixing ratio profiles into the upper troposphere. They suggested that use of Raman LIDAR technology for ABL water vapor soundings is available and is comparable with balloon based profiles. Because measurements of water vapor profiles in Arctic environments are rare, DIAL

and Raman LIDAR based methods for water vapor profiling can improve fog, cloud, and Vis for short term predictions.

2) UAVs thermodynamic profiling

Unmanned aerial vehicles (UAVs) are becoming very popular for meteorological and environmental applications (e.g., Bottyan et al. 2013; 2016; Gultepe et al. 2018). UAVs can be accurately controlled by ground based pilots to move the UAVs in certain flight paths that represent constant altitude flights and profiling models. Measurements from the UAVs include various meteorological parameters similar to a radiosonde sounding. In addition to T, RH_w, pressure (P), altitude (z), Vis, U_h and direction (Gultepe et al 2018; Bates et al 2013). They may also be used for air quality monitoring of trace gases such as O₃, CO₂, CO, and PM_{2.5}, and earth surface morphology, including snow coverage, water accumulation, and surface temperature. Measurements from UAVs have also been used to estimate temperature and velocity turbulence levels (e.g., Lawrence and Balsley 2013). For aviation operations, UAVs can be used near airports to gather weather information that can help to improve the NWP's initial conditions and monitor weather conditions in real time. Although they have limitations on flying time (e.g., quadcopter UAVs), 3D wind measurement issues, and flying into the clouds and fog, they are being developed for extreme weather conditions (with fixed wing UAVs), and in the future they can fly into the cloud systems (Wick et al. 2018; Wurman et al. 2012), and may have potential for continuous and accurate weather measurements. Uncertainty in UAV measurements can be significant for wind related parameters because of the impact of the rotors or body of the UAV on airflow (Gultepe et al. 2018). Therefore, additional work is needed to improve wind measurements from UAVs (Reineman et al. 2013; Gultepe et al. 2018). Various meteorological

parameters from the UAVs are also being used by others (Jonassen et al. 2012) for boundary layer (BL) research. These parameters include aerosol number concentrations (N_a), fog droplet number concentration (N_d), Vis, particle spectra, and air quality parameters (Boer et al. 2017; Gultepe et al. 2017).

The UAVs can be used to improve NWP predictions for meteorological applications that include wind speed, Vis, RH and T. A work by Jonassen et al. (2012) stated the importance of the use of UAV systems to improve NWP simulations, and this area of research is needed for further development of aviation products.

3) Aircraft based in-situ systems

Commercial aircraft flights can provide additional observations of meteorological parameters related to aviation operations. Automated meteorological reports from on board sensors mounted on major commercial air carriers are generally referred to internationally as Aircraft Meteorological Data Relay (AMDAR) reports. In the U. S. they are also called Aircraft Communication Addressing and Reporting System (ACARS) reports, and the meteorological data is referred to as Meteorological Data Collection and Reporting System (MDCRS) (Moninger et al. 2003). The MDCRS reports are essential for NWP model initializations, especially for rapidly updated models such as the NOAA's WRF-RAP model (Benjamin et al. 2016). Also, the commercially available Tropospheric Airborne Meteorological Data Reporting system (TAMDAR), utilizing commercial flight data collection systems, provides a data base for aviation parameters such as wind, turbulence, temperature, etc. (Moosakhanian et al. 2006). The TAMDAR data (Moninger et al. 2010; Benjamin et al. 2006a,b; Fournier 2006) used with the RUC model over three year period revealed that **TAMDAR** data significantly improved RUC

forecasts. The meteorological parameters obtained from AMDAR and TAMDAR are similar to radiosonde measurements. TAMDAR also provides EDR (defined as energy dissipation rate to the $1/3$ power) estimates and icing detection amount. Moninger et al. (2010) over two 10-day periods provided results on meteorological parameters such as T, RH_w, and wind representing winter and summer conditions. The assessment showed that TAMDAR's impacts on 3-h RUC forecasts of temperature, relative humidity, and wind are found to be positive and, for temperature and relative humidity, the improvements were substantial.

Estimates of turbulence are also available from selected AMDAR flights as either derived equivalent gust velocity (DEVG), or EDR. Both of these turbulence estimation algorithms are summarized in Sharman (2016); for more detailed discussions see Sharman et al. (2014), Cornman (2016), and Kim et al. (2017). Stickland (1998) compared DEVG and EDR estimations for aviation applications, and even though both are supposedly aircraft-independent, he recommended the use of EDR for aviation operations. This recommendation has been followed up by requiring EDR to be the international standard for aircraft turbulence intensity reporting (ICAO 2001). EDR can also be estimated from second-order structure functions of the AMDAR winds (Frehlich and Sharman 2010), and possibly through Mode-S and ADS-B (Automatic Dependent Surveillance-Broadcast) messages (Kopec et al. 2016). So far though, these techniques have not been implemented operationally.

Another experimental commercial aircraft on-board system is the Backscatter Cloud Probe (BCP) that provides information about the concentration and size of ice crystals in clouds. The probe has been tested as part of the European Research Infrastructure program, IAGOS (In-

service Aircraft for a Global Observing System). Bestwick et al. (2015) demonstrated that the BCP measurements could be used to diagnose HIWC conditions, providing pilots with an onboard warning of an HIWC hazard. The sensor output could also be broadcast as part of other systems such as TAMDAR. Additional research is needed for use of the BCP operationally.

A number of experiments including the EU High Altitude Ice Crystals (<http://www.haic.eu>) and North American HIWC Projects (Strapp et al. 2016), were developed and executed using remote sensing and airborne in situ assets. Leroy et al. (2016; 2017) characterized the ice particle size distributions in HIWC using in situ measurements while Protat et al. (2014) used airborne C-band polarimetric radar data to profile the cloud ice water content within HIWC clouds. Yost et al. (2017) developed a prototype method for detecting HIWC conditions using geostationary satellite data coupled with in-situ total water content (TWC) observations obtained during aircraft-related icing projects. They developed three satellite-derived parameters that were used for determining high HIWC probability conditions. These include 1) the overshooting convective updraft or textured anvil cloud, 2) tropopause-relative infrared brightness T, and 3) daytime-only cloud optical depth. Their results are consistent with aircraft flight reports obtained near deep convective storms and cirrus anvils (Lawson et al. 1998; Mason et al. 2006; Bravin et al., 2015). Prediction of HIWC conditions needs to be improved by combining NWP model simulations and remote sensing results. Both require more in-situ observations to establish reliable statistics (Gultepe and Heymsfield 2016; Haggerty et al., 2018).

Overall, observations from various observational platforms summarized above can contribute to improvements of aviation nowcasts, weather reports, and NWP predictions extensively, and they

may eventually lead to improvements in aviation operations, but their limitations should also be considered.

3. NWP models

NWP models are important for improving aviation related nowcasts (defined here as lead times ≤ 3 hrs) and forecasts over medium and large lead times (>3 hrs). Their short-term success in nowcasting is strongly related to the incorporation of observations. An NWP model's ability to accurately simulate atmospheric dynamical and physical processes depends critically on several initialization parameters and PBL characteristics (Jonassen et al. 2012). The spatial grid resolution and the parameterization schemes used to represent processes related to clouds, radiation, precipitation, and turbulence are most crucial ones (Pleim and Xiu 1995; Alapaty et al. 2001; Teixeira et al. 2008; Lin et al 1983; Tomita 2008; Khairoutdinov and Kogan, 2000; Ferrier et al. 1994; Herrington et al. 2013; Pu et al. 2018).

The quality of the data used to initialize and force the model for predictions is also essential for the success of numerical model simulations. Many models are initialized from global atmospheric analyses or forecasts (e.g., from the Global Forecast System (GFS) or the European Centre for Medium-Range Weather Forecasts (ECMWF)) with low resolutions typically being 15–50 km in the horizontal and 3–6 h in time. Therefore, scale issues play an important role for predictions over short times scales. These atmospheric data may not be accurate enough for high-resolution simulations of local features such as fog or turbulence, and these can be sensitive to small errors in the large-scale flow (Nance and Durran 1997; Belair et al. 1998; Khairoutdinov and Randall 2006; Kucken et al. 2012; Selz and Craig, 2014). Because of these errors, data

assimilation techniques using detailed and accurate observations are necessary for generating more accurate initial conditions for NWP models for all scales. The quality of the analysis data for model initialization depends mainly on the data assimilation techniques, which compile the short-range forecasts (from the NWP model to generate the first guess), observations, and their error statistics (Kalnay 2003; 1996). Also, the quality and coverage of the observations used to create the analysis have influences on the accuracy of the analysis (e.g., Langland et al. 1999). Observations can be particularly sparse over areas such as the world's oceans and the Arctic and Antarctic, and that likely leads to large uncertainties in predictions.

a) downscaling

Because of scale issues model output can include large uncertainties in the predicted parameters. The winds can be to some extent reproduced by numerical downscaling of a state-of-the-art ECMWF operational analysis using the WRF model (Jonassen et al. 2012). However, by assimilating profile data obtained from the UAS (Unmanned Airplane Systems) at Eyrarbakki in southwest Iceland in their analysis, substantial improvements of wind, T, and RH in the region were achieved. Vislocky and Fritsch (1995) developed a statistical model to predict parameters that are important for aviation and used automatic nonlinear/linear methods that use NWP MOS (Model Output Statistics) data. Their method was time consuming, but with increasing computer resources their method can improve integrated predictive systems over various scales.

b) Initial conditions

Initialization of NWP forecasts requires assimilation of various observations for regional models as well as short-range NWP model outputs (Kalnay 2003; 1996, Warner 2011). For instance,

inputs into the operational MRMS-Severe/Aviation system (Smith et al. 2016; Wen et al. 2017; Benjamin et al. 2009) include radar data from the U.S. WSR-88D network, GOES radiances and cloud properties (Minnis et al. 2008), surface terrain elevation information, the National Lightning Detection Network (Orville 2008; Smith et al. 2016), and hourly surface and upper-air analyses from the Rapid Refresh model (Benjamin et al. 2009). Several individual and automated algorithms have been developed using the MRMS system to obtain an integrated forecasting and analysis system that provides real-time products applicable to severe weather and aviation nowcasting. In this system, automated algorithms based on data from multiple radars provided better information with greater temporal resolution and spatial coverage than a single-radar.

c) Turbulence

Since operational NWP models are too coarse to even begin to resolve turbulence scales relevant for aircraft, post-processing algorithms applied to NWP model output is commonly used to infer regions of likely turbulence. These inferences are based on “diagnostics” of turbulence derived typically from spatial gradients of various NWP model output variables. In the past, various post-processing turbulence diagnostics have been proposed, and some are used operationally. For example, the TI (Turbulence Index) diagnostic developed by Ellrod and Knapp (1992) uses NWP model output velocity fields to derive a diagnostic based on the product of horizontal wind deformation and vertical wind shear. The TI has been used by the Aviation Weather Center (NOAA/AWC) (Behne 2008), the Air Force Weather Agency (Brooks and Oder 2004), the Met Office in the United Kingdom (Turp and Gill 2008), and the Canadian Meteorological Centre (Turcotte and Verret 1999). The physical basis of TI was considered initially due to frontogenesis through the process of dynamical deformation (Mancuso and Endlich 1966; Ellrod

and Knapp 1992). The hypothesis suggested that stronger horizontal thermal gradients caused by frontogenesis can lead to an increase in the vertical shear of the horizontal wind through the thermal wind relation, and indicates that a higher potential for CAT occurs via the local reduction in Richardson number (Ri) and consequent production of Kelvin–Helmholtz instability). Commercial aircraft encounter severe, or greater, turbulence about 5000 times each year. These incidents resulted in tens of millions of dollars in injury claims per year (Sharman et al. 2006). In fact, these statistics were obtained only for the US airspace and are not a global representation. A significant limitation for the forecasting of all aviation turbulence types is to identify the source of gravity waves (McCann 2001; McCann et al 2012; Knox et al 2008). Observations from early field projects (Sorenson 1964) indicated that two flow regimes associated with CAT are possible: strongly cyclonic and strongly anticyclonic flows. Because the TI neglects anticyclonic shear or curvature in its derivation, Ellrod and Knox (2010) suggested that a new way should be taken to account for the anticyclonic shear.

The Graphical Turbulence Guidance (GTG) product uses an ensemble mean of many different diagnostics, which seems to improve the statistical performance of the turbulence forecasts (Sharman et al. 2006, Kim et al. 2011, Sharman and Pearson 2016, Kim et al. 2018). Example turbulence diagnostics typically used for clear-air and mountain wave sources include vertical and horizontal wind shears, static stability, wind speed, horizontal deformation, frontogenesis, ageostrophic indicators, turbulent kinetic energy (TKE), and Richardson number (Ri) (e.g., Knox et al. 2016). These diagnostics are designed to capture grid-scale processes (10–100 km) that may lead to sub-grid scale turbulence.

The GTG product does provide short-term forecasts, but its usage is limited by a 1-h update cycle, because of the latency in receiving the underlying NWP-model data and the time required to compute the turbulence diagnostics. Therefore, forecasts are usually not available until at least 2h beyond the valid time. Also, Pinto et al. (2015) and Sharman and Pearson (2016) stated that because of the highly transient and small spatial scales of turbulence associated with convective storms, neither the NWP model nor the turbulence-forecasting post-processing algorithms are particularly skillful at forecasting turbulence associated with convection. To address these issues, Pearson and Sharman et al. (2016) developed a turbulence nowcast system (GTGN) which merges turbulence observations with short-term GTG forecasts to produce more timely and accurate information for tactical turbulence avoidance. Their results suggested that turbulence nowcasts integrated with observations considerably outperforms the corresponding turbulence forecasts.

d) Low level wind shear (LLWS)

Low level wind shear (LLWS) at airports can occur due to fronts, thunderstorms, inversions, and surface obstructions (FAA-P-8740-40, 2008). Traditionally, surface in-situ wind sensors are used to identify LLWS cases, but recently, remote sensing platforms and aircraft based measurements are also used for detection. The surface sensors are located at the certain distances along the flight paths (Thobois et al. 2018; Oude et al. 2018), but do not cover higher levels; therefore, Doppler lidar (for cloud free conditions) and radars (cloudy air conditions) can be used for LLWS detection (Chan et al. 2007). Low level wind shear prediction using NWP models depends on model time and space resolutions (especially within the PBL), model physics, and large scale forcing conditions, and initial conditions. Using an NWP model, and the QuikSCAT

space borne scatterometer (QSCAT) and Buoy observations (Kara et al. 2007, 2008) stated that wind speed errors near ocean boundaries can be up to 5 m s^{-1} and for high resolution NWP forecasts, RMSE in wind speed can also be as high as 4 m s^{-1} . Banta et al. (2017) also suggested that wind speed error in NWPs were larger than the required accuracy at high resolution areas and suggested the use of LIDAR observations to improve forecasts (McCarty et al 2017). Gao et al. (2012) and Moninger et al. (2010) stated that errors in AMDAR measurements can be as high as $4\text{-}6 \text{ m s}^{-1}$ and suggest some corrections. Wind directional errors can be up to 35 degrees for AMDAR measurements and usually increases toward to the surface (Gao et al. 2012). Therefore, measurements of the wind speed from various measurement systems and wind speed and direction from NWP models need to be improved since they are directly used in the LLWS calculations (Chun et al. 2017).

e) Physical processes for aviation nowcasts

The production of aviation meteorological forecasts is based mainly on forecasters using numerical weather prediction (NWP) model data in combination with available observations (e.g., Jacobs and Matt 2004, Fahey et al. 2016, Bright et al. 2016). Their work suggests that NWP modeling has not yet reached a state where physical processes such as clouds and precipitation can be resolved at the spatial and temporal resolutions necessary for reliable aviation weather forecasts. Jacobs and Maat (2004) also emphasized that various physical processes associated with fog and low stratus clouds are not adequately described in NWP models due to the complexity of the underlying physical processes and the lack of sufficient vertical resolution in the atmospheric BL. Because of this, sudden weather changes on small time and spatial scales can only be evaluated and predicted if the forecaster has access to detailed observations

concerning current weather changes. The results of their work strongly emphasized that quality of short-term forecasts, up to 6 h, depends mainly on the availability of local and upstream observations.

f) Icing

Most if not all, current icing algorithms include empirical relations (e.g., temperature dependency) as described in Thompson et al. (1997), for tractability. In their work, inflight icing potential was predicted using algorithms developed by the National Center for Atmospheric Research (NCAR), the National Weather Service's National Aviation Weather Advisory Unit, and the Air Force Global Weather Center. The numerical model data from the Eta, MAPS, and MM5 models were used in their research. As part of the WISP94 field program (Thompson et al. 1997), detailed evaluations of icing algorithms were conducted. Most of the icing algorithms used in NWP are only functions of T (Noh et al. 2013; Tan and Storelvmo 2016; Odegaard 1997). Thompson et al. (1997) stated that they all predict a flat or increasing frequency of icing at decreasing temperatures. On the other hand, statistical studies of pilot-reported icing (Rasmussen et al. 1992) suggested that the number of icing reports decreases with decreasing T. Note that saturation vapor pressure also diminishes with decreasing T. The decreases usually occurs at lower temperatures ($<-15^{\circ}\text{C}$) because of increasing ice nucleation processes at cold T and less available vapor content. In the Thompson et al. work (1997), all algorithms predicted increasing or stable icing at lower temperatures as expected because of nature of the parameterizations used in the models. These models simply diagnose icing conditions empirically where clouds can occur as a function of RH and T interval between 0°C and -20°C . In fact, the large uncertainty in RH, as high as 10-15% (Gultepe et al. 2016), may lead to

substantial differences in icing rates. Similar issues also exist for airport ground operations where de-icing calculations are strongly related to T and Vis (Thompson et al. 1997, Brown et al. 1997). Traditionally, the need for ground de-icing was assessed based on horizontal Vis, but research by Rasmussen et al. (2001, 2003) showed that the icing hazard was more dependent on the liquid equivalent of snowfall rate. This discovery led to the development of NCAR's Weather Support to De-Icing Decision Making System (WSDDM, Rasmussen, et al. 2001). These works signify that icing research is presently immature and need to be improved for NWP model simulations for aviation operations.

g) Visibility Reduction due to Fog and Precipitation

Visibility reduction due to fog and precipitation is critical for aircraft operations. In fact, fog represents one of the most hazardous weather events affecting aviation activities. Over last decade, progress has been made in the study of fog processes (e.g., MATERHORN-fog, Gultepe et al. 2016) and climatology (Hodgess and Pu 2016; Albers 1977; Tardif and Rasmussen, 2007; Dorman et al. 2017). NWP models were also used for simulating various types of fog events (e.g., Bergot et al. 2007; Guedalia and Bergot 1994; Bott et al. 1990; Pu et al. 2016; Lin et al. 2017; Chachare and Pu 2018) and indicated that numerical simulation of fog is sensitive to various physical parameterization schemes (Gultepe et al 2006; Stolinga and Warner 1999), initial model conditions (Jones 1965; Anderson 1996), and land surface processes (Guedalia and Bergot 1994). Specifically, numerical prediction of the fog presents one of the challenges in NWP due to uncertainties in model physics and Vis algorithms (Gultepe et al. 2009, Guedalia and Bergot 1994, Lin et al. 2017). Also, significant errors in near-surface atmospheric variables prevent accurate prediction of fog and precipitation (especially snow) in NWPs (e.g., Pu et al.

2016; Pu 2017). These errors, therefore, need to be reduced when using NWP models for Vis predictions.

h) Satellite data assimilations

Satellite-based wind vectors can be used to infer wind shear, turbulence, and convective activity. Convective clouds identified by the CCM (convective cloud mask, Mecikalski et al. 2007) were supported by the work of Velden et al. (1997, 1998, 2005) that developed the atmospheric motion vector (AMV) algorithm. In this way, GOES-based wind products can be utilized for wind-related event analysis and in data assimilation that can be used for NWP initial conditions and nowcasting applications. Short-term (0 to 1 hr) convective storm nowcasting remains a problem for operational weather forecasting and poses a significant financial risk for the aviation industry (Sieglauff et al. 2011). The NWP models, meteorological observations, and radar are used for short-term convective forecasting, but all have shortcomings. Geostationary imagers data can help reduce some uncertainty, and that can be valuable for convective initiation predictions. The University of Wisconsin Convective Initiation (UWCI) nowcasting algorithm provides an objective, satellite-based decision support tool (Mecikalski et al. 2007).

i) Cloud base height

Cloud base height is an important parameter for aviation operations (Table 1), but without proper prediction of cloud microphysical parameters, h_c cannot be estimated accurately. Its estimation is related to cloud total water content (CTWC) and relative humidity (as well as dew point temperature depression (Guttman and Jeck 1987). The formation of cloud at low levels is also related to PBL physical and dynamical conditions. Unfortunately, cloud total water content (TWC) can be subject to large uncertainties in the PBL forecasted properties, because of issues

related to model resolution at low levels and turbulence/physical processes interactions. For example, a warm bias of about 3.3°C in SST can lead to a q_v bias of 1.2 g kg⁻¹ that was simulated by ECMWF (Sun et al., 2003). Improved NWP prediction of RH and T in the PBL can lead to more accurate TWC forecasting and that can be used for improving prediction of C_h levels.

j) Microphysical schemes for fog, cloud, and precipitation predictions

NWPs need better physically-based algorithms to improve fog, cloud and precipitation processes. Detailed, but accurate, microphysical algorithms are required at various scales to obtain reliable precipitation amount and types, Vis, wind, and turbulence, and cloud radiative properties. Recently it is stated that there are some new microphysical algorithms based on improving the single particle growth history (Harrington 2013a; 2013b) rather than assumed size distributions for each particle phase (Gultepe et al. 2018; Ferrier 1994, Lin et al. 1983) improved predictions. Pu et al. (2018) found that the simulation of clouds within mesoscale convective systems is sensitive to the various microphysical schemes. They commented that ice hydrometeors play an important role in the accurate numerical prediction of clouds and precipitation. Lately, there has been a shift in the way ice-phase hydrometeors are represented in microphysics schemes, moving from predefined hydrometeor categories with prescribed physical characteristics (e.g., bulk density) and focusing on the prediction of the particle physical evolution instead (e.g., Harrington et al. 2013a,b; Morrison and Milbrandt 2015). This has led to the smoother evolution of ice crystals during growth and avoids the artificial process of “conversion” between ice categories and auto-conversion processes. Further improvements of the microphysical algorithms can lead to the development of better weather warning and decision making systems.

The NCEP and UKMet Office are working together to create World Area Forecast (WAF) guidance for the aviation weather community worldwide. NCEP has a plan to upgrade its GFS to a Finite Volume – Version 3 model in 2019 (FV3: see <https://www.gfdl.noaa.gov/fv3/fv3-documentation-and-references>), which will employ an advanced cloud-allowed microphysical scheme, so that better cloud-related predictions such as Vis, ceiling, and reflectivity, can be provided to the global aviation weather community.

Based on the various challenging topics described above, NWP predictions for nowcasting applications related to aviation operations may include large uncertainties; therefore, integrated methods should be considered for short term forecasts (e.g., lead time <6 hours), and these are described in next section.

4. Integrated systems

a) Numerical guidance systems for aviation

A numerical guidance system (NGS) for aviation applications that includes post-processing NWP model output and local and upstream observations over high-resolution topographical data can be used to provide information on changing weather conditions at airports (Hansen et al. 2008). The NGS, supported by detailed predictions of Vis, ceiling, wind, and precipitation observations as well as TAF and TREND type weather forecasts, can be used more efficiently for aviation weather nowcasts.

The NGS can be supplied with high-resolution remote sensing observations such as radar, LIDAR, and wind profilers. For example, Nakamura et al. (2009) and Luce et al. (2010) used both LIDAR and radar to study CAT conditions below a cirrus cloud system. A statistical approach, known as the Graphical Turbulence Guidance (Sharman et al. 2006, Sharman and Pearson 2017), was developed to predict turbulence using a weighted regression of multiple turbulence diagnostics. This product and others such as convection, icing, ceiling and visibility, and surface wind gusts are available operationally on NOAA's Aviation Digital Data Service website (<https://www.aviationweather.gov/>).

b) Integrated systems for nowcasting and test bed sites (supersites)

Integrated weather nowcast systems rely on both in-situ and remote sensing observations as well as NWP model forecasts. Test bed sites (also called supersites) are an integral part of meteorological research and operations. Ralph et al. (2013) emphasized that *they can foster new forecast innovations and their transition into operations*. Ralph et al. (2013) determined that these developments related to supersites present new opportunities for businesses and agencies to improve their products and services. Their work extensively studied the importance of test beds for research and operations. They stated that: *"Test beds tend to be "outsiders" relative to either the core mission of forecasting or the core mission of research. In spite of this, they enable more rapid improvements in forecast services and demonstrate tangible relevance of research centers to forecast services in the future."* A supersite, planned by NWS as the "Operations Proving Ground (OPG)" in Kansas City, MO, will provide full integration testing of new tools and methods in an operational environment. These OPGs require a well-established research community focused on performing exploratory research and development. They also suggested

that transformational research can provide breakthrough advances for forecast/operation services in the future. Ralph et al. (2013) clearly stated the objectives of test beds are to accelerate the translation of research and development into operations, services, and decision making for short lead time periods. Overall, a test bed site can be used for operational systems, and provide better use of data in forecasts and applications to improve economic/public safety benefits.

A new integrated system for aviation operations called The Short-Term Prediction Research and Transition (SPoRT) program using NASA, NOAA, and DoD satellite data and research capabilities is available to the operational weather community to improve short term weather forecasts on regional and local scales (Ralph et al. 2013; Stano et al. 2010; Ellrod and Gultepe 2007). The SPoRT focuses on weather and aviation related problems that include the timing and location of severe weather, changing weather conditions influenced by topography, visibility, land-ocean boundaries, and the monitoring weather in remote areas. The SPoRT involves forecasters in the entire process who help develop product training materials and help assess the utility of the products.

The NOAA NWS Advanced Weather Interactive Processing System (AWIPS, Argyle et al. 2017; Raytheon, 2016) program is a complex network of systems that ingest and integrate meteorological, hydrological, satellite, and radar data for display at Weather Forecast and River Forecast Centers. Weather forecasters then use the data to provide accurate weather, water, and climate predictions and highly reliable warnings and advisories (Kelly and Ghirardelli 1998). As stated in their work, the AWIPS results are extensively used in aviation operations and nowcasting, including time-sensitive, high-impact warnings to protect life and property

(Ghirardelli and Glahn 2010). They stated that the Localized Aviation MOS (Model Observed Sounding) Program (LAMP) consisting of analyzing observations, advective models, and statistical methods can improve the longer-range MOS forecasts based on the GFS model.

One of the earlier integrated systems developed was the CAN-Now project, and its primary objective was to provide a four-season Forecasting/nowcasting system at the major Canadian airports with detailed nowcasts and forecasts (Isaac et al. 2014). The CAN-Now output allows airport related decision makers, including pilots, dispatchers, de-icing crews, ground operators, and air traffic controllers to make accurate decisions to improve safety and efficiency. The prototype nowcasts rely on existing routinely available weather information including NWP model output, site climatologies, remote sensing and lightning network observations, and in-situ measurements of wind, precipitation, visibility, ceiling, and temperature. The integrated nowcast system called The Adaptive Blending of Observations and Models (ABOM) system was developed by Bailey et al. (2009) to be included in the CAN-Now system. The prototype system was used in a nowcasting mode for detecting weather hazards and providing forecasts out to about 3–6 h for most phenomena, and out to 36 h for some subsets of phenomena.

There are several other types of integrated systems that are being used in Europe. The integrated nowcasting through comprehensive analysis (INCA) (Haiden et al. 2011) and AROME-NWC (Auger et al. 2015; Seity et al. 2011) are common ones. It includes downscale processes and updates NWP predictions using the latest observations from surface in-situ observations and high-resolution (1 km) orography data. A verification of INCA simulations of T, RH, and wind analyses was performed against high-resolution network observations in Austria by Kann et al.

(2011) and Haiden et al. (2011). The AROME was developed in France that uses a non-hydrostatic mesoscale model version simulated for the forecast time range of 0–30 h (Auger et al. 2011; Seity et al., 2011). This model is initialized by using a 3-D variational data assimilation scheme (3DVar), and that provides the initial fields relevant for an accurate nowcast; This system was related to the ALADIN–France model (Fischer et al., 2005). Integrated turbulence nowcasts have been developed that use short-term NWP forecasts nudged by in situ and radar observations of turbulence (Pearson and Sharman 2016).

Another example of the use of integrated systems to detect and nowcast hazardous weather is provided by the low-level wind shear (LLWS) alert systems. It is well-known that thunderstorms can be accompanied by intense updrafts and downdrafts. The strong downdrafts or downbursts below cloud base on or near the ground can force low flying aircraft downward, and can also cause strong divergent flow, producing low-level (horizontal) wind shear which can lead to unexpected rapid changes in aircraft airspeed. The outflow winds associated with downbursts have horizontal extents > 4 km and can persist from 5-30 min. During the Joint Airport Weather Studies project (McCarthy et al. 1982), Doppler radar examination of numerous thunderstorm downdrafts and outflows indicated that wind shear particularly hazardous to aircraft occurred on much smaller temporal and spatial scales, and Fujita (1981, see also McCarthy and Serafin 1984, Wilson and Wakimoto, 2001) termed this smaller scale, but more hazardous downdrafts/outflows as “microbursts”. The damaging outflow winds associated with microbursts have horizontal extents of ≤ 4 km and can persist from 2-10 min, typically (Wilson et al. 1984).

The scale and suddenness of microbursts make them particularly hazardous to aircraft departing or approaching an airport. Thunderstorm outflow or microburst wind shear is known to have caused 21 aircraft accidents with 438 fatalities in the United States between 1975 and 1994.(Wolfson et al. 1994). In response to these accidents, the Federal Aviation Agency (FAA) developed and deployed three ground-based low altitude wind-shear detection systems: the Low Altitude Wind Shear Alert System (LLWAS) (e.g., Linden and Simpson 1985, Wilson and Gramzow 1991), the Terminal Doppler Weather Radar (TDWR) (e.g., Wilson et al. 1984, Michelson et al. 1990), and the Airport Surveillance Radar Weather Systems Processor (ASR-9 WSP) (Weber and Stone 1995, Cho 2015). The FAA-sponsored Integrated Terminal Weather System (ITWS) uses TDWR reflectivity data with short-term NWP model nowcasts to predict microburst intensity and location (Wolfson et al. 1994). Since the deployment of these systems, along with enhanced pilot training, commercial aircraft LLWS accidents have dropped to nearly zero in the U.S. The dramatic decrease in these accidents testifies to the safety benefits provided by these detection systems.

Enhanced physical understanding of the microburst phenomenon has been provided by high-resolution simulations (e.g., Proctor 1988, 1989, Orf et al. 1996, Orf and Anderson 1999, Nicholls et al. 1993), and laboratory studies (e.g., Ferrero et al. 2014). Because of its importance to aviation, LLWS is routinely forecasted using the vector wind difference of wind between 2000 ft AGL (619.5 m) and the surface (e.g., NOAA NWS Instruction 10-813, 2016), although these forecasts are mainly driven by resolvable non-convective sources, e.g., frontal passages, low-level jets, lee side mountain effects, sea breeze fronts, etc. As NWP model resolution increases

to become convection-resolving, routine microburst nowcasts using both observations and NWP forecasts will become routine.

c) Artificial Intelligence for high-impact weather

As done for other scientific research involving large data sets, increasing data volume and resolution of observations, as well as model simulation output for weather forecasting, led to the application of artificial intelligence for aviation (AIA) research and guidance. Because current NWP models runs have increased time and space resolutions (McGovern et al. 2017; Weygandt et al. 2009), as well as new observing systems, including in-situ observations, weather radars, LIDARs, and GOES-16 also generate data at high time and space scale resolutions (Stano et al. 2010; Goodman et al. 2012), forecasters and users do not have time to make rapid decisions if data are not somehow prepared for easy evaluation in advance (Karstens et al. 2015). These data sets are called “*big data*.” Artificial intelligence (AI) methods (Pasini and Marzban 2008) use various techniques to process big data sets and then apply the results to weather forecasting issues, which are crucial for creating timely weather reports (McGovern et al. 2017). They stated that AI techniques based on physical understanding of the environment could improve prediction skill of high-impact weather situations. The AI approach expands information available over MOS techniques (Glahn and Lowry 1972) for deriving probabilistic, categorical, and deterministic forecasts available from NWP models.

McGovern et al. (2017) provided an extensive summary of AI techniques used in the meteorological applications. Haupt et al. (2008) also provided an overview of AI techniques applicable to artificial neural networks (ANNs), including decision tree algorithms, genetic

algorithms (Allen et al. 2007), fuzzy logic, and principal component analysis (Elmore and Richman 2001). In this area, using a decision tree technique, Burrow et al. (2005) developed lightning detection algorithms for mid-latitudes. Williams (2014) used a random forest approach to diagnose convectively-induced turbulence. These works suggest that AI methods are starting to be used extensively in post-processing of NWP output and in-situ observations.

The AI systems and statistical based neural network systems can help transfer knowledge related to aviation forecasts into the aviation operations when fast computer systems become easily available in the future.

5. Future Challenges and Issues

There are various challenging topics related to aviation meteorology that can significantly impact aviation operations, and these are summarized below.

a) Visibility and Ceiling Issues

Jacobs and Maat (2005) show that for lead times greater than 4 h, the TAF guidance provides more accurate cloud h_c and Vis forecasts than those derived manually by forecasters. For shorter lead times (<3 hr), their work suggested that the differences in the comparisons of aviation related parameters are found to be small. For aviation applications, the economic value of reliable weather forecasts is very high (Hansen et al 2009; Gultepe et al 2016). For this reason, large occurrence of high impact weather related to h_c and Vis at an airport can reduce airport capacity that can lead to enormous economic costs. The cloud ceiling (defined in meters for cloud cover $\geq 6/10$ of the sky) predictions can be performed based on NWP predictions using the lowest level of cloud total condensed water content (TCWC). The fuzzy logic-based analog

forecasting systems (Hansen 2007; Bankert et al. 2004) can also be used for this purpose. A terminal aerodrome forecast (TAF) provides weather conditions and their most probable time of occurrence. The C_h and Vis (defined by Glickman 2000) are the two variables that together determine flight category [e.g., instrumented flight rules (IFR where $C_h < 1000$ ft or $Vis < 3$ miles) or visual flight rules (VFR) (see Table 1 for flight condition definitions, Verlinden and Bright 2017).

Table 1: FAA based flight classification that is based on cloud ceiling height and horizontal visibility.

Flight classification	Cloud ceiling (ft)	Horizontal Visibility (miles)
IFR	<1000	<3
MVFR	≥ 1000 and ≤ 3000	≥ 3 and ≤ 5
VFR	>3000	>5

In addition to this, the meteorological and aviation scientific communities recently studied meteorological parameters important for aviation operations that are related to ceiling height and Vis forecasts (Rudack and Ghirardelli 2010). These forecasts are valuable for making economical decisions and societal context (e.g. the loss of life). Gultepe et al. (2007) suggested that reductions in Vis can be caused by several hydrometeors including fog, haze, mist, rain, snow, and blowing snow. Figure 2 shows the meteorological events that contribute to the integrated Vis estimations. Because of Vis complexity and difficulty in measurements especially in cold climates, its use in NWP can be difficult and includes large uncertainties (Gultepe et al. 2006, 2018).

b) Contrails and Frost

Contrail formation, development, and dissipation are important for aviation and climate sciences but studies on these are limited. Contrails form when water vapor condenses on IN (ice nuclei) and then freeze on aerosols from the exhaust of aircraft engines at T less than typically -40°C (see e.g., Schumann et al. 2012 for an overview). Although contrails at -40°C occur at high levels in midlatitudes and tropical weather, they can also occur near the surface during Arctic winter (Gultepe et al. 2015). Heymsfield et al. (2010; 2011; 2005) also stated the importance of contrail microphysical conditions for better understanding of ice cloud nucleation processes. Contrails can indicate higher values of moisture at the cold temperatures that may cause frost and light snow precipitation at high northern latitudes (Gultepe et al. 2016; 2017). Figure 8 shows heavy frost conditions occurred on an ice particle counter sensor during an Arctic project (Gultepe et al., 2015; 2018). Frost formation on aircraft surfaces is also a condition for deicing at the airports which is required by the FAA (2004).

FIGURE 8

Over the northern latitudes, contrails, including aircraft-produced ice particles (APIPs), can be visible within the ABL over the airports (Gultepe and Heymsfield 2016; Heymsfield et al. 2011; Schumann and Heymsfield 2017; Gultepe et al. 2014; 2015, Woodley et al. 1991; Langmuir et al. 1948; Ludlam 1956). Contrails may modify the atmospheric environment in several ways. For example, Heymsfield et al. (2011) stated that holes in clouds are also due to inadvertent seeding of clouds with IN particles generated by aircraft and these are produced through spontaneous freezing of cloud droplets in air (Heymsfield and Sabin 1993; Heymsfield and Sabin 1989) and that is cooled as it flows around aircraft propeller tips or jet aircraft wings. Their work also suggested that polar clouds are particularly susceptible to the APIPs effects through

modifications in radiative processes. This may also suggest that ice crystals sampled by aircraft probes over the Arctic environment may include AIPs and these need to be researched. Also, contrails are considered as prototype cirrus which impacts the energy budget of the atmosphere by reflecting incoming SW radiation and trapping outgoing IR radiation (Markowicz and Witek 2011, Schumann et al. 2012; Spangenberg et al. 2013; Minnis et al. 2013). How contrails from an aircraft can contribute to global climate change was studied in detail by Minnis et al. (1998, 1999), Schumann et al. (2012), Schumann and Heymsfield (2017). Whether or not contrails would contribute to global warming or cooling is still not clear, and probably cannot be ascertained without resort to high-resolution climate models (Schumann and Mayer 2017).

c) Climate change impact on aviation

Future research on the combined impacts of climate change and climate variability on aviation operations can help airlines and other aircraft operators for long term planning. For example, Goodman and Griswold (2017) investigated future density-altitude (DA) trend evaluations. Their work stressed the importance of future investigations on the impacts of ENSO and Atlantic Oscillations (AO) on DA to be used in seasonal-scale planning of aviation operations. The weight restriction is an important factor in planning future flight operations, therefore, needs to be evaluated. For this reason, airlines may need to be rescheduled out of the hottest parts of the day. Other potential impacts include anticipated jet stream changes with consequent impacts to CAT (e.g., Williams and Joshi 2013; Williams 2017; Storer et al. 2017), and changes to convection (e.g., Del Genio et al. 2007) and other extreme events (Puempel and Williams 2016). Both Irvine et al. (2016) and Williams (2016) suggested that the effect of wind changes as a potential impact of climate change on aviation can be important for future aviation operations. This is of particular interest for trans-Atlantic flights, where the pattern of upper-level winds

over the north Atlantic, in particular the location and strength of the jet stream, strongly influences both the optimal flight route and the resulting flight time. Some of these effects may be mitigated by “climate optimized routing” procedures (e.g., Matthes et al. 2012).

FIGURE 9

Figure 9 shows the time series of cold spell T and warm spell T indexes obtained from CMIPS models (Sillmann et al. 2013a,b) where increasing warm days and slightly decreasing cold days are seen from 1948 to 2005. Therefore, increasing convective activities are likely expected and that can be related to shear, turbulence, and heating processes and these can play an important role for planning procedures of the aviation applications.

d) Operational satellites

Lately, geostationary satellites with more than the traditional five imaging channels are being used for weather analysis and operations, and these satellites carry additional channels in the IR windows. A review paper on geostationary satellites is given this special issue by Ellrod and Pryor (2018); therefore, limited information is provided in this sub-section. The Advanced Baseline Imager (ABI) is used on the Geostationary Operational Environmental Satellite-R Series (GOES-16). ABI views Earth with 16 spectral bands (compared to five on previous GOES), including two visible channels, four near-infrared channels, and ten infrared channels. Himawari 8 is a Japanese weather satellite and carries an Advanced Himawari Imager (AHI) with also a 16 channel multispectral imager to capture visible and infrared images of the Asia-Pacific region (Berndt et al 2018). The instrument was designed and built by Exelis Geospatial Systems (now Harris Space & Intelligence Systems). The FY-4 (FengYun-4) is the China Meteorological Administration (CMA) second-generation three-axis stabilized, geostationary

meteorological satellite developed by CAST (China Academy of Space Technology) (Yang et al 2017). Two variants of spacecraft of the FY-4, with one carrying optical sensors and the other carrying microwave sensors were developed. It carries an AGRI (Advanced Geosynchronous Radiation Imager) with 14 channels, VISSR (Visible and Infrared Spin-Scan Radiometer) 5 channels, GIIRS (Geostationary Interferometric Infrared Sounder), LMI (Lightning Mapping Imager, Goodman et al. 2011), and a SEP (Space Environment Package).

New generation imagers are also being deployed on polar-orbiting satellites, which provide aviation information over high-latitude regions, which are only partially observed by geostationary orbiters. These new imagers, such as the Visible Infrared Imaging Radiometer Suite (VIIRS) on the Suomi National Polar-orbiting Partnership (NPP) satellite and NOAA-20+ series, provide a large number of channels that are similar to or more expansive than their geostationary satellite counterparts (Menzel et al. 2018). They will greatly enhance the satellite information useful for aviation over Polar Regions. Inclusion of spectral IR capability for geostationary satellites such as Chinese GIIRS (Menzel et al. 2018) can improve knowledge obtained for atmospheric stability, providing information on convective weather warnings and forecasts (Chiodi and Harrison 2010). Spectral IR capability has been used in polar orbiting satellites (e.g., AIRS (the Atmospheric Infrared Sounder), CrIS (Cross-Track Infrared Sounder; Zhang et al. 2016, Wang et al., 2012) and IASI (the Infrared Atmosphere Sounding Instrument) on Aqua, Suomi-NPP, NOAA-20, and METOP (Meteorological Operation) satellites; Mittaz and Harris 2011; Blumstein et al. 2007; Wang and Cao 2008) to obtain T, RH, and wind vertical structure in the region with no clouds and above the cloud tops. More extensive development of spectral IR techniques could revolutionize technology related to aviation weather forecasts.

To improve nowcasting techniques for detecting, tracking, and monitoring the early development of small convective clouds, convective initiation forecasts over the CONUS and possibly over marine environments were studied in detail using satellite observations (Mecikalski et al. 2007). Historically, most of the convective weather predictions used weather radars (e.g., Mueller et al. 2003). However, radars usually do not see the early stages of convective cloud development prior to precipitation development. Since the 1990s, NCAR began to incorporate satellite information into convective storm nowcasting system (the Auto-Nowcaster). Satellite feature detection algorithms (e.g., Bankert 1994; Roberts et al. 1999; Tag et al. 2000, and Roberts and Rutledge 2003) were usually used to classify cloud types, identify surface convergence boundaries, and monitor the cloud growth based on the changes in their IR cloud-top T. These developments were positive for nowcasting systems but additional data sets from GOES-16 channels can further provide information related to cloud types and related physics and dynamical processes, and need to be researched.

e) Measurement uncertainties

1) T and RH: A better understanding of the uncertainties in observations can be important for decision making systems, and that can be used for obtaining better physical parameterizations for NWP simulations and improvements in data assimilation techniques (e.g. 4-D Var) for model initial conditions. T and RH uncertainties in NWP predictions can be very large and that affects the prediction of cloud formation, visibility, and convective intensity, and surface-air interactions through turbulent fluxes using NWPs (Feingold 1999). Figure 10 shows RH_w measurements obtained during the FRAM project (Gultepe et al. 2014; Gultepe 2015). This plot shows that Vis

is strongly related to RH_w ; increasing RH_w results in decreasing Vis. A small change in RH_w at about 4-5% can lead to Vis changes from 50 km down to few meters. This means the possible errors in RH_w from NWP predictions can lead to significant issues for aviation forecasts, e.g. Vis and cloud types and that can affect operations significantly.

FIGURE 10

2) Visibility and Ceiling height: The present challenges of Vis and h_c measurements are related to precipitation/fog hydrometeors types and scale issues (Gultepe and Isaac 2004; 2006). They suggested that discrimination of droplets from precipitation and its usage in Vis parameterizations are critical for NWP Vis predictions. Figure 11a shows a scatter plot of Vis measurements from the most commonly used sensors (Vaisala FD12p and Sentry sensors), and ice fog crystals (Fig. 11b) occurring over Yellowknife International Airport (CYK) during the FRAM ice fog project (2010-2011 winter, Gultepe et al. (2016); ice fog crystal sizes were usually $<300\text{ }\mu\text{m}$). The concentration of the Vis observations (along green line) in Fig. 11a is seen above the 1:1 line (red line), indicating that FD12p Vis values were usually larger than Sentry Vis by about 50%. For this reason, in automated observing systems, a double Vis sensor approach should be used for model validations and comparisons with METAR observations. Especially, this needs to be improved for cold climate applications where warming trend can cause severe cold fog events (Figure 12).

FIGURE 11

FIGURE 12

Based on its occurrence, forecasting Vis over short time intervals (0-6 hrs) is challenging and most NWP models do not explicitly predict Vis (Chmielecki and Raftery 2011); therefore, Vis forecasts must first be derived from other meteorological parameters such as cloud water content

(CWC), RH_w , and precipitation. Roquelaure and Bergot (2008, 2009) were the first to use Bayesian model averaging (BMA) in Vis forecasting. Zhou et al. (2009) also described the use of a short-range ensemble forecast system to generate probabilistic visibility forecasts. The UK Met Office Global and Regional Ensemble Prediction System (MOGREPS) and NOAA NCEP Ensemble Prediction Model (Zhou et al. 2009; Zhou and Du 2010) have already been used for probabilistic aviation weather predictions (Gill and Buchanan 2014; Chun et al. 2017; Kim et al., 2015).

Operationally, aviation-related interests in the US typically use two types of ceiling and Vis forecasts provided by the NWS Global Forecast System (GFS) model: 1) GFS MOS forecasts and 2) GFS Localized Aviation Model Output Statistics Program (LAMP) forecasts. Both the GFS MOS and GFS LAMP produce probabilistic forecasts for seven ranges of Vis and return to the user a categorical forecast corresponding to the most likely range of values. These existing methods do not provide a general framework for generating a full predictive probability density function (PDF) for Vis (Chmielecki and Raftery 2011). They stated that predictive PDFs are attractive for Vis forecasts because both thresholds of ceiling height and Vis correspond directly to the conditions governing flight rules. A predictive PDF allows the user to determine the probability of Vis falling below any threshold of interest rather than a single pre-specified threshold. Therefore, PDF based approaches for ensemble prediction of Vis and ceiling height need more research.

Cloud ceiling measurements are usually performed by ceilometers or are based on manual observations of sky conditions at airports. It is defined as the height of the lowest layer of clouds above the surface that is either broken or overcast, but not thin. The broken and overcast

conditions are measured by the "octals", which are 8 equal segments of the sky. The ceilometers measurements usually provide cloud conditions at 3 levels e.g. low clouds, middle clouds, and high level clouds, but they may not have the same meaning as man-made observations. Therefore, these measurements should be properly compared and integrated for aviation applications

3) Turbulence and EDR

Measurements of 3D wind components and prediction of EDR and gust conditions are also critical to aviation operations (Sharman et al. 2018, Gultepe et al. 2018, current issue). Although gust values usually are presented based on the horizontal wind components, the vertical component also plays a significant role in gust and EDR estimation. These can be obtained using in-situ ultrasonic sensors (Gultepe et al. 2018) or from AMDAR or TAMDAR EDR reports from commercial flights, and also likely from remote sensing platforms such as LIDAR and radar, and inferences for satellite features (Benjamin et al. 2007). In all events, EDR is an estimated quantity that is not actually “measured”, so it is particularly difficult to determine the uncertainty in the estimate. Pearson and Sharman (2017) studied EDR from onboard aircraft estimates versus nearby METARs wind speed and wind gust measurements (Figures 13a and 13b, respectively). The fits for each represent large variability in data. The scatter around the mean curves was very large. This is not surprising since turbulence is a microscale phenomenon with large spatial and temporal variability. But this implies that uncertainties in the use of dynamical parameterizations for EDR versus gust can be large and NWP models need probabilistic approaches or better diagnostic approaches.

FIGURE 13

4) Low Level Wind Shear (LLWS) measurements

As provided previously low level wind shear measurements can have large uncertainties based on measurement field designs and instrument type. For example, ultrasonic wind sensors (2D or 3D) can have issues when icing or precipitation occur (Gultepe et al. 2018). If they are heated for icing conditions, additional issues may arise due to heating the tips of sensing units. On the other hand, icing may also affect conventional wind measurements using regular anemometers. Use of Doppler LIDAR based techniques may work nicely to obtain good results for clear air and light cloud conditions but under the heavy precipitation and large optical thickness conditions they cannot penetrate in-cloud conditions and will fail for wind measurement retrievals (Thobois et al. 2018). Table 2 (ICAO 2005) provides criteria for low LLWS definitions that indicates the accuracy wind speed and direction measurements should have.

Table 2: Synthesis of the ICAO guidelines for observing low level wind shears (ICAO, 2005).

Features	Alerts	Warnings
Coverage	3 NM extension to runways is commonly used whatever the wind shear equipment (LLWAS, Lidars, TDWR/Radars)	Up to 9.55 km for a glide slope of 3Deg in order to monitor up to the altitude of 500 m.
Update Frequency	<ul style="list-style-type: none">• LLWAS: update every 30 sec• Radar/lidar: update between 1 to 6 mins	Typically 5 minutes are used for radars and lidars
Resolution	<ul style="list-style-type: none">• LLWAS: 1 NM between 2 anemometers• RADAR: 100-250 m• Lidar: 100-200 m	Same as alerts
Scanning patterns	One horizontal scan (PPI) at 3 deg scans per approach are used	Several products can be used from 2 to 5 PPI scans
Methods for computing alerts	<ul style="list-style-type: none">• Wind shear alerts: Headwind/tailwind changes over 1 NM or along the runway superior to 15 Knots.• Microburst alerts: Headwind/tailwind changes over 1 NM or along the runway superior to 40 Knots.• LLWAS: NCAR Algorithm• RADAR: Runway-oriented wind shears algorithms like the ones developed by MIT-Lincoln Lab for TDWR, HKO algorithm, products of commercial software like RAINBOW5 developed by Selex and IRIS developed by Vaisala.	Additional products can be computed from radial radar or lidar data according to local needs like shear products, gust front detection, wind reconstruction

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f) Convection parameterization and prediction

Convection parameterization based on NWP models, observations, and integrated methods can play an important role for aviation operations. Use of forecaster contributions for providing convective outlooks, mesoscale concepts, and severe weather warnings such as heavy precipitation, hail, and tornado watches can improve short term predictions for aviation operations that usually need a forecast warning time of less than a 1 hr time-period. The Storm Prediction Center (SPC) (Karstens et al. 2018; Cohen et al. 2017) also has a human component for severe weather prediction. This needs to be considered because accumulated errors of NWP model physical components for predictions can be significant during simulation times less than 1 hr. In fact, synoptic scale environments associated with severe weather can complicate short term predictions and human based knowledge can help to improve short term predictions.

Convection-allowing numerical model (CAM) ensembles can provide extensive information related to storm intensity, location, and evolution but do not forecast accurately maximum hail size at the surface (McGovern et al. 2017). Based on the large variability related to meteorological observations and NWP scale issues, and deterministic parameterizations, probabilistic analysis of the aviation meteorological parameters predictions are needed. For example, Figure 14 shows the observed frequency of hail amount for sizes >25 mm versus forecast probability using the CAM Analysis and Prediction of Storms (CAPS) ensemble predictions using methods provided in McGovern et al. (2017). In the inset, it shows the same for the actual numbers of cases. In this inset, observed frequency increases while forecast probability decreases significantly. Based on various simulations using conditions given in the legend

(McGovern et al. 2017), it is seen that increasing counts result in lower predictability of the meteorological parameters (Fig. 14). Verification results and a single forecast case in this figure are given for the machine-learning hail forecasts and other storm surrogate probability forecasts, including HAILCAST, column total graupel, and updraft helicity (McGovern et al. 2017). The Random Forest (RF) analysis (Ahijevych et al. 2016) used for this experiment was trained using CAPS ensemble forecasts during May-June 2014, and evaluated based on CAPS ensemble forecasts. The performance diagram in Fig. 14a shows that for a given probability threshold, the machine-learning models tend to have fewer false alarms, a lower frequency bias, and higher overall accuracy than other methods. The attributes diagram in Fig. 14b indicates that the probabilities from the machine-learning models and updraft helicity are generally reliable, while other methods tend to produce probabilities that are overconfident. These results suggest that probabilistic approaches for convection prediction need to be developed in the future that are based on RF or other AI methods.

The demand for accurate nowcasts of convective precipitation that includes heavy precipitation and hail has led to development of the high-resolution data assimilation and rapid cycling numerical weather prediction system (e.g., Sun et al. 2013). In their work, they reviewed the recent progress on the use of NWP for nowcasting convective precipitation and provided future expected challenges and opportunities. They emphasized that NWP models generally produce larger quantitative precipitation forecasts (QPFs) than nowcasting systems beyond a few forecast hours. Therefore, they suggest blending radar echo extrapolation with a numerical model run to generate a seamless 0–6-h forecast. Nowcasting and Initialization for Modeling Using Regional Observation Data System (NIMROD; Golding 1998) was the first system that used blended radar

echo extrapolation with a NWP output. For the first hour nowcast, the extrapolation of the observed precipitation field was given full weight, and it was gradually relaxed with increasing lead time to where the model eventually received full weight. This method was better than earlier radar echo tracking systems. The blending of the corrected model forecasts with extrapolation forecasts allows for a smooth transition from the extrapolation to model forecasts (Sun et al. 2013). Similar results have been shown over the years starting with Browning (1980), Doswell (1986), and Austin et al. (1987). A recent paper by Sokol and Zacharov (2012) described a new blending method that assimilates the extrapolated radar reflectivity with a nudging technique. The decrease in skill by extrapolation related to the size and organization of the precipitation were also emphasized by Wilson (1966) and Wilson et al. (1998). Based on a large set of predictor fields, and inserting the location of boundary layer convergence lines in NCAR's AutoNowcaster (ANC) (Mueller et al. 1993), Wilson et al. (2004) predicted storm initiation up to one hour in advance that shows the importance of BL processes. The ANC system uses fuzzy logic to combine predictor fields that reflect the atmospheric environmental conditions and boundary layer forcing based on observations and numerical model runs.

To meet the needs of nowcasting, numerical models have to be run at resolutions of at least a few kilometers. Wilson and Roberts (2006) stated that the 10-km Rapid Update Cycle (RUC10) 3-h forecasts issued every 3 hr were correct at predicting areas of convective initiation only 13% of the time. Sun et al. (2013) stated that possible factors limiting the model's ability to predict precipitation initiation, likely was insufficient model resolution in addition to many other factors. Models with high resolutions can enable the explicit representation of convective processes without cumulus parameterization schemes. These models are called as "convection-permitting"

or “convection-allowing” NWP (e.g., Sun et al. 2013). Many other studies show that forecasts from the convection-permitting models produced more skillful guidance than those from a coarser-resolution model employing convective parameterization (e.g., Done et al. 2004; Kain et al. 2006; Weisman et al. 2008; Clark et al. 2009). Verification of convection forecasts is challenging, and innovative methods are needed to account for small errors in model derived location and timing (e.g., Pinto et al. 2015).

FIGURE 14

g) Observational methods

The accurate testing of nowcasting products is strongly related to observations and their analysis. Golding (1998) suggested that the products should be assessed against both point observations and analyses.

Nowcasting systems usually integrate observations with Numerical Weather Prediction (NWP) model products for short term predictions up to six hours ahead. In Golding et al. (1998), precipitation, cloud, and visibility were the main conditions. The precipitation rate in the analysis used a combination of the processed radar and satellite data, surface reports, and NWP simulation output. The precipitation type was also diagnosed in their work using NWP fields. Improving nowcasts is a strong function of the integrated systems that are used in the observations and model outputs (Bailey et al. 2009). Developments of these nowcasting systems in the near future likely will be improved by artificial intelligence (AI) methods.

Generally, NWP prediction assessments against point observations are only reported for analyses because the representativeness errors of meteorological parameters are of similar magnitude to

the forecast errors. He stated assessments against analyses performed over restricted geographical areas are considered good because of observational coverage. If not considered, then the verification statistics can be very uncertain. Because of possible natural variability in observations, use of supersites with satellite stations (Gultepe et al. 2018; Ralph et al. 2013) should to be further researched for data assimilation and model output validations. Verifications performed by (Vislocky and Fritsch 1997) showed that the observations-based methods were not only far superior to persistence climatology at all lead times (5%–20% improvement) but also outperformed the MOS-based technique at the 1- and 3-h lead time projections with skill increases averaging four percentage points. This suggests that for nowcasting applications, observations should be weighted more than MOS techniques.

h) Overall summary

In the future, although expanded computational techniques can be expected to reduce the uncertainty in the predicted parameters related to aviation meteorology, improvements in individual models and physical parameterizations and their careful verification is paramount (e.g., Yano et al. 2018 and references therein). Viz., physical parameterizations related to aviation meteorology forecasting are not well-represented at NWP scales presently in use; therefore, new scale-dependent physical parameterizations will be needed to improve the NWPs predictions in deterministic or probabilistic approaches.

Forecasting accuracy of high impact weather parameters are strongly dependent on availability of integrated data sets (both observations and predictions) and should take advantage of probabilistic forecast methods (Benjamin et al. 2010; Zhou et al. 2009). Unfortunately, errors

related to components of the NWP ensemble simulations do not usually cancel out each other but tend to accumulate. As shown in this review, both measurements and statistical approaches, as well as newly developed scale-dependent physical (e.g. Vis) and dynamical parameterizations (e.g. EDR, CAT) are needed to improve the accuracy of the NWP model predictions that are related to core physical and dynamic processes.

Overall, the issues with predictions of gusts and EDR, Vis, precipitation amount and rate, fog, icing/deicing, and lightning as well as convective intensity require more advanced designs for the meteorological supersites and physically-based approaches for parameterizations of severe weather parameters under various climatic environments. In this respect, in-situ observations at the surface and within the atmospheric layer in both cloud and cloud-free regions are required to improve the aviation nowcasting and also for improving the accuracy of the long-range forecasts.

In response for the needs of global aviation community, NCEP and UK Met Office are currently assigned by ICAO (International Civil Aviation Organization) to create World Area Forecast (WAF) guidance for the aviation weather community worldwide. Both centers are now providing operational global icing and turbulence forecasts based on their global forecast systems. NCAR's fuzzy logic icing and GTG turbulence algorithms have already been implemented into NCEP's Unified Post Processor (UPP) to generate both icing and turbulence forecasts (Chuang et al. 2018). Results of this collaboration indicate that aviation meteorology issues are not only locally recognized but also globally, and need to be evaluated and integrated.

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Figure Captions

Figure 1a-b: Statistics for aircraft related accidents related to meteorological parameters from 1994 to 2000: (a) actual numbers of accidents and (b) probabilistic distributions in pie chart (Data from NTSB 2010).

Figure 1c-d: Part 91-Weather as cause/factor during all accidents for the period of 2000-2011. The NTSB (National Transportation Safety Board) based statistics which resulted in 19441 accidents and 29% of these accidents were related to weather conditions (c) (Eick, 2014) and Part 121-air carrier weather related cause/factors for 2000-2011 (d).

Figure 2: Various weather conditions representing visibilities related to warm fog, moisture, rain, freezing fog, ice fog, snow, blowing snow, and ashes (from top left to the right boxes).

Figure 3: CIP (Cloud Icing Project) conceptual diagram (a). Precipitation types: snow (asterisks), rain (large open circles), and freezing drizzle (small gray circles). (Adapted from Bernstein et al 2005) © American Meteorological Society. Used with permission. (b) shows a picture of

splintering mechanism, which generated many small droplets and then quickly froze occurred during a wet snow case at $T=-3^{\circ}\text{C}$ on March 15 2013 during SAAWSO project (Gultepe et al. 2017) took place over St. Johns' area, NL, Canada .

Figure 4: Example of texture-based clustering of GOES imagery on Dec. 5 2003: Three-band red, green, blue (RGB) image (a) and color-coded clustering classifier (b). Color bar shows cloud types (c). An example of the GOES-12 imager-derived cloud top pressure product at 1800 U T C 15 Nov 2005 is shown in (d). (Adapted from Mecikalski et al. 2007). © American Meteorological Society. Used with permission.

Figure 5: The σ_w^2 profiles (a), horizontal mean wind speed profiles (b), and σ_w^2 profiles (c) for a 24-h period on 11 Aug 2006 during TexAQS 2006 project (Adapted from Tucker et al. 2009).

Figure 6: Example observations of the 16 January 2015, mountain ice fog event that occurred during the MATERNHORN project over the Utah Mountains; Halo backscatter ratio and 3D winds based on Doppler velocities and VAD technique (a), and CL-31 Backscatter ratio (β) (b).

Figure 7: A reflectivity RHI of a large convective cell gathered at 0005:23 UTC 26 Jun 2015. Reflectivity field (Z) is shown in (a) where the dashed line marks the 55-dBZ contour; 60 dBZ is seen up to 13 km MSL, indicating the likely presence of large hail, Doppler velocities in (b), the various regions based on S-Pol radar Z_{DR} marked with white contour lines and are labeled (c), and differential phase ϕ_{DP} is shown in (d); starting offset is set at about 0°C and over marked regions of vertical ice crystals, ϕ_{DP} is decreasing in range (d). Adapted from Hubbert et al. (2018), © American Meteorological Society (AMS). Used with permission.

Figure 8: Frost formation on ice particle counter sensor which occurred during the FRAM ice fog project in Barrow, AL, on April 16 2008.

Figure 9: Time series of percentile indices from 1948 to 2005 of the ensemble mean (solid) and median (dashed) of 31 CMIP5 models (black) and 18 CMIP3 models (green). The shading indicates the interquartile ensemble spread (range between the 25th and 75th quantiles). Note that the percentile indices from the reanalysis ERA40 (blue) from 1958 to 2001 and NCEP1 (red) from 1948 to 2005 are calculated with a different base period (1961 to 1990) than those from ERA-Interim (cyan) and NCEP2 (orange) with a base period from 1979 to 2008. Displayed are global averages over all land for CSDI (a) and for WSDI (b). Grey shading along the horizontal x-axis indicates the evolution of globally averaged volcanic forcing according to Sato et al. (1993) (Adapted from Sillmann et al. 2013). © American Meteorological Society. Used with permission.

Figure 10: Vis versus RH_w from a severe fog case event at the FRAM site during in Snow-V10 project.

Figure 11: Vis from FD12P sensor against Sentry Vis (a) for all precipitation types and ice fog, and ice fog crystals (b) collected during FRAM-IF project took place over Yellowknife International Airport (2010-2011 Winter).

Figure 12: Ice fog occurrence over the Arctic Ocean on Aug 24 2010 (Permission by G. Toth).

Figure 13: Plots of 117 069 wind speed (a) and 15 382 wind gust observations in Knots (b) matched with in situ EDR (Eddy Dissipation Rates) reports within 5 km, 5 min, and 1000 ft of each other. Median speed and gust values within each 1-kt bin are shown as black dots. Fit lines to the median values are shown in black (linear) and purple (square root) (Adapted from Pearson and Sharman 2017). © American Meteorological Society. Used with permission.

Figure 14: Performance diagram comparing different hail forecasting methods (a). Attributes diagram indicating the reliability of different forecasting methods (b) (Adapted from McGovern et al. 2017). © American Meteorological Society. Used with permission.

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