

Generalised vectorial ∞ -eigenvalue non linear problems for L^∞ functionals

Article

Published Version

Creative Commons: Attribution 4.0 (CC-BY)

Open access

Katzourakis, N. (2022) Generalised vectorial ∞ -eigenvalue non linear problems for L^∞ functionals. *Nonlinear Analysis: Theory, Methods & Applications*, 219. 112806. ISSN 0362-546X doi: 10.1016/j.na.2022.112806 Available at <https://centaur.reading.ac.uk/102539/>

It is advisable to refer to the publisher's version if you intend to cite from the work. See [Guidance on citing](#).

To link to this article DOI: <http://dx.doi.org/10.1016/j.na.2022.112806>

Publisher: Elsevier

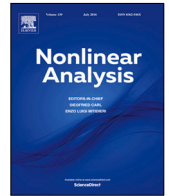
All outputs in CentAUR are protected by Intellectual Property Rights law, including copyright law. Copyright and IPR is retained by the creators or other copyright holders. Terms and conditions for use of this material are defined in the [End User Agreement](#).

www.reading.ac.uk/centaur

CentAUR

Central Archive at the University of Reading

Reading's research outputs online



Generalised vectorial ∞ -eigenvalue nonlinear problems for L^∞ functionals

Nikos Katzourakis

Department of Mathematics and Statistics, University of Reading, Whiteknights Campus, Pepper Lane, Reading RG6 6AX, United Kingdom

ARTICLE INFO

Article history:

Received 19 October 2021

Accepted 25 January 2022

Communicated by Francesco Maggi

MSC:

35D30

35D40

35J47

35J92

35J70

35J99

35P30

Keywords:

∞ -Eigenvalue problem

Nonlinear Eigenvalue problems

∞ -Laplacian

L^∞ functionals

Absolute minimisers

Calculus of variations in L^∞

Lagrange multipliers

ABSTRACT

Let $\Omega \Subset \mathbb{R}^n$, $f \in C^1(\mathbb{R}^{N \times n})$ and $g \in C^1(\mathbb{R}^N)$, where $N, n \in \mathbb{N}$. We study the minimisation problem of finding $u \in W_0^{1,\infty}(\Omega; \mathbb{R}^N)$ that satisfies

$$\|f(Du)\|_{L^\infty(\Omega)} = \inf \left\{ \|f(Dv)\|_{L^\infty(\Omega)} : v \in W_0^{1,\infty}(\Omega; \mathbb{R}^N), \|g(v)\|_{L^\infty(\Omega)} = 1 \right\},$$

under natural assumptions on f, g . This includes the ∞ -eigenvalue problem as a special case. Herein we prove the existence of a minimiser u_∞ with extra properties, derived as the limit of minimisers of approximating constrained L^p problems as $p \rightarrow \infty$. A central contribution and novelty of this work is that u_∞ is shown to solve a divergence PDE with measure coefficients, whose leading term is a divergence counterpart equation of the non-divergence ∞ -Laplacian. Our results are new even in the scalar case of the ∞ -eigenvalue problem.

© 2022 Published by Elsevier Ltd.

1. Introduction and main results

Let $n, N \in \mathbb{N}$ be integers and let also $\Omega \Subset \mathbb{R}^n$ be a bounded open set with Lipschitz boundary. In this paper we study the following variational problem: find a minimising map $u_\infty : \overline{\Omega} \rightarrow \mathbb{R}^N$ in the space $W_0^{1,\infty}(\Omega; \mathbb{R}^N)$ that solves

$$\|f(Du_\infty)\|_{L^\infty(\Omega)} = \inf \left\{ \|f(Dv)\|_{L^\infty(\Omega)} : v \in W_0^{1,\infty}(\Omega; \mathbb{R}^N), \|g(v)\|_{L^\infty(\Omega)} = 1 \right\}. \quad (1.1)$$

We are also interested in studying the structure of such constrained minimisers, and also in deriving appropriate PDEs that they satisfy as necessary conditions. The functions $f : \mathbb{R}^{N \times n} \rightarrow \mathbb{R}$ and $g : \mathbb{R}^N \rightarrow \mathbb{R}$

E-mail address: n.katzourakis@reading.ac.uk.

will be assumed to satisfy certain natural hypotheses. We note that our general notation in (1.1) and subsequently will be either self-explanatory, or a convex combination of otherwise standard symbolisations (as e.g. in [16,21,23,36]).

The L^p counterpart of (1.1), and especially the L^2 case, is textbook material in the Calculus of Variations (see e.g. [19]). Especially, the case of $f = |\cdot|$ and $g = |\cdot|$, the corresponding Euclidean norms on $\mathbb{R}^{N \times n}$ and \mathbb{R}^N respectively, is known as the *p-eigenvalue problem*, or the eigenvalue problem for the *p*-Laplacian. The L^∞ case we study herein, particularly in the vectorial case of $N \geq 2$, is completely new and, despite its importance, has not been considered before. When $N = 1$ with f the Euclidean norm on \mathbb{R}^n and g the absolute value on \mathbb{R} , (1.1) reduces to the (scalar) ∞ -eigenvalue problem, whose study goes back to the seminal work of Juutinen–Lindqvist–Manfredi in [28]. Since then, there has been a considerable interest on this problem and also on relevant ones (see for instance Juutinen–Lindqvist [27] and Bhattacharya–Marazzi [7]), as well as on related problems with constraints (see e.g. Aronsson–Barron [2] and Barron–Jensen [4]). However, all these works are restricted to either the 1-dimensional case of $n = 1$, or to the scalar case of $N = 1$. Crucially, these approaches rely essentially on the (scalar) Aronsson–Euler operator and on the theory of Viscosity Solutions for nonlinear PDE, both of which are not available when $N \geq 2$ (for a general introduction to the field we refer to the lecture notes [14,29]). Indeed, virtually all works on scalar-valued Calculus of Variations in L^∞ rely in some way on viscosity solutions and on the comparison principle. For various interesting works, some of which are relevant to applications and some to the ∞ -eigenvalue problem, we refer to [3,5,8,9,11,12,22,26,35,37,39,40].

Vectorial and higher order variational problems involving constraints have only very recently started being explored (see [31,33] and also [13]). In either case, the vectorial nature of the problem requires novel methods which are not based neither on viscosity solutions, nor on the Aronsson–Euler equation. Let us also note that the mere existence of a minimiser u_∞ to (1.1) is a relatively simple matter by applying the Direct Method of the Calculus of Variations and weak* lower-semicontinuity arguments for supremal functionals (under the appropriate quasi-convexity assumptions for f , see e.g. [6]). However, if one wishes to derive additional information on these (generally non-unique) minimisers, for example derive a necessary PDE system they satisfy, then this is a far less trivial matter. Among other complications arising, the L^∞ norm is non-differentiable, non-strictly convex and lacks the property of being σ -additive with respect to the domain argument.

The customary starting point for L^∞ variational problems, which we also employ herein as well, is to obtain minimisers as limits of respective L^p approximating variational problems as $p \rightarrow \infty$. Although this is perhaps not an intrinsic L^∞ approach, it typically bears significant fruit as these *special* minimisers which are obtained as limits of L^p minimisers always carry a finer structure. The central novelty of this work though regards the necessary PDE conditions that such minimisers to (1.1) satisfy. Our approach in studying (1.1) is inspired by a recent development in higher order L^∞ problems by the author and Moser in [34] (related earlier observations were made in a geometric higher order context in [38]). The main idea is that, if one rescales the L^p Euler–Lagrange equations in a different way from the customary one used to derive the Aronsson–Euler equations as $p \rightarrow \infty$, then it is possible to derive a divergence structure PDE for the L^∞ minimiser. This should be understood as a divergence form counterpart of the non-divergence Aronsson–Euler equations. However, this forcing of divergence structure to the essentially non-divergence L^∞ equations has a price to be paid: the equations involve measure coefficients arising as auxiliary variables. This is somewhat reminiscent of the way that eigenvalues appear as parameters in an eigenvalue problem.

The observation that a divergence PDE with measure coefficients can be derived in L^∞ has also been made earlier in a work by Evans and Yu [20], and before that had also been conjectured by Aronsson himself, the founder of Calculus of Variations in L^∞ , in the unpublished note [1]. However, it was not pursued further, possibly because in the case studied in [20] as a divergence form counterpart of the ∞ -Laplacian, these measures could be highly degenerate and supported only on the boundary. This renders the PDE trivial

in the interior of the domain. Nevertheless, in the higher order case employed in [34] involving the ∞ -Bilaplacian, as well as in the case of constrained problems studied herein, these PDE systems with measure coefficients provide non-trivial information. In particular, in [34] these measure were absolutely continuous and in fact given by harmonic functions and, for (1.1), the boundary is a nullset and these measures are supported on “large” contact sets in the interior.

Now we present our main results. To this end, we will utilise the following hypotheses regarding the functions $f : \mathbb{R}^{N \times n} \rightarrow \mathbb{R}$ and $g : \mathbb{R}^N \rightarrow \mathbb{R}$:

$$\left\{ \begin{array}{l} (a) \quad f \in C^1(\mathbb{R}^{N \times n}), \\ (b) \quad f \text{ is (Morrey) quasiconvex on } \mathbb{R}^{N \times n}, \\ (c) \quad \text{exist } C_1, C_2 > 0 \text{ with } C_1 \leq C_2 \text{ such that} \\ \quad 0 < C_1 f(X) \leq \partial f(X) : X \leq C_2 f(X), \\ \quad \text{for all } X \in \mathbb{R}^{N \times n} \setminus \{0\}, \\ (d) \quad \text{exist } C_3, \dots, C_6 > 0, \alpha > 1 \text{ and } \beta \leq (\alpha - 1)/\alpha \text{ such that} \\ \quad -C_3 + C_4 |X|^\alpha \leq f(X) \leq C_5 |X|^\alpha + C_6, \\ \quad |\partial f(X)| \leq C_5 f(X)^\beta + C_6, \\ \quad \text{for all } X \in \mathbb{R}^{N \times n}, \end{array} \right. \quad (1.2)$$

and

$$\left\{ \begin{array}{l} (a) \quad g \in C^1(\mathbb{R}^N), \\ (b) \quad g \text{ is coercive, i.e for any } \eta \in \mathbb{R}^N \setminus \{0\} \text{ we have} \\ \quad \lim_{t \rightarrow \infty} g(t\eta) = \infty, \\ (c) \quad \text{exist } C_7, C_8 > 0 \text{ with } C_7 \leq C_8 \text{ such that} \\ \quad 0 < C_7 g(\eta) \leq \partial g(\eta) \cdot \eta \leq C_8 g(\eta), \\ \quad \text{for all } \eta \in \mathbb{R}^N \setminus \{0\}. \end{array} \right. \quad (1.3)$$

In the above, ∂f and ∂g denote the corresponding derivatives of f and g respectively, whilst “:” and “ \cdot ” symbolise the Euclidean inner products on $\mathbb{R}^{N \times n}$ and \mathbb{R}^N respectively. By “(Morrey) quasiconvexity” we mean the usual concept of quasiconvexity for integral functionals as e.g. presented in [16], not the “ L^∞ quasiconvexity notions” of Barron–Jensen–Wang [6]. Under these hypotheses, Theorem 1 that follows is our first main result.

Theorem 1. Suppose that (1.2) and (1.3) hold. Then, the following are true:

(A) The problem (1.1) has a solution $u_\infty \in W_0^{1,\infty}(\Omega; \mathbb{R}^N)$.

(B) There exist Radon measures

$$M_\infty \in \mathcal{M}(\overline{\Omega}; \mathbb{R}^{N \times n}), \quad \nu_\infty \in \mathcal{M}(\overline{\Omega})$$

and a number $\Lambda_\infty \geq 0$ such that

$$\left\{ \begin{array}{ll} \operatorname{div}(M_\infty) + \Lambda_\infty \partial g(u_\infty) \nu_\infty = 0, & \text{in } \Omega, \\ u_\infty = 0, & \text{on } \partial\Omega, \end{array} \right. \quad (1.4)$$

weakly in $(C_0^1(\overline{\Omega}; \mathbb{R}^N))^*$, with

$$\Lambda_\infty = \|f(Du_\infty)\|_{L^\infty(\Omega)} > 0. \quad (1.5)$$

Further, we have the uniform bounds

$$\left\{ \begin{array}{l} \Lambda_\infty \geq \left(\max \left\{ \frac{C_4^{1/\alpha}}{\operatorname{diam}(\Omega) \|\partial g\|_{L^\infty(\{0 \leq g \leq 1\})}} - C_3^{1/\alpha}, 0 \right\} \right)^\alpha, \\ \Lambda_\infty \leq C_5 \left(\frac{(g(\cdot \eta))^{-1}(1)}{R_\Omega} \right)^\alpha + C_6, \end{array} \right. \quad (1.6)$$

where R_Ω is the radius of the largest open ball in Ω , and $(g(\cdot\eta))^{-1}$ is the inverse of $s \mapsto g(s\eta)$ on $[0, \infty)$ for any fixed $\eta \in \mathbb{R}^N$ with $|\eta| = 1$ (well-defined by (1.3)).

(C) The quadruple $(u_\infty, \Lambda_\infty, M_\infty, \nu_\infty)$ satisfies the next approximation properties: there exists a sequence $(p_j)_1^\infty \subseteq (n/\alpha, \infty)$ with $p_j \rightarrow \infty$ as $j \rightarrow \infty$ and for any such p , a quadruple

$$(u_p, \Lambda_p, M_p, \nu_p) \in W_0^{1,\alpha p}(\Omega; \mathbb{R}^N) \times (0, \infty) \times \mathcal{M}(\overline{\Omega}; \mathbb{R}^{N \times n}) \times \mathcal{M}(\overline{\Omega})$$

such that

$$\begin{cases} u_p \longrightarrow u_\infty & \text{in } C^\gamma(\overline{\Omega}; \mathbb{R}^N), \text{ for all } \gamma \in (0, 1), \\ Du_p \longrightarrow Du_\infty & \text{in } L^q(\Omega; \mathbb{R}^{N \times n}), \text{ for all } q \in (1, \infty), \\ \Lambda_p \longrightarrow \Lambda_\infty & \text{in } [0, \infty), \\ M_p \xrightarrow{*} M_\infty & \text{in } \mathcal{M}(\overline{\Omega}; \mathbb{R}^{N \times n}), \\ \nu_p \xrightarrow{*} \nu_\infty & \text{in } \mathcal{M}(\overline{\Omega}), \end{cases} \quad (1.7)$$

as $p \rightarrow \infty$ along $(p_j)_1^\infty$. Further, u_p solves the minimisation problem

$$\|f(Du_p)\|_{L^p(\Omega)} = \inf \left\{ \|f(Dv)\|_{L^p(\Omega)} : v \in W_0^{1,\alpha p}(\Omega; \mathbb{R}^N), \|g(v)\|_{L^p(\Omega)} = 1 \right\} \quad (1.8)$$

and (u_p, Λ_p) solves weakly the divergence PDE system

$$\begin{cases} \operatorname{div} \left(f(Du_p)^{p-1} \partial f(Du_p) \right) + (\Lambda_p)^p g(u_p)^{p-1} \partial g(u_p) = 0, & \text{in } \Omega, \\ u_p = 0, & \text{on } \partial\Omega. \end{cases} \quad (1.9)$$

Finally, the measures M_p, ν_p are given by

$$\begin{cases} M_p := \frac{1}{\mathcal{L}^n(\Omega)} \left(\frac{f(Du_p)}{\Lambda_p} \right)^{p-1} \partial f(Du_p) \mathcal{L}^n \llcorner \Omega, \\ \nu_p := \frac{1}{\mathcal{L}^n(\Omega)} g(u_p)^{p-1} \mathcal{L}^n \llcorner \Omega. \end{cases} \quad (1.10)$$

We note that the meaning of the satisfaction of (1.4) weakly in $(C_0^1(\overline{\Omega}; \mathbb{R}^N))^*$ is as follows: for any test map $\phi \in C_0^1(\overline{\Omega}; \mathbb{R}^N)$, we have

$$\int_{\overline{\Omega}} D\phi : dM_\infty = \Lambda_\infty \int_{\overline{\Omega}} \partial g(u_\infty) \cdot \phi d\nu_\infty. \quad (1.11)$$

In general, the matrix-valued measure M_∞ in Theorem 1 implicitly depends on Du_∞ , but it is not clear how exactly, especially in the case that the derivative ∂f is nonlinear. Notwithstanding, if we strengthen our assumptions to include that f is quadratic, together with a more stringent condition on g , we obtain the stronger result of Theorem 2 that follows. Theorem 2 allows to characterise M_∞ as a linear function of a (special) Borel measurable representative Du_∞^* of the gradient of the minimiser. Additionally, we obtain much more detailed information on the structure of the measure coefficients arising. Our additional hypothesis required is the following.

$$\begin{cases} \text{Exists } \mathbf{A} \in \mathbb{R}^{N \times n} \otimes \mathbb{R}^{N \times n} \text{ such that, for all } X \in \mathbb{R}^{N \times n} \\ f(X) = \mathbf{A} : X \otimes X, \\ \text{and the assumption (1.3)(c) is satisfied with } C_7 = C_8. \end{cases} \quad (1.12)$$

Under (1.12), we may establish our second principal result, which is given right below.

Theorem 2. Suppose that (1.2), (1.3) and (1.12) are satisfied. Then, in addition to the conclusions of Theorem 1, the following are true:

(A) There exists a Radon measure $\mu_\infty \in \mathcal{M}(\overline{\Omega})$ and a Borel measurable mapping $Du_\infty^* : \overline{\Omega} \rightarrow \mathbb{R}^{N \times n}$, which is a version of $Du_\infty \in L^\infty(\Omega; \mathbb{R}^{N \times n})$, such that

$$M_\infty = \partial f(Du_\infty^*) \mu_\infty. \quad (1.13)$$

Hence, u_∞ solves the divergence PDE system

$$\begin{cases} \operatorname{div}(\partial f(Du_\infty^*) \mu_\infty) + \Lambda_\infty \partial g(u_\infty) \nu_\infty = 0, & \text{in } \Omega, \\ u_\infty = 0, & \text{on } \partial\Omega, \end{cases} \quad (1.14)$$

weakly in $(C_0^1(\overline{\Omega}; \mathbb{R}^N))^*$.

(B) The map Du_∞^* can be represented as

$$Du_\infty^*(x) = \begin{cases} \lim_{k \rightarrow \infty} Dv_{j_k}(x), & \text{if the limit exists,} \\ 0, & \text{otherwise,} \end{cases} \quad (1.15)$$

where $(v_j)_1^\infty \subseteq C_0^1(\overline{\Omega}; \mathbb{R}^N)$ is any sequence satisfying that

$$\begin{cases} \lim_{j \rightarrow \infty} \|v_j - u_\infty\|_{(W_0^{1,1} \cap L^\infty)(\Omega)} = 0, \\ \limsup_{j \rightarrow \infty} \|f(Dv_j)\|_{L^\infty(\Omega)} \leq \Lambda_\infty \end{cases}$$

(one such is constructed in the proof). Further, μ_∞ can be approximated by

$$\mu_p := \frac{1}{\mathcal{L}^n(\Omega)} \left(\frac{f(Du_p)}{\Lambda_p} \right)^{p-1} \mathcal{L}^n \llcorner_\Omega, \quad (1.16)$$

as $p_j \rightarrow \infty$, in the sense that $\mu_p \xrightarrow{*} \mu_\infty$ in $\mathcal{M}(\overline{\Omega})$.

(C) The measures μ_∞, ν_∞ concentrate whereon $f(Du_\infty^*)$ and $g(u_\infty)$ are respectively maximised over $\overline{\Omega}$. Additionally,

$$\begin{cases} \nu_\infty(\overline{\Omega}) = \nu_\infty(\{g(u_\infty) = 1\}) = 1, \\ \mu_\infty(\overline{\Omega}) = \mu_\infty(\{f(Du_\infty^*) = \Lambda_\infty\}) = C_8 C_1^{-1}. \end{cases} \quad (1.17)$$

Finally, the boundary $\partial\Omega$ is a nullset for both measures $Du_\infty^* \mu_\infty$ and ν_∞ :

$$\|Du_\infty^* \mu_\infty\|(\partial\Omega) = \nu_\infty(\partial\Omega) = 0. \quad (1.18)$$

Let us note that our results are new even in the special scalar case of the ∞ -eigenvalue problem, as we provide a new divergence PDE describing ∞ -eigenvectors, which is an alternative to the fully nonlinear PDE involving the ∞ -Laplacian derived in [28].

It is worth noting that our approach herein allows to bypass the need for theories of generalised solutions for the Aronsson–Euler systems arising in L^∞ , which are non-divergence, highly degenerate and with discontinuous coefficients. Such theories require different new ideas and some heavy machinery which depart from standard methods involving Viscosity Solutions (see e.g. [15,30] for work in this direction). Even though it is not expected that the Aronsson–Euler systems can become redundant in general, in this particular case we can indeed bypass them.

Now we describe the content and the organisation of this paper. The table of contents gives an idea regarding the order of presentation. The proofs of Theorems 1 and 2 do not appear explicitly in the main text, but instead are a consequence of numerous lemmas and propositions in Sections 2–6, which gradually establish all the claims made in the statements of Theorems 1–2, plus some additional auxiliary information for the p -problems.

In Section 2 we discuss our hypotheses showing that, albeit restrictive, they do nonetheless allow for large classes of functions f, g . In particular, (1.2)(c) is compatible with the possible lack of convexity. Evidently, (1.12) is considerably more restrictive, but still allows for a large class of functions g .

In Section 3 we prove a large part of the assertions made in Theorem 1, those which include existence for (1.1) and approximation via corresponding L^p constrained minimisation problems. A new ingredient here is the necessity to construct a strongly precompact class of admissible Lipschitz maps in the respective L^p minimisation classes, due to the lack of homogeneity of the functionals. Let us also note that for this part of the work, we could have relaxed our (Morrey) quasiconvexity assumption to include only “Barron–Jensen–Wang L^∞ quasiconvexity” as in [5,6] to prove existence of minimisers, by utilising Young measures or quasi-minimisers for the approximating L^p problems (for which the minima need not be attained). However, this added layer of technical complexity does not offer much insight as we need to assume considerably stronger assumptions to derive the necessary PDE systems satisfied by constrained minimisers.

In Section 4 we establish the satisfaction of the PDE system (1.4) under the weaker assumptions (1.2)–(1.3), by utilising tools developed in the previous sections.

In Section 5 we introduce the appropriate mollification operators required to prove Theorem 2. This regularisation scheme utilises results on the geometry of (strongly) Lipschitz domain proved in Hofmann–Mitrea–Taylor [24], and is closely related to the regularisation schemes used in Ern–Guermond [18]. The main idea is to use the existence of smooth vector fields which are transversal to the \mathcal{H}^{n-1} -a.e. defined normal vector field on $\partial\Omega$ to “shrink” the function to a compactly supported one in Ω , before regularising by convolution.

In Section 6 we complete the proofs of Theorems 1 and 2 by establishing the satisfaction of (1.14), utilising the results established in earlier sections. Key ingredients here are the use of an energy identity for L^p constrained minimisers and the use of Hutchinson’s measure function-pairs from [25], which are a convenient way to bypass the heavy use of Young measures to identify weak* limits of sequences of products of measures with functions.

Finally, in Section 7 we consider the vectorial counterpart of the ∞ -eigenvalue problem on the ball (i.e. for f, g being the Euclidean norms) and in this case we are able to compute explicit measures for which the divergence PDE is satisfied.

2. Preliminaries and discussion of hypotheses

We begin by noting that in this paper we are using the notation

$$C_0^1(\overline{\Omega}; \mathbb{R}^N) := C^1(\overline{\Omega}; \mathbb{R}^N) \cap C_0(\Omega; \mathbb{R}^N)$$

to symbolise the space of continuous mappings $\overline{\Omega} \rightarrow \mathbb{R}^N$ which vanish on $\partial\Omega$, are C^1 on Ω and whose derivatives extend continuously as mappings $\overline{\Omega} \rightarrow \mathbb{R}^{N \times n}$. Further, everywhere in this paper, for $p \in [1, \infty)$ we are tacitly using the rescaled L^p -norms defined as

$$\|h\|_{L^p(\Omega)} := \left(\frac{1}{\mathcal{L}^n(\Omega)} \int_{\Omega} |h|^p \, d\mathcal{L}^n \right)^{1/p} = \left(\int_{\Omega} |h|^p \, d\mathcal{L}^n \right)^{1/p},$$

which, by virtue of Hölder’s inequality, are a family of seminorms which is monotone increasing in $p \in [1, \infty)$. Regarding the notation used in (1.12), we note that \mathbf{A} is a fourth order tensor, seen as a matrix over the matrix space $\mathbb{R}^{N \times n}$ and “ \cdot ” therein is the corresponding Euclidean inner product in $\mathbb{R}^{N \times n} \otimes \mathbb{R}^{N \times n}$:

$$\mathbf{A} : \mathbf{B} = \sum_{1 \leq \alpha, \beta \leq N} \sum_{1 \leq i, j \leq n} \mathbf{A}_{\alpha i \beta j} \mathbf{B}_{\alpha i \beta j}.$$

Evidently, “ \otimes ” symbolises the tensor product of matrices, namely $X \otimes Y$ is the fourth order tensor with components $X_{\alpha i} Y_{\beta j}$, when $X, Y \in \mathbb{R}^{N \times n}$. We continue by noting that assumption (1.2)(c) readily implies that

$$f > 0 \text{ on } \mathbb{R}^{N \times n} \setminus \{0\}, \quad f(0) = 0 \quad \text{and } f \text{ is radially increasing on } \mathbb{R}^{N \times n}, \quad (2.1)$$

in the sense that $t \mapsto f(tX)$ is increasing on $(0, \infty)$, for any fixed $X \in \mathbb{R}^{N \times n} \setminus \{0\}$. Similarly, assumption (1.3)(c) implies that

$$g > 0 \text{ on } \mathbb{R}^N \setminus \{0\}, \quad g(0) = 0 \quad \text{and } g \text{ is radially increasing on } \mathbb{R}^N. \quad (2.2)$$

Albeit restrictive, there are nonetheless numerous (non-convex) functions which satisfy (1.2)–(1.3). As an illustration, in the example below we construct a large class of functions which satisfy the inequality (c) even though they are not radially symmetric. This class of course includes all quadratic functions. We argue on $\mathbb{R}^{N \times n}$ only, but the construction trivially applies to \mathbb{R}^N as well. Further, we remark that (1.2)(c) is compatible with (1.2)(b).

Example 3. Let \mathbf{S} be a compact C^1 hypersurface on $\mathbb{R}^{N \times n}$ satisfying

$$\mathbf{S} \subseteq \mathbb{B}_{3/2}(0) \setminus \mathbb{B}_{1/2} \quad (2.3)$$

and that any half-ray $\text{span}^+[E] := \{tE : t \geq 0\}$ along a unit direction $E \in \mathbb{R}^{N \times n}$ intersects \mathbf{S} at exactly one point:

$$\mathcal{H}^0(\text{span}^+[E] \cap \mathbf{S}) = 1.$$

We further suppose that the (outwards orientated) unit normal vector field $n_{\mathbf{S}} : \mathbf{S} \rightarrow \mathbb{R}^N$ satisfies $n_{\mathbf{S}}(X) : X > 0$, namely the angle between the normal vector at X and the direction X itself is acute. Let $\alpha > 1$ and define f to be the unique α -homogeneous function on $\mathbb{R}^{N \times n}$ satisfying

$$\mathbf{S} = \{f = 1\}.$$

Explicitly, f can be represented as

$$f(X) := \inf \left\{ t > 0 : [0, X) \cap t^{1/\alpha} \mathbf{S} = \emptyset \right\},$$

where $[0, X)$ is the straight line segment $\{tX : 0 \leq t < 1\}$ and $t^{1/\alpha} \mathbf{S}$ is the dilation of \mathbf{S} by $t^{1/\alpha}$. Then, by our assumptions on \mathbf{S} exists $\varepsilon_0 \in (0, 1)$ such that

$$\frac{1 - \varepsilon_0}{2} \leq (1 - \varepsilon_0)|X| \leq n_{\mathbf{S}}(X) : X \leq |X| \leq \frac{3}{2},$$

for all $X \in \mathbf{S}$. Since $\partial f(X) = n_{\mathbf{S}}(X)$ and also $f(X) = 1$ for $X \in \mathbf{S}$, the above inequalities yield

$$\frac{1 - \varepsilon_0}{2} f(X) \leq \partial f(X) : X \leq \frac{3}{2} f(X),$$

for all $X \in \mathbf{S}$. Finally, since

$$\mathbb{R}^{N \times n} = \bigcup_{t \geq 0} t^{1/\alpha} \mathbf{S},$$

by noting that f is α -homogeneous (which implies that ∂f is $(\alpha - 1)$ -homogeneous), the obtained inequality in fact holds on the entire space $\mathbb{R}^{N \times n}$.

Now we derive some consequences of the satisfaction of assumptions (1.2) and (1.12). First note that if $C_7 = C_8 \equiv C$ in (1.3), then we have $Cg(\eta) = \partial g(\eta) \cdot \eta$ as equality. Even though this is restrictive, there are still several functions satisfying this condition. For instance, for any (possibly non-symmetric) matrix $A \in \mathbb{R}^N \otimes \mathbb{R}^N$ and $\gamma > 0$, the function given by

$$g(\eta) := (A : \eta \otimes \eta)^{2\gamma}$$

satisfies the identity with $C = 4\gamma$, as

$$\partial g(\eta) \cdot \eta = \left\{ 2\gamma (A : \eta \otimes \eta)^{2\gamma-1} A : ((\cdot) \otimes \eta + \eta \otimes (\cdot)) \right\} \cdot \eta = 4\gamma g(\eta),$$

for all $\eta \in \mathbb{R}^N$.

Lemma 4. Suppose that f satisfies (1.2) and (1.12). Then:

(1) By setting

$$\mathbb{S}\mathbf{A} := \frac{\mathbf{A} + \mathbf{A}^{\top(1,2) \leftrightarrow (3,4)}}{2},$$

where $\mathbf{A}^{\top(1,2) \leftrightarrow (3,4)}$ is the adjoint of the linear map $\mathbf{A} : \mathbb{R}^{N \times n} \rightarrow \mathbb{R}^{N \times n}$, we have the representations

$$f(X) = \mathbb{S}\mathbf{A} : X \otimes X = |\sqrt{\mathbb{S}\mathbf{A}}X|^2,$$

for all $X \in \mathbb{R}^{N \times n}$. In particular, the symmetric part $\mathbb{S}\mathbf{A}$ of the tensor \mathbf{A} is positive definite (i.e. non-negative) and hence the square root $\sqrt{\mathbb{S}\mathbf{A}} : \mathbb{R}^{N \times n} \rightarrow \mathbb{R}^{N \times n}$ is well defined.

(2) We have the identity

$$\partial f(X) = \mathbf{A} : ((\cdot) \otimes X + X \otimes (\cdot)),$$

for all $X \in \mathbb{R}^{N \times n}$.

(3) f is non-negative and convex on $\mathbb{R}^{N \times n}$ with $\{f = 0\} = \{0\}$.

(4) Let σ denote the spectrum of a linear operator. Then, we have the bounds

$$(\min \sigma(\mathbb{S}\mathbf{A}))|X|^2 \leq f(X) \leq |\mathbf{A}||X|^2,$$

for all $X \in \mathbb{R}^{N \times n}$.

Note that the adjoint (transpose) operator $\mathbf{A}^{\top(1,2) \leftrightarrow (3,4)}$ is the operator which in index form satisfies

$$(\mathbf{A}^{\top(1,2) \leftrightarrow (3,4)})_{\alpha i \beta j} = \mathbf{A}_{\beta j \alpha i},$$

for all $\alpha, \beta \in \{1, \dots, N\}$ and all $i, j \in \{1, \dots, n\}$. This renders $\mathbb{S}\mathbf{A} \in \mathbb{R}^{N \times n} \otimes \mathbb{R}^{N \times n}$ a real self-adjoint (symmetric) fourth order tensor (seen as a matrix over matrices).

Proof of Lemma 4. (1) The identity $f(X) = \mathbb{S}\mathbf{A} : X \otimes X$ is immediate as the rank-one tensor $X \otimes X$ is symmetric, hence $\mathbf{A} = \mathbb{S}\mathbf{A}$ on the symmetric subspace of $\mathbb{R}^{N \times n} \otimes \mathbb{R}^{N \times n}$. Further, by (1.12), (1.2) holds for $\alpha = 2$ and by (2.1) we have

$$\mathbb{S}\mathbf{A} : X \otimes X \geq 0 \quad \text{and} \quad \mathbb{S}\mathbf{A} : X \otimes X \geq C_4|X|^2 - C_3,$$

for all $X \in \mathbb{R}^{N \times n}$. By the spectral theorem it follows that the symmetric tensor $\mathbb{S}\mathbf{A}$ is positive definite (i.e. non-negative) and $\sigma(\mathbb{S}\mathbf{A}) \subseteq [0, |\mathbf{A}|]$. Further, the estimate above implies that $\mathbb{S}\mathbf{A}$ is actually strictly positive

and $\min \sigma(\mathbb{S}\mathbf{A}) > 0$: indeed, if hypothetically there existed $X_0 \neq 0$ with $\mathbb{S}\mathbf{A} : X_0 \otimes X_0 = 0$, then for any $t > 0$

$$0 = \mathbb{S}\mathbf{A} : (tX_0) \otimes (tX_0) \geq t^2 C_4 |X_0|^2 - C_3,$$

which leads to a contradiction as $t \rightarrow \infty$. Finally, since \mathbf{A} is positive and symmetric, $\sqrt{\mathbb{S}\mathbf{A}}$ exists and is also a positive symmetric operator satisfying $\mathbb{S}\mathbf{A} = \sqrt{\mathbb{S}\mathbf{A}}\sqrt{\mathbb{S}\mathbf{A}}$. Therefore,

$$\begin{aligned} f(X) &= \mathbb{S}\mathbf{A} : X \otimes X \\ &= \left(\sqrt{\mathbb{S}\mathbf{A}} \sqrt{\mathbb{S}\mathbf{A}}^{\top(1,2) \leftrightarrow (3,4)} \right) : X \otimes X \\ &= (\sqrt{\mathbb{S}\mathbf{A}}X) : (\sqrt{\mathbb{S}\mathbf{A}}X) \\ &= |\sqrt{\mathbb{S}\mathbf{A}}X|^2, \end{aligned}$$

for any $X \in \mathbb{R}^{N \times n}$.

(2) Follows by a direct differentiation.

(3) Follows by part (1) by noting that f is the restriction of the convex quadratic form $(X, Y) \mapsto \mathbb{S}\mathbf{A} : X \otimes Y$ on the diagonal of $\mathbb{R}^{N \times n} \times \mathbb{R}^{N \times n}$.

(4) Follows directly from part (1), by recalling the variational definition of the minimum eigenvalue of a symmetric operator. \square

3. Existence in L^p and compactness as $p \rightarrow \infty$

In order to solve the approximating L^p constrained problems, we first need the following result which establishes the existence of strongly converging (energy comparison) maps as $p \rightarrow \infty$ in the respective constrained admissible classes.

Lemma 5. *For any $v \in W_0^{1,\infty}(\Omega; \mathbb{R}^N) \setminus \{0\}$, there exists $(t_p)_{p \in (n/\alpha, \infty]} \subseteq (0, \infty)$ with $t_p \rightarrow t_\infty$ as $p \rightarrow \infty$, such that*

$$\|g(t_p v)\|_{L^p(\Omega)} = 1$$

for all $p \in (n/\alpha, \infty]$. Further, if $\|g(v)\|_{L^\infty(\Omega)} = 1$, then $t_\infty = 1$.

Proof of Lemma 5. Fix $v \in W_0^{1,\infty}(\Omega; \mathbb{R}^N) \setminus \{0\}$ and set

$$\rho_\infty(t) := \max_{x \in \overline{\Omega}} g(tv(x)), \quad t \geq 0.$$

Then, by (1.3) and (2.2) we have that $\rho(0) = 0$ and also $\rho_\infty \in C([0, \infty))$. Now we show that ρ_∞ is strictly increasing. Let us begin by showing first it is non-decreasing. For any $s > 0$ and $\eta \in \mathbb{R}^N \setminus \{0\}$, (1.3) implies

$$0 < C_7 \frac{g(s\eta)}{s} \leq \partial g(s\eta) \cdot \eta = \frac{d}{ds}(g(s\eta)),$$

which yields that $s \mapsto g(s\eta)$ is strictly increasing on $(0, \infty)$. Then, for any $x \in \overline{\Omega}$ and $t > s \geq 0$ we have that $g(sv(x)) \leq g(tv(x))$ (with strict inequality if $v(x) \neq 0$), and therefore

$$\rho_\infty(s) = \max_{x \in \overline{\Omega}} g(sv(x)) \leq \max_{x \in \overline{\Omega}} g(tv(x)) = \rho_\infty(t).$$

Hence, ρ_∞ is non-decreasing. We now show that $t \mapsto \rho_\infty(t)$ is actually strictly increasing on $(0, \infty)$. Suppose for the sake of contradiction that this is not the case. Then, by the continuity of ρ_∞ , there exists $t_0, \varepsilon_0 > 0$

such that $\rho_\infty \equiv \rho_\infty(t_0)$ on the interval $(t_0 - \varepsilon_0, t_0 + \varepsilon_0)$. However, by Danskin's theorem [17], the derivative $\rho'(t_0^+)$ from the right exists, and is given by the formula

$$\rho'_\infty(t_0^+) = \max_{x \in \Omega_{t_0}} \{ \partial g(t_0 v(x)) \cdot v(x) \}$$

where

$$\Omega_{t_0} = \{ \bar{x} \in \overline{\Omega} : \rho_\infty(t_0) = g(t_0 v(\bar{x})) \}.$$

By utilising (1.3), the expression for $\rho'_\infty(t_0^+)$ yields

$$\begin{aligned} \rho'_\infty(t_0^+) &= \frac{1}{t_0} \max_{x \in \Omega_{t_0}} \{ \partial g(t_0 v(x)) \cdot t_0 v(x) \} \\ &\geq \frac{C_7}{t_0} \max_{x \in \Omega_{t_0}} g(t_0 v(x)) \\ &= \frac{C_7}{t_0} \rho_\infty(t_0) \\ &> 0. \end{aligned}$$

This is a contradiction to ρ_∞ being constant on $(t_0, t_0 + \varepsilon_0)$, hence establishing that ρ_∞ is indeed strictly increasing. Recall now that by (1.3)(b) we also have $g(s\eta) \rightarrow \infty$ as $s \rightarrow \infty$. Thus, for any fixed $\bar{x} \in \Omega$ for which $v(\bar{x}) \neq 0$, we have

$$\lim_{t \rightarrow \infty} \rho_\infty(t) \geq \lim_{t \rightarrow \infty} g(t v(\bar{x})) = \infty.$$

The mean value theorem then implies that there exists a number $t_\infty > 0$ such that $\rho_\infty(t_\infty) = 1$, namely

$$\|g(t_\infty v)\|_{L^\infty(\Omega)} = 1.$$

Additionally, if $\|g(v)\|_{L^\infty(\Omega)} = 1$ to begin with, then $t_\infty = 1$. Fix now $p \in (n/\alpha, \infty)$ and set

$$\rho_p(t) := \int_{\Omega} g(t v(x))^p dx, \quad t \geq 0.$$

Then, by (2.2) we have $\rho_p(0) = 0$ and also the strict monotonicity of $s \mapsto g(se)$ on $(0, \infty)$. Then, the monotone convergence theorem yields that $\rho_p(t) \rightarrow \infty$ as $t \rightarrow \infty$. Therefore, there exists $t_p > 0$ such that $\rho_p(t_p) = 1$, namely

$$\|g(t_p v)\|_{L^p(\Omega)} = 1.$$

We now claim that $t_p \rightarrow t_\infty$ as $p \rightarrow \infty$. Assuming for the sake of contradiction that $t_p \not\rightarrow t_\infty$ as $p \rightarrow \infty$, this means there exists a sequence $(t_{p_j})_1^\infty \subseteq (n/\alpha, \infty)$ and a $t_0 \in [0, t_\infty) \cup (t_\infty, \infty]$ such that $t_{p_j} \rightarrow t_0$ as $j \rightarrow \infty$. Further, the sequence $(t_{p_j})_1^\infty$ can be assumed to be monotone (either increasing or decreasing). We first show that $t_0 < \infty$. Indeed, if we had $t_0 = \infty$, then the sequence $(t_{p_j})_1^\infty$ must be monotone increasing. Hence, by (1.3)(b) we have $g(t_{p_j} v(x)) \nearrow \infty$ as $j \rightarrow \infty$, for any $x \in \Omega \cap \{v \neq 0\}$. The monotone convergence theorem then yields the contradiction

$$1 = \int_{\Omega} g(t_{p_j} v)^{p_j} d\mathcal{L}^n \nearrow \infty.$$

Therefore, we must have $t_0 < \infty$ and hence $t_0 \in [0, t_\infty) \cup (t_\infty, \infty)$. If now $t_{p_j} \rightarrow t_0$, we have $t_{p_j} v \rightarrow t_0 v$ in $C(\overline{\Omega}; \mathbb{R}^N)$, as $j \rightarrow \infty$. By the continuity of g , this implies $g(t_{p_j} v) \rightarrow g(t_0 v)$ in $C(\overline{\Omega})$, as $j \rightarrow \infty$. Since $\|\cdot\|_{L^p(\Omega)} \rightarrow \|\cdot\|_{L^\infty(\Omega)}$ as $p \rightarrow \infty$ in the pointwise sense on $L^\infty(\Omega)$, we infer that

$$\begin{aligned} 1 &= \|g(t_{p_j} v)\|_{L^{p_j}(\Omega)} \\ &= \|g(t_0 v)\|_{L^{p_j}(\Omega)} + O(\|g(t_{p_j} v) - g(t_0 v)\|_{L^\infty(\Omega)}) \\ &= \|g(t_0 v)\|_{L^{p_j}(\Omega)} + O(|t_{p_j} - t_0|) \\ &\xrightarrow{j \rightarrow \infty} \|g(t_0 v)\|_{L^\infty(\Omega)} \\ &= \rho_\infty(t_0), \end{aligned}$$

which is a contradiction if $t_\infty \neq t_0$ due to the strict monotonicity of ρ_∞ . \square

Now we proceed to show existence of solution to the approximate constrained minimisation problem.

Lemma 6. *For any $p > n/\alpha$, the minimisation problem (1.8) has a solution $u_p \in W_0^{1,\alpha p}(\Omega; \mathbb{R}^N)$.*

Proof of Lemma 6. Let $p \in (n/\alpha, \infty)$ be fixed. We begin by noting that, by virtue of Lemma 5, the admissible class is non-empty: for any fixed $v_0 \in W_0^{1,\infty}(\Omega; \mathbb{R}^N)$ with $v_0 \not\equiv 0$, there exists $t_p > 0$ such that $\|g(t_p v_0)\|_{L^p(\Omega)} = 1$, yielding that $t_p v_0$ is in the admissible class of (1.8). Next, since by (1.2)(b) f is (Morrey) quasiconvex in $\mathbb{R}^{N \times n}$, so is f^p , as a result of Jensen's inequality: indeed, for any fixed $X \in \mathbb{R}^{N \times n}$ and $\phi \in W_0^{1,\infty}(\Omega; \mathbb{R}^N)$, we have

$$f^p(X) \leq \left(\int_{\Omega} f(X + D\phi) d\mathcal{L}^n \right)^p \leq \int_{\Omega} f^p(X + D\phi) d\mathcal{L}^n.$$

Further, by (1.2)(d) f^p satisfies the estimate

$$-C_3(p) + C_4(p)|X|^{\alpha p} \leq f^p(X) \leq C_5(p)|X|^{\alpha p} + C_6(p),$$

for some p -dependent constants $C_3(p), \dots, C_6(p) > 0$. By standard results on quasiconvex integral functionals (see e.g. [16]), it follows that $\|f(D(\cdot))\|_{L^p(\Omega)}$ is weakly lower semi-continuous and coercive in the space $W_0^{1,\alpha p}(\Omega; \mathbb{R}^N)$. Further, by the Morrey embedding $W_0^{1,\alpha p}(\Omega; \mathbb{R}^N) \subseteq C^{1-\frac{n}{\alpha p}}(\overline{\Omega}; \mathbb{R}^N)$, it follows that the admissible class is weakly closed as the functional $\|g(\cdot)\|_{L^p(\Omega)}$ is weakly continuous on $W_0^{1,\alpha p}(\Omega; \mathbb{R}^N)$. Hence, there exists a minimiser u_p which solves (1.8), as claimed. \square

Now we consider the Euler–Lagrange equations that the approximate minimiser u_p satisfies. Unsurprisingly, they involve a Lagrange multiplier, which arises by the integral constraint $\|g(\cdot)\|_{L^p(\Omega)} = 1$.

Lemma 7. *For any $p > n/\alpha$, let u_p be the minimiser of (1.8) given by Lemma 6. Then, there exists $\lambda_p \in \mathbb{R}$ such that the pair $(u_p, \lambda_p) \in W_0^{1,\alpha p}(\Omega; \mathbb{R}^N) \times \mathbb{R}$ satisfies weakly the PDE system*

$$\begin{cases} \operatorname{div} \left(f(Du_p)^{p-1} \partial f(Du_p) \right) + \lambda_p g(u_p)^{p-1} \partial g(u_p) = 0, & \text{in } \Omega, \\ u_p = 0, & \text{on } \partial\Omega. \end{cases}$$

Proof of Lemma 7. Follows by standard results on Lagrange multipliers in Banach spaces (see e.g. Zeidler [41, Th. 43.D, p. 290]). \square

Now we obtain additional information on the family of eigenvalues $(\lambda_p)_{p>n/\alpha}$.

Lemma 8. *For any $p > n/\alpha$, we set*

$$L_p := \|f(Du_p)\|_{L^p(\Omega)}.$$

Then, there exists $A_p > 0$ such that

$$\lambda_p = (A_p)^p$$

and also

$$0 < \left(\frac{C_1}{C_8} \right)^{1/p} L_p \leq A_p \leq \left(\frac{C_2}{C_7} \right)^{1/p} L_p.$$

Proof of Lemma 8. We begin by noting that $L_p > 0$, namely the infimum over the admissible class in (1.8) is strictly positive, as a consequence of the constraint and our assumptions (1.2)–(1.3) (via (2.1)–(2.2)):

the only map $u \in W_0^{1,\alpha p}(\Omega; \mathbb{R}^N)$ for which $\|f(Du)\|_{L^p(\Omega)} = 0$ is $u_0 \equiv 0$, but u_0 is not in the admissible class because $\|g(u_0)\|_{L^p(\Omega)} = 0$. Next, by testing against u_p in the weak formulation of the Euler–Lagrange equations (Lemma 7), we have

$$\int_{\Omega} f(Du_p)^{p-1} \partial f(Du_p) : Du_p \, d\mathcal{L}^n = \lambda_p \int_{\Omega} g(u_p)^{p-1} \partial g(u_p) \cdot u_p \, d\mathcal{L}^n.$$

By (1.2)(c) and (1.3)(c) we have

$$\begin{cases} C_1 f(Du_p) \leq \partial f(Du_p) : Du_p \leq C_2 f(Du_p), \\ C_7 g(u_p) \leq \partial g(u_p) \cdot u_p \leq C_8 g(u_p), \end{cases}$$

\mathcal{L}^n -a.e. on Ω . Hence, since $f, g \geq 0$, integration gives

$$\begin{cases} C_1 \int_{\Omega} f^p(Du_p) \, d\mathcal{L}^n \leq \int_{\Omega} f^{p-1}(Du_p) \partial f(Du_p) : Du_p \, d\mathcal{L}^n \leq C_2 \int_{\Omega} f^p(Du_p) \, d\mathcal{L}^n, \\ C_7 \int_{\Omega} g^p(u_p) \, d\mathcal{L}^n \leq \int_{\Omega} g^{p-1}(u_p) \partial g(u_p) \cdot u_p \, d\mathcal{L}^n \leq C_8 \int_{\Omega} g^p(u_p) \, d\mathcal{L}^n. \end{cases}$$

By recalling that

$$\int_{\Omega} f^p(Du_p) \, d\mathcal{L}^n = (L_p)^p > 0 \quad \text{and} \quad \int_{\Omega} g^p(u_p) \, d\mathcal{L}^n = 1,$$

it follows that $\lambda_p > 0$. By virtue of the above, by defining $\Lambda_p := (\lambda_p)^{1/p} > 0$, we have the estimates

$$C_1 (L_p)^p \leq \lambda_p C_8, \quad C_2 (L_p)^p \geq \lambda_p C_7,$$

which lead to the desired inequality. \square

We now show the existence of solution to the problem (1.1) and the compactness of the class of p -pairs of eigenvectors–eigenvalues $(u_p, \Lambda_p)_{p>n/\alpha}$.

Proposition 9. *There exists $(u_{\infty}, \Lambda_{\infty}) \in W_0^{1,\infty}(\Omega; \mathbb{R}^N) \times (0, \infty)$ such that, along a sequence $(p_j)_1^{\infty}$ we have*

$$\begin{cases} u_p \longrightarrow u_{\infty} & \text{in } C^{\gamma}(\overline{\Omega}; \mathbb{R}^N), \text{ for all } \gamma \in (0, 1), \\ Du_p \longrightarrow Du_{\infty} & \text{in } L^q(\Omega; \mathbb{R}^{N \times n}), \text{ for all } q \in (1, \infty), \\ \Lambda_p \longrightarrow \Lambda_{\infty} & \text{in } (0, \infty). \end{cases}$$

Further, u_{∞} solves the minimisation problem (1.1) and also Λ_{∞} is given by (1.5). Finally, Λ_{∞} satisfies the uniform bounds (1.6).

Proof of Proposition 9. Fix $p > n/\alpha$, $q \leq p$ and a map $v_0 \in W_0^{1,\infty}(\Omega; \mathbb{R}^N)$ with $v_0 \not\equiv 0$. Then, by Lemma 5 there exists $(t_p)_{p \in (n/\alpha, \infty]} \subseteq (0, \infty)$ with $t_p \longrightarrow t_{\infty}$ as $p \rightarrow \infty$, such that $\|g(t_p v_0)\|_{L^p(\Omega)} = 1$ for all $p \in (n/\alpha, \infty]$. By Hölder’s inequality and minimality, this allows to estimate

$$\|f(Du_p)\|_{L^q(\Omega)} \leq \|f(Du_p)\|_{L^p(\Omega)} \leq \|f(D(t_p v_0))\|_{L^p(\Omega)} \leq \|f(t_p Dv_0)\|_{L^{\infty}(\Omega)}.$$

Hence,

$$\sup_{q \geq p} \|f(Du_p)\|_{L^q(\Omega)} \leq \sup_{q \geq p} \|f(t_p Dv_0)\|_{L^{\infty}(\Omega)} < \infty,$$

and the finiteness of the last term is a consequence of the compactness of $(t_p)_{p>n/\alpha}$. Further, by (1.2) we have the lower bound $f^q(X) \geq C_4(q)|X|^{\alpha q} - C_3(q)$ for some q -dependent constants $C_3(q), C_4(q) > 0$ and all $X \in \mathbb{R}^{N \times n}$. When combined with the previous estimate, this lower bound implies

$$\sup_{q \geq p} \|Du_p\|_{L^{\alpha q}(\Omega)} \leq C(q) < \infty,$$

for some q -dependent $C(q) > 0$. Further, application of Poincaré's inequality improves the above estimate to

$$\sup_{q \geq p} \|u_p\|_{W^{1,\alpha q}(\Omega)} \leq C(q) < \infty,$$

for a new constant $C(q) > 0$. Hence, standard compactness and diagonal arguments in Sobolev spaces imply the existence of a map

$$u_\infty \in \bigcap_{n/\alpha < p < \infty} W_0^{1,\alpha p}(\Omega; \mathbb{R}^N)$$

and (for any sequence) a subsequence such that the claimed modes of convergence hold true as $p \rightarrow \infty$ along this subsequence. Fix now any $v \in W_0^{1,\infty}(\Omega; \mathbb{R}^N)$ satisfying $\|g(v)\|_{L^\infty(\Omega)} = 1$. Note that, necessarily, $v \not\equiv 0$ by virtue of (2.2). By Lemma 5, there exists $(t_p)_{p \in (n/\alpha, \infty)} \subseteq (0, \infty)$ with $t_p \rightarrow 1$ as $p \rightarrow \infty$, such that $\|g(t_p v)\|_{L^p(\Omega)} = 1$ for all $p > n/\alpha$. By Lemma 6, the definition of L_p in Lemma 8, Hölder inequality and minimality, we estimate

$$\|f(Du_p)\|_{L^q(\Omega)} \leq L_p \leq \|f(t_p Dv)\|_{L^p(\Omega)}$$

for any such v . By the weak lower semi-continuity of the functional $\|f(D(\cdot))\|_{L^q(\Omega)}$ on $W_0^{1,\alpha q}(\Omega)$, by letting $p \rightarrow \infty$ along a subsequence, we obtain for the given fixed $v \in W_0^{1,\infty}(\Omega; \mathbb{R}^N)$ that

$$\|f(Du_\infty)\|_{L^q(\Omega)} \leq \liminf_{p_j \rightarrow \infty} L_{p_j} \leq \limsup_{p_j \rightarrow \infty} L_{p_j} \leq \|f(Dv)\|_{L^\infty(\Omega)}.$$

In conclusion, by letting also $q \rightarrow \infty$, we deduce the energy inequality

$$\begin{cases} \|f(Du_\infty)\|_{L^\infty(\Omega)} \leq \liminf_{p_j \rightarrow \infty} L_{p_j} \leq \limsup_{p_j \rightarrow \infty} L_{p_j} \leq \|f(Dv)\|_{L^\infty(\Omega)}, \\ \text{for any } v \in W_0^{1,\infty}(\Omega; \mathbb{R}^N) \text{ with } \|g(v)\|_{L^\infty(\Omega)} = 1. \end{cases}$$

Next, we note that $Du_\infty \in L^\infty(\Omega; \mathbb{R}^{N \times n})$ (and is not merely in the intersection of $L^{\alpha p}(\Omega; \mathbb{R}^{N \times n})$ for $p \in (n/\alpha, \infty)$). This follows by (1.2), which yields

$$\|f(Du_\infty)\|_{L^\infty(\Omega)} \geq C_4 \|Du_\infty\|_{L^\infty(\Omega)}^\alpha - C_3.$$

As a result, by Morrey's estimate we have that $u_\infty \in W_0^{1,\infty}(\Omega; \mathbb{R}^N)$. Further, u_∞ is in the admissible class of (1.1), since by the uniform convergence $u_p \rightarrow u_\infty$ on $\overline{\Omega}$ as $p \rightarrow \infty$ along a subsequence, the continuity of g , we have

$$\begin{aligned} 1 &= \|g(u_p)\|_{L^p(\Omega)} \\ &= \|g(u_\infty)\|_{L^p(\Omega)} + (\|g(u_p)\|_{L^p(\Omega)} - \|g(u_\infty)\|_{L^p(\Omega)}) \\ &= \|g(u_\infty)\|_{L^p(\Omega)} + O(\|g(u_p) - g(u_\infty)\|_{L^p(\Omega)}) \\ &= \|g(u_\infty)\|_{L^p(\Omega)} + O(\|g(u_p) - g(u_\infty)\|_{L^\infty(\Omega)}) \\ &\rightarrow \|g(u_\infty)\|_{L^\infty(\Omega)}, \end{aligned}$$

as $p \rightarrow \infty$ subsequentially. In conclusion, by the arbitrariness of the map v in our energy inequality, it follows that u_∞ indeed solves the minimisation problem (1.1).

Let now Λ_∞ be defined by

$$\Lambda_\infty := \|f(Du_\infty)\|_{L^\infty(\Omega)}.$$

Note that the above definition of Λ_∞ as the infimum in (1.1) readily implies that it must be strictly positive. Indeed, by (2.1)–(2.2), for any map u_0 in the admissible class of (1.1) for which we have $\|f(Du_0)\|_{L^\infty(\Omega)} = 0$, it follows that $u_0 \equiv 0$, which is a contradiction since we must also have $\|g(u_0)\|_{L^\infty(\Omega)} = 0 < 1$. Further, the choice $v := u_\infty$ in our energy inequality implies that $L_p \rightarrow \Lambda_\infty$ as $p \rightarrow \infty$ along a subsequence. Additionally, by Lemma 8 we have that $|L_p - \Lambda_p| \rightarrow 0$ as $p \rightarrow \infty$, hence $\Lambda_p \rightarrow \Lambda_\infty$ as $p \rightarrow \infty$.

To complete the proof, it remains to establish the claimed uniform bounds on Λ_∞ . By Poincaré's inequality, since $g(0) = 0$, we have

$$\begin{aligned} 1 &= \|g(u_\infty)\|_{L^\infty(\Omega)} \leq \text{diam}(\Omega) \|D(g(u_\infty))\|_{L^\infty(\Omega)} \\ &\leq \text{diam}(\Omega) \|\partial g\|_{L^\infty(u_\infty(\overline{\Omega}))} \|Du_\infty\|_{L^\infty(\Omega)}. \end{aligned}$$

Since $g \geq 0$ and $\|g(u_\infty)\|_{L^\infty(\Omega)} = 1$, this yields that $0 \leq g(u_\infty) \leq 1$ everywhere on $\overline{\Omega}$. Hence, we have $u(\overline{\Omega}) \subseteq \{0 \leq g \leq 1\}$, which in turn implies

$$1 \leq \text{diam}(\Omega) \|\partial g\|_{L^\infty(\{0 \leq g \leq 1\})} \|Du_\infty\|_{L^\infty(\Omega)}.$$

Since by (1.2) we have $|X| \leq C_4^{-1/\alpha} (f(X) + C_3)^{1/\alpha}$ for any $X \in \mathbb{R}^{N \times n}$, we obtain

$$1 \leq \text{diam}(\Omega) \|\partial g\|_{L^\infty(\{0 \leq g \leq 1\})} \frac{\|f(Du_\infty)\|_{L^\infty(\Omega)}^{1/\alpha} + C_3^{1/\alpha}}{C_4^{1/\alpha}}.$$

The above inequality readily leads to the claimed lower bound for Λ_∞ in (1.6).

For the upper bound, consider the Lipschitz function $\text{dist}(\cdot, \partial\Omega)$ of distance from the boundary $\partial\Omega$, extended by zero on $\mathbb{R}^n \setminus \Omega$. Since $\text{dist}(\cdot, \partial\Omega) \in W_0^{1,\infty}(\Omega)$, for any fixed $\eta \in \mathbb{R}^N$ with $|\eta| = 1$ we may invoke Lemma 5 to find $t_\infty > 0$ such that $\xi_\infty := t_\infty \text{dist}(\cdot, \partial\Omega)\eta$ is in the admissible class for (1.1), namely $\|g(\xi_\infty)\|_{L^\infty(\Omega)} = 1$. Since $|D(\text{dist}(\cdot, \partial\Omega))| \leq 1$ \mathcal{L}^n -a.e. on Ω , by minimality and (1.2), we estimate

$$\begin{aligned} \Lambda_\infty &= \|f(Du_\infty)\|_{L^\infty(\Omega)} \\ &\leq \|f(D\xi_\infty)\|_{L^\infty(\Omega)} \\ &\leq \|f(t_\infty \eta \otimes D(\text{dist}(\cdot, \partial\Omega)))\|_{L^\infty(\Omega)} \\ &\leq C_5 \left(t_\infty \|\eta \otimes D(\text{dist}(\cdot, \partial\Omega))\|_{L^\infty(\Omega)} \right)^\alpha + C_6 \\ &\leq C_5 (t_\infty)^\alpha + C_6. \end{aligned}$$

Now we need an estimate for t_∞ . To this end, let

$$R_\Omega := \sup\{r > 0 \mid \exists x \in \Omega : \mathbb{B}_r(x) \subseteq \Omega\}.$$

Then, there exists an $\bar{x} \in \Omega$ such that $\mathbb{B}_{R_\Omega}(\bar{x}) \subseteq \Omega$, and this is the largest such ball. Hence, $\text{dist}(\bar{x}, \partial\Omega) = R_\Omega$. Since by construction, ξ_∞ satisfies $\|g(\xi_\infty)\|_{L^\infty(\Omega)} = 1$, it follows that

$$1 = \sup_{\Omega} g(t_\infty \text{dist}(\cdot, \partial\Omega)\eta) \geq g(t_\infty \text{dist}(\bar{x}, \partial\Omega)\eta) = g(t_\infty R_\Omega \eta).$$

By (2.2), we have that the function $[0, \infty) \ni s \mapsto g(s\eta) \in [0, \infty)$ is strictly increasing and onto because $g(0) = 0$ and $g(s\eta) \rightarrow \infty$ as $s \rightarrow \infty$. Hence, its inverse function $(g(\cdot\eta))^{-1} : [0, \infty) \rightarrow [0, \infty)$ is well defined. Therefore, since $g(t_\infty R_\Omega \eta) \leq 1$, we have

$$t_\infty R_\Omega = (g(\cdot\eta))^{-1}(g(R_\Omega \eta)) \leq (g(\cdot\eta))^{-1}(1).$$

Combining the previous estimates, we infer that

$$\Lambda_\infty \leq C_5 \left(\frac{1}{R_\Omega} (g(\cdot\eta))^{-1}(1) \right)^\alpha + C_6.$$

The above estimate completes the claimed uniform upper bound on Λ_∞ in (1.6), and therefore Proposition 9 ensues. \square

4. The divergence PDE system in L^∞ , part I

Using the tools already developed, in this section we establish the satisfaction of the divergence PDE system (1.4) by the pair $(u_\infty, \Lambda_\infty)$, under only assumptions (1.2)–(1.3). Later in Section 6 we will establish satisfaction of (1.14) under the additional stronger assumption (1.12). We begin with the limiting measures.

Lemma 10. *For any $p > n/\alpha + 2$, consider the non-negative measures $\mu_p, \nu_p \in \mathcal{M}(\overline{\Omega})$ and also the matrix-valued measure $M_p \in \mathcal{M}(\overline{\Omega}; \mathbb{R}^{N \times n})$, given by (1.10) and (1.16). Then, for all large enough p we have the bounds*

$$\begin{cases} \mu_p(\overline{\Omega}) \leq \left(\frac{C_8}{C_1}\right)^{1-\frac{1}{p}}, \\ \|M_p\|(\overline{\Omega}) \leq \left(\frac{C_8}{C_1}\right)^{1-\frac{1}{p}} \left(C_5(\Lambda_\infty + 1)^\beta + C_6\right), \end{cases}$$

and, by setting $\omega(p) := \|g(u_p) - g(u_\infty)\|_{L^\infty(\Omega)}$, we have

$$\begin{cases} \frac{1}{1 + \omega(p)} \leq \nu_p(\overline{\Omega}) \leq 1, \\ \nu_p\left(\left\{g(u_\infty) < \|g(u_\infty)\|_{L^\infty(\Omega)} - 2\omega(p)\right\}\right) \leq (1 - \omega(p))^{p-1}, \end{cases}$$

for $p, q \geq n/\alpha + 2$ large enough. Consequently, there exists a further subsequence and limiting measures $\mu_\infty, \nu_\infty \in \mathcal{M}(\overline{\Omega})$ and $M_\infty \in \mathcal{M}(\overline{\Omega}; \mathbb{R}^{N \times n})$ such that $\mu_p \xrightarrow{*} \mu_\infty$ and $\nu_p \xrightarrow{*} \nu_\infty$ in $\mathcal{M}(\overline{\Omega})$, and also $M_p \xrightarrow{*} M_\infty$ in $\mathcal{M}(\overline{\Omega}; \mathbb{R}^{N \times n})$, as $p \rightarrow \infty$, along this subsequence. Additionally, ν_∞ satisfies

$$\nu_\infty(\overline{\Omega}) = \nu_\infty\left(\left\{g(u_\infty) = \|g(u_\infty)\|_{L^\infty(\Omega)}\right\}\right) = 1, \quad \nu_\infty(\partial\Omega) = 0.$$

Proof of Lemma 10. By (1.16) and Lemma 8 we estimate

$$\begin{aligned} \mu_p(\Omega) &= \int_\Omega \left(\frac{f(\mathrm{D}u_p)}{\Lambda_p}\right)^{p-1} \mathrm{d}\mathcal{L}^n \\ &\leq \frac{1}{\Lambda_p^{p-1}} \left(\int_\Omega f(\mathrm{D}u_p)^p \mathrm{d}\mathcal{L}^n\right)^{\frac{p-1}{p}} \\ &= \left(\frac{L_p}{\Lambda_p}\right)^{p-1} \\ &\leq \left(\frac{C_8}{C_1}\right)^{1-\frac{1}{p}}. \end{aligned}$$

Further, for $p > n/\alpha + 2$, by (1.10) and assumption (1.2)(d), we estimate

$$\begin{aligned} \|M_p\|(\overline{\Omega}) &= \int_\Omega \left(\frac{f(\mathrm{D}u_p)}{\Lambda_p}\right)^{p-1} |\partial f(\mathrm{D}u_p)| \mathrm{d}\mathcal{L}^n \\ &\leq \frac{1}{\Lambda_p^{p-1}} \int_\Omega f(\mathrm{D}u_p)^{p-1} \left(C_5 f(\mathrm{D}u_p)^\beta + C_6\right) \mathrm{d}\mathcal{L}^n \\ &= \frac{1}{\Lambda_p^{p-1}} \int_\Omega \left(C_5 f(\mathrm{D}u_p)^{p-1+\beta} + C_6 f(\mathrm{D}u_p)^{p-1}\right) \mathrm{d}\mathcal{L}^n. \end{aligned}$$

In view of Lemma 8 and Proposition 9, for large p the previous estimate yields

$$\begin{aligned}\|M_p\|(\overline{\Omega}) &\leq \frac{C_5}{\Lambda_p^{p-1}} \left(\int_{\Omega} f(\mathbf{D}u_p)^p \, d\mathcal{L}^n \right)^{\frac{p-1+\beta}{p}} + \frac{C_6}{\Lambda_p^{p-1}} \left(\int_{\Omega} f(\mathbf{D}u_p)^p \, d\mathcal{L}^n \right)^{\frac{p-1}{p}} \\ &= C_5 \frac{L_p^{p-1+\beta}}{\Lambda_p^{p-1}} + C_6 \frac{L_p^{p-1}}{\Lambda_p^{p-1}} \\ &= \left(\frac{L_p}{\Lambda_p} \right)^{p-1} (C_5 L_p^{\beta} + C_6) \\ &\leq \left(\frac{C_8}{C_1} \right)^{1-\frac{1}{p}} \left(C_5 (\Lambda_{\infty} + 1)^{\beta} + C_6 \right),\end{aligned}$$

as claimed. Similarly, by (1.10) and the fact that $\|g(u_p)\|_{L^p(\Omega)} = 1$, we may estimate

$$\nu_p(\overline{\Omega}) = \int_{\Omega} g(u_p)^{p-1} \, d\mathcal{L}^n \leq \left(\int_{\Omega} g(u_p)^p \, d\mathcal{L}^n \right)^{\frac{p-1}{p}} = 1.$$

Next, by setting $\omega(p) := \|g(u_p) - g(u_{\infty})\|_{L^{\infty}(\Omega)}$ and noting that $\omega(p) \rightarrow 0$ as $p \rightarrow \infty$ (along a subsequence) due to the uniform convergence $g(u_p) \rightarrow g(u_{\infty})$ on $\overline{\Omega}$, we estimate

$$\begin{aligned}1 &= \int_{\Omega} g(u_p)^p \, d\mathcal{L}^n \\ &= \int_{\Omega} g(u_p)^{p-1} g(u_p) \, d\mathcal{L}^n \\ &\leq \int_{\Omega} g(u_p)^{p-1} \left(g(u_{\infty}) + \|g(u_p) - g(u_{\infty})\|_{L^{\infty}(\Omega)} \right) \, d\mathcal{L}^n \\ &\leq \int_{\Omega} g(u_p)^{p-1} (1 + \omega(p)) \, d\mathcal{L}^n,\end{aligned}$$

where in the last step we also used that $g(u_{\infty}) \leq 1$ on Ω , as a consequence of the continuity and the non-negativity of $g(u_{\infty})$ and the constraint $\|g(u_{\infty})\|_{L^{\infty}(\Omega)} = 1$. Hence, the above inequality shows that

$$1 \leq \nu_p(\overline{\Omega})(1 + \omega(p)).$$

Finally, let us fix $q \geq n/\alpha + 2$ and define the open set

$$A_q := \left\{ g(u_{\infty}) < \|g(u_{\infty})\|_{L^{\infty}(\Omega)} - 2\omega(q) \right\}.$$

We note that the desired remaining estimate for ν_p can be deduced by the more general result [32, Proposition 7], but for the sake of completeness we provide a self-contained simpler proof. For p and ε as above, we estimate

$$\begin{aligned}\nu_p(A_q) &= \frac{1}{\mathcal{L}^n(\Omega)} \int_{A_q} g(u_p)^{p-1} \, d\mathcal{L}^n \\ &\leq \frac{1}{\mathcal{L}^n(\Omega)} \int_{A_q} \left(g(u_{\infty}) + \|g(u_p) - g(u_{\infty})\|_{L^{\infty}(\Omega)} \right)^{p-1} \, d\mathcal{L}^n \\ &\leq \frac{1}{\mathcal{L}^n(\Omega)} \int_{A_q} (g(u_{\infty}) + \omega(q))^{p-1} \, d\mathcal{L}^n.\end{aligned}$$

Hence, by noting that $A_q = \{g(u_{\infty}) < 1 - 2\omega(q)\}$, which a result of our earlier observations, the above estimate implies

$$\begin{aligned}\nu_p(A_q) &\leq \frac{1}{\mathcal{L}^n(\Omega)} \int_{A_q} \left((1 - 2\omega(q)) + \omega(q) \right)^{p-1} \, d\mathcal{L}^n \\ &\leq \frac{\mathcal{L}^n(A_q)}{\mathcal{L}^n(\Omega)} (1 - \omega(q))^{p-1} \\ &\leq (1 - \omega(q))^{p-1}.\end{aligned}$$

This establishes all the claimed estimates.

To conclude the proof, it remains to establish the claims regarding the limiting case. By standard sequential weak* compactness results in the spaces of Radon measures, together with the boundedness of $(Du_p)_{p>n/\alpha}$ in $L^{2\alpha}(\Omega; \mathbb{R}^{N \times n})$ (by virtue of Proposition 9), we obtain the existence of limit measures μ_∞ , M_∞ and ν_∞ such that $\mu_p \xrightarrow{*} \mu_\infty$, $M_p \xrightarrow{*} M_\infty$ and $\nu_p \xrightarrow{*} \nu_\infty$ in the corresponding spaces over $\overline{\Omega}$, along a subsequence as $p \rightarrow \infty$. We now also show the additional properties of the measure ν_∞ . By the weak* lower-semicontinuity of measures on open sets, we have

$$\nu_\infty(A_q) \leq \liminf_{p \rightarrow \infty} \nu_p(A_q) = 0,$$

for any q fixed. Hence, by letting $q \rightarrow \infty$, the upper continuity of the measure ν_∞ implies

$$\nu_\infty(\{g(u_\infty) < 1\}) = \lim_{q \rightarrow \infty} \nu_\infty(\{g(u_\infty) < 1 - 2\omega(q)\}) = 0.$$

This implies that $\nu_\infty(\{g(u_\infty) = 1\}) = \nu_\infty(\overline{\Omega})$. Further, since the function $h \equiv 1$ belongs to $C(\overline{\Omega})$, the subsequential weak* convergence $\nu_p \xrightarrow{*} \nu_\infty$ implies

$$\nu_\infty(\overline{\Omega}) = \int_{\overline{\Omega}} h \, d\nu_\infty = \lim_{p \rightarrow \infty} \int_{\overline{\Omega}} h \, d\nu_p = \lim_{p \rightarrow \infty} \nu_p(\overline{\Omega}) \geq \lim_{p \rightarrow \infty} \frac{1}{1 + \omega(p)} = 1.$$

Finally, since $u_\infty \equiv 0$ on $\partial\Omega$ and by (2.2) we get $g(0) = 0$, it follows that $g(u_\infty) \equiv 0$ on $\partial\Omega$. Thus, we infer that $\partial\Omega \subseteq \{g(u_\infty) < 1\}$, which yields that $\nu_\infty(\partial\Omega) = 0$. \square

Now we may establish the satisfaction of the PDE system (1.4) for the quadruple $(u_\infty, \Lambda_\infty, M_\infty, \nu_\infty)$ under only assumptions (1.2) and (1.3).

Lemma 11. *Let $M_\infty \in \mathcal{M}(\overline{\Omega}; \mathbb{R}^{N \times n})$ and $\nu_\infty \in \mathcal{M}(\overline{\Omega})$ be the Radon measures obtained in Lemma 10. Then, the pair $(u_\infty, \Lambda_\infty)$ satisfies the divergence PDE system (1.4), weakly in $(C_0^1(\overline{\Omega}; \mathbb{R}^N))^*$ (namely (1.11) holds true for any $\phi \in C_0^1(\overline{\Omega}; \mathbb{R}^N)$).*

Proof of Lemma 11. Fix $\phi \in C_0^1(\overline{\Omega}; \mathbb{R}^N)$ and $p > n/\alpha + 2$. By (1.10) and (1.16), we may rewrite the divergence PDE system (1.9) as

$$\begin{cases} \operatorname{div}(Df(Du_p)\mu_p) + \Lambda_p \partial g(u_p)\nu_p = 0, & \text{in } \Omega, \\ u_p = 0, & \text{on } \partial\Omega. \end{cases}$$

By the measure identity

$$M_p = \partial f(Du_p)\mu_p,$$

The weak formulation of the PDE means that for any $\phi \in C_0^1(\overline{\Omega}; \mathbb{R}^N)$, we have

$$\int_{\Omega} D\phi : dM_p = \Lambda_p \int_{\Omega} \partial g(u_p) \cdot \phi \, d\nu_p.$$

By Proposition 9, we have that $\Lambda_p \rightarrow \Lambda_\infty$ and also $u_p \rightarrow u_\infty$ uniformly on $\overline{\Omega}$ as $p \rightarrow \infty$ along a subsequence. By (1.3), we also have that $\partial g(u_p) \rightarrow \partial g(u_\infty)$ uniformly on $\overline{\Omega}$ as $p \rightarrow \infty$, along the same subsequence. The conclusion follows directly by the application of Lemma 10 and the strong-weak* continuity of the duality pairing $C(\overline{\Omega}) \times \mathcal{M}(\overline{\Omega}) \rightarrow \mathbb{R}$. \square

5. Regularisations up to the boundary

In this section we introduce the appropriate mollifications that will be utilised in the next section to show the satisfaction of Eq. (1.14). This regularisation scheme utilises results on the geometry of (strongly)

Lipschitz domain from Hofmann–Mitrea–Taylor [24], and is closely related to the regularisation schemes used in Ern–Guermond [18].

To begin with, let $n \in L^\infty(\partial\Omega, \mathcal{H}^{n-1}; \mathbb{R}^n)$ be the outer unit normal vector field on $\partial\Omega$. Then, (see Hofmann–Mitrea–Taylor [24, Sec. 2, 4] for the proofs of the claims in the paragraph) there exists a vector field $\xi \in C_c^\infty(\mathbb{R}^n; \mathbb{R}^n)$ that is globally transversal to n on $\partial\Omega$, namely exists $\delta_0 > 0$ such that

$$\xi \cdot n \geq \delta_0, \quad \mathcal{H}^{n-1}\text{-a.e. on } \partial\Omega.$$

Further, ξ can be chosen to have length $|\xi| \equiv 1$ in an open collar $\{\text{dist}(\cdot, \partial\Omega) < r_0\}$ around $\partial\Omega$ for some $r_0 > 0$ and to vanish on $\{\text{dist}(\cdot, \partial\Omega) > 2r_0\}$. If $\partial\Omega$ is a compact C^∞ manifold, then one can choose $\xi := n$ and the transversality condition is satisfied for $\delta_0 = 1$. Further, there exists $\ell, \varepsilon_0 > 0$ such that, for all $\varepsilon \in (0, \varepsilon_0)$ we have

$$\text{dist}(x + \varepsilon\ell\xi(x), \partial\Omega) \geq 2\varepsilon, \quad \text{for all } x \in \partial\Omega.$$

Using the above observations from [24], we may now define our mollifiers. Fix $\varepsilon \in (0, \varepsilon_0)$ and some $\varrho \in C_c^\infty(\mathbb{B}_1(0))$ satisfying $\varrho \geq 0$ and $\|\varrho\|_{L^1(\mathbb{R}^n)} = 1$. For any $v \in L^\infty(\Omega; \mathbb{R}^N)$, extended by zero on $\mathbb{R}^n \setminus \Omega$, we define $K^\varepsilon v : \mathbb{R}^n \rightarrow \mathbb{R}^N$ by setting

$$(K^\varepsilon v)(x) := \int_{\mathbb{R}^n} v(x + \varepsilon\ell\xi(x) - \varepsilon y) \varrho(y) dy.$$

What this regularisation does is to “compress” v to a map which is compactly supported inside Ω before mollifying. However, for technical convenience it is *not* exactly equal to the standard mollifier of the “compressed” function $v(\cdot + \varepsilon\ell\xi(\cdot))$, which instead equals the convolution

$$\frac{1}{\varepsilon^n} \varrho\left(\frac{\cdot}{\varepsilon}\right) * v(\cdot + \varepsilon\ell\xi(\cdot))$$

(this would require to put “ $\xi(x - \varepsilon y)$ ” instead of “ $\xi(x)$ ” in the formula defining K^ε). The advantage of this slight variance, as we will see right next, is a simpler formula for the derivatives.

The next result lists the main properties of this mollification scheme.

Proposition 12. *The family of regularisation operators $(K^\varepsilon)_{0 < \varepsilon < \varepsilon_0}$ satisfy the next properties:*

- (1) *For any $v \in L^\infty(\Omega; \mathbb{R}^N)$, we have $K^\varepsilon v \in C_c^\infty(\Omega; \mathbb{R}^N)$ and also $K^\varepsilon v \rightarrow v$ as $\varepsilon \rightarrow 0$ a.e. on Ω and in $L^q(\Omega; \mathbb{R}^N)$, for any $q \in [1, \infty)$.*
- (2) *For any $v \in L^\infty(\Omega; \mathbb{R}^N)$ and any convex function $\Phi : \mathbb{R}^N \rightarrow \mathbb{R}$ satisfying $0 \in \text{argmin}\{\Phi : \mathbb{R}^N\}$ (namely such that $\Phi \geq \Phi(0)$ on \mathbb{R}^N), we have*

$$\Phi(K^\varepsilon v(x)) \leq \text{ess sup}_{\Omega \cap \mathbb{B}_\varepsilon(x + \varepsilon\ell\xi(x))} \Phi(v),$$

for any $x \in \Omega$. In particular, $\Phi(K^\varepsilon v) \leq \|\Phi(v)\|_{L^\infty(\Omega)}$ on Ω .

- (3) *For any $v \in W_0^{1,\infty}(\Omega; \mathbb{R}^N)$, we have*

$$\begin{cases} D(K^\varepsilon v) = K^\varepsilon(Dv)[I + \varepsilon\ell D\xi]^\top, \\ |D(K^\varepsilon v) - K^\varepsilon(Dv)| \leq \varepsilon\ell \|D\xi\|_{L^\infty(\mathbb{R}^n)} \|Dv\|_{L^\infty(\Omega)}, \end{cases}$$

on Ω . Also, as $\varepsilon \rightarrow 0$ we have $K^\varepsilon v \rightarrow v$ in $W_0^{1,q}(\Omega; \mathbb{R}^N)$ for all $q \in [1, \infty)$ and in $C^\gamma(\overline{\Omega}; \mathbb{R}^N)$ for all $\gamma \in (0, 1)$. Further, $K^\varepsilon v \xrightarrow{*} v$ in $W_0^{1,\infty}(\Omega; \mathbb{R}^N)$.

- (4) *For any $v \in W_0^{1,\infty}(\Omega; \mathbb{R}^N)$ and any convex function $\Phi : \mathbb{R}^{N \times n} \rightarrow \mathbb{R}$ satisfying $0 \in \text{argmin}\{\Phi : \mathbb{R}^{N \times n}\}$, there exists $C > 0$ such that*

$$\Phi(D(K^\varepsilon v)(x)) \leq \text{ess sup}_{\Omega \cap \mathbb{B}_\varepsilon(x + \varepsilon\ell\xi(x))} \Phi(Dv) + \varepsilon C^*,$$

for any $x \in \Omega$, where the constant C^* depends only on Ω , ℓ , $D\xi$, $D\Phi$ and $\|Dv\|_{L^\infty(\Omega)}$. In particular,

$$\Phi(D(K^\varepsilon v)) \leq \|\Phi(Dv)\|_{L^\infty(\Omega)} + \varepsilon C^*,$$

everywhere on Ω .

Proof of Proposition 12. (1) A change of variables yields the identity

$$(K^\varepsilon v)(x) = \int_{\mathbb{B}_\varepsilon(x+\varepsilon\ell\xi(x))} \frac{1}{\varepsilon^n} \varrho\left(\frac{x+\varepsilon\ell\xi(x)-z}{\varepsilon}\right) v(z) \, dz$$

which, combined with the fact that $\text{dist}(x+\varepsilon\ell\xi(x), \partial\Omega) \geq 2\varepsilon$ when $x \in \partial\Omega$, imply that $K^\varepsilon v \equiv 0$ on an open neighbourhood of $\mathbb{R}^n \setminus \Omega$ because $v \equiv 0$ on $\mathbb{R}^n \setminus \Omega$ and also $\mathbb{B}_\varepsilon(x+\varepsilon\ell\xi(x)) \subseteq \mathbb{R}^n \setminus \overline{\Omega}$ when $x \in \partial\Omega$ (and also for x in open neighbourhood of $\partial\Omega$). Further, since $\text{supp}(\varrho) \subseteq \mathbb{B}_1(0)$, the integral above is in fact equal to the same integral taken over \mathbb{R}^n , hence we easily deduce by recursive differentiation that $K^\varepsilon v \in C^\infty(\mathbb{R}^n; \mathbb{R}^N)$.

(2) Since $\varrho\mathcal{L}^n$ is a probability measure on \mathbb{R}^n , by Jensen's inequality, we estimate

$$\begin{aligned} \Phi(K^\varepsilon v(x)) &= \Phi\left(\int_{\mathbb{R}^n} v(x+\varepsilon\ell\xi(x)-\varepsilon y) \varrho(y) \, dy\right) \\ &\leq \int_{\mathbb{R}^n} \Phi\left(v(x+\varepsilon\ell\xi(x)-\varepsilon y)\right) \varrho(y) \, dy \\ &\leq \text{ess sup}_{y \in \mathbb{B}_1(0)} \Phi\left(v(x+\varepsilon\ell\xi(x)-\varepsilon y)\right) \\ &= \text{ess sup}_{\mathbb{B}_\varepsilon(x+\varepsilon\ell\xi(x))} \Phi(v), \end{aligned}$$

for any $x \in \Omega$. By using that $v \equiv 0$ on $\mathbb{R}^n \setminus \Omega$ and our assumption on Φ , we further have

$$\begin{aligned} \Phi(K^\varepsilon v(x)) &\leq \max\left\{\text{ess sup}_{\Omega \cap \mathbb{B}_\varepsilon(x+\varepsilon\ell\xi(x))} \Phi(v), \text{ess sup}_{\mathbb{B}_\varepsilon(x+\varepsilon\ell\xi(x)) \setminus \Omega} \Phi(v)\right\} \\ &\leq \max\left\{\text{ess sup}_{\Omega \cap \mathbb{B}_\varepsilon(x+\varepsilon\ell\xi(x))} \Phi(v), \Phi(0)\right\} \\ &\leq \text{ess sup}_{\Omega \cap \mathbb{B}_\varepsilon(x+\varepsilon\ell\xi(x))} \Phi(v), \end{aligned}$$

for any $x \in \Omega$.

(3) We readily compute

$$D(K^\varepsilon v)(x) = \int_{\mathbb{R}^n} Dv(x+\varepsilon\ell\xi(x)-\varepsilon y) [I + \varepsilon\ell D\xi(x)]^\top \varrho(y) \, dy$$

which yields the claimed identity. The desired inequality is a simple consequence of the above identity together with the estimate of Part (2). The asserted modes of convergence follow by standard arguments on mollifiers (see e.g. [19]).

(4) Since $\Phi : \mathbb{R}^{N \times n} \rightarrow \mathbb{R}$ is convex, it is in $W_{\text{loc}}^{1,\infty}(\mathbb{R}^{N \times n})$. Fix $R > 0$ such that

$$R > \|D\xi\|_{L^\infty(\mathbb{R}^n)} \|Dv\|_{L^\infty(\Omega)}.$$

Then, by Parts (2)–(3) we estimate

$$\begin{aligned} \Phi(D(K^\varepsilon v)(x)) &= \Phi\left(K^\varepsilon(Dv)(x) + \varepsilon\ell K^\varepsilon(Dv)D\xi(x)^\top\right) \\ &\leq \Phi(K^\varepsilon(Dv)(x)) + \|D\Phi\|_{L^\infty(\mathbb{B}_R(0))} \|\varepsilon\ell K^\varepsilon(Dv)D\xi^\top\|_{L^\infty(\Omega)} \\ &\leq \Phi(K^\varepsilon(Dv)(x)) + \varepsilon\ell \|D\Phi\|_{L^\infty(\mathbb{B}_R(0))} \|Dv\|_{L^\infty(\Omega)} \|D\xi\|_{L^\infty(\mathbb{R}^n)} \\ &\leq \text{ess sup}_{\Omega \cap \mathbb{B}_\varepsilon(x+\varepsilon\ell\xi(x))} \Phi(Dv) + C^*\varepsilon, \end{aligned}$$

for any $x \in \Omega$, where we have set

$$C^* := \ell \|D\Phi\|_{L^\infty(\mathbb{B}_R(0))} \|D\xi\|_{L^\infty(\mathbb{R}^n)} \|Dv\|_{L^\infty(\Omega)}.$$

The proof of the proposition is now complete. \square

6. The divergence PDE system in L^∞ , part II

In this section we establish the satisfaction of (1.14) for the minimising quadruple $(u_\infty, \Lambda_\infty, \mu_\infty, \nu_\infty)$, under the hypotheses (1.2), (1.3) and also (1.12). We begin with some notation.

Remark 13. Under (1.12), since f is assumed quadratic, (1.2) is in fact satisfied for $C_1 = C_2$ (see the observations following Example 3). Hence, by introducing the positive constant

$$\kappa := \frac{C_8}{C_1} \left(= \frac{C_7}{C_2} \right),$$

the conclusion of Lemma 8 strengthens to the equality

$$L_p = \kappa^{1/p} \Lambda_p.$$

Next, we derive some differential identities and energy inequalities, which will be utilised to obtain the necessary estimates.

Lemma 14. For any $p \in (n/\alpha + 2, \infty)$, consider the quadruple $(u_p, \Lambda_p, \mu_p, \nu_p)$ as in Section 4. Then, for any $v \in W_0^{1,\infty}(\Omega; \mathbb{R}^N)$, we have the differential identity

$$\int_{\Omega} f(Dv - Du_p) \, d\mu_p = \int_{\Omega} f(Dv) \, d\mu_p - \int_{\Omega} f(Du_p) \, d\mu_p + \Lambda_p \int_{\Omega} \partial g(u_p) \cdot (u_p - v) \, d\nu_p.$$

Note that in view of (1.10) and (1.16), we have that $\nu_p(\partial\Omega) = \mu_p(\partial\Omega) = 0$ for $p \in (n/\alpha + 2, \infty)$. Thus, all the integrals above are non-trivial only over Ω .

Proof of Lemma 14. Since $v - u_p \in W_0^{1,\alpha p}(\Omega; \mathbb{R}^N)$, by using (1.12) we have

$$\int_{\Omega} f(Dv - Du_p) \, d\mu_p = \int_{\Omega} \mathbf{A} : (Dv - Du_p) \otimes (Dv - Du_p) \, d\mu_p,$$

which, by virtue of Lemma 4(2), can be expanded as

$$\begin{aligned} \int_{\Omega} f(Dv - Du_p) \, d\mu_p &= \int_{\Omega} \mathbf{A} : Dv \otimes Dv \, d\mu_p + \int_{\Omega} \mathbf{A} : Du_p \otimes Du_p \, d\mu_p \\ &\quad + \int_{\Omega} \mathbf{A} : (Du_p \otimes (-Dv) + (-Dv) \otimes Du_p) \, d\mu_p \\ &= \int_{\Omega} f(Dv) \, d\mu_p - \int_{\Omega} f(Du_p) \, d\mu_p \\ &\quad + \int_{\Omega} \mathbf{A} : (Du_p \otimes (Du_p - Dv) + (Du_p - Dv) \otimes Du_p) \, d\mu_p \\ &= \int_{\Omega} f(Dv) \, d\mu_p - \int_{\Omega} f(Du_p) \, d\mu_p + \int_{\Omega} \partial f(Du_p) : D(u_p - v) \, d\mu_p. \end{aligned}$$

By arguing as in the proof of Lemma 11 and testing against $\phi := u_p - v$ in the weak formulation, we readily deduce the claimed identity. \square

Lemma 15. *In the setting of Lemma 14, for any $p \in (n/\alpha + 2, \infty)$ we have*

$$\begin{cases} \int_{\overline{\Omega}} f(Du_p) d\mu_p = \kappa A_p, \\ \int_{\overline{\Omega}} |Du_p|^2 d\mu_p \leq \frac{\kappa}{C_4} (A_p + C_3 \kappa^{-1/p}). \end{cases}$$

Proof of Lemma 15. From (1.16), Lemma 8 and Remark 13 (noting also that $\mathcal{L}^n(\partial\Omega) = 0$), we have

$$\int_{\overline{\Omega}} f(Du_p) d\mu_p = \int_{\Omega} f(Du_p) \frac{f(Du_p)^{p-1}}{A_p^{p-1}} d\mathcal{L}^n = \frac{1}{A_p^{p-1}} L_p^p = \kappa A_p.$$

Further, by (1.2) and (1.12) (noting also that $\alpha = 2$ in (1.2) under (1.12)), we have

$$\kappa A_p = \int_{\overline{\Omega}} f(Du_p) d\mu_p \geq C_4 \int_{\overline{\Omega}} |Du_p|^2 d\mu_p - C_3 \mu_p(\overline{\Omega}).$$

The claimed inequality is now a consequence of the above together with the bound $\mu_p(\overline{\Omega}) \leq \kappa^{-1-1/p}$, which follows from Lemma 10 and Remark 13. \square

The following result is an immediate consequence of assumption (1.12), Lemmas 4, 14, 15 and Proposition 9.

Corollary 16. *In the setting of Lemma 15, for any $p \in (n/\alpha + 2, \infty)$ and any map $v \in W^{1,\infty}(\Omega; \mathbb{R}^N)$, we have the estimate*

$$c_0 \int_{\overline{\Omega}} |Dv - Du_p|^2 d\mu_p \leq \int_{\overline{\Omega}} f(Dv) d\mu_p - \kappa A_p + C_0 \|u_p - v\|_{L^\infty(\Omega)},$$

where

$$c_0 := \min \sigma(\mathbb{S}\mathbf{A}), \quad C_0 := \sup_{n/\alpha+2 < p < \infty} \{A_p \|\partial g(u_p)\|_{L^\infty(\Omega)}\}.$$

Now we expound on the methodology utilised in the remainder of this section, in order to complete the proof of Theorem 2.

Remark 17 (The Method). The estimate of Corollary 16 is the main energy estimate we will need to pass to the limit as $p \rightarrow \infty$ along a sequence in the PDE system (1.9) to obtain (1.14). The main difficulty in trying that is that both Du_p and μ_p converge in a weak (weak*) sense only, and in fact in different spaces. Therefore, a priori it is not at all clear that

$$Du_p \mu_p \xrightarrow{*} Du_\infty \mu_\infty$$

and the product $Du_\infty \mu_\infty$ may not be a well defined measure, as in general Du_∞ is in $L^\infty(\Omega; \mathbb{R}^{N \times n})$ and only Lebesgue measurable, hence it may not be defined on lower-dimensional subsets of $\overline{\Omega}$ on which the Borel measure μ_∞ may concentrate (e.g. on hypersurfaces in Ω or on the boundary $\partial\Omega$).

To circumvent these problems, we argue as follows. The idea is to show first that

$$Du_p \mu_p \xrightarrow{*} V_\infty \mu_\infty, \quad \text{in } \mathcal{M}(\overline{\Omega}; \mathbb{R}^{N \times n}),$$

as $p \rightarrow \infty$, for some Borel measurable $V_\infty : \overline{\Omega} \rightarrow \mathbb{R}^{N \times n}$ in $L^2(\overline{\Omega}, \mu_\infty; \mathbb{R}^{N \times n})$. (In particular, the measure $V_\infty \mu_\infty$ is then well defined.) Then, using weak* lower-semicontinuity we let $p \rightarrow \infty$ in Corollary 16 to obtain for any map $v \in C_0^1(\overline{\Omega}; \mathbb{R}^N)$ (not just in $W_0^{1,\infty}(\Omega; \mathbb{R}^N)$) that

$$c_0 \int_{\overline{\Omega}} |Dv - V_\infty|^2 d\mu_\infty \leq \int_{\overline{\Omega}} f(Dv) d\mu_\infty - \kappa A_\infty + C_0 \|u_\infty - v\|_{L^\infty(\Omega)}.$$

Next, one would like to set “ $v := u_\infty$ ” to obtain “ $Du_\infty = V_\infty$ ”. However, this is not directly possible, at the very least because directly $Du_\infty \mu_\infty$ is not well defined, and also the limiting process of the previous step prevents us for setting $v = u_\infty$ due to the lack of regularity. To this end, we utilise the regularisation operators $(K^\varepsilon)_{0 < \varepsilon < \varepsilon_0}$ introduced in Section 5 to set $v := K^\varepsilon u_\infty$ and deduce as $\varepsilon \rightarrow 0$ that a *special Borel measurable representative* Du_∞^* *does exist*, which is a version of the gradient of u_∞ in the equivalence classes of a.e.-equality for both $Du_\infty \in L^\infty(\Omega; \mathbb{R}^{N \times n})$ and for $V_\infty \in L^2(\overline{\Omega}, \mu_\infty; \mathbb{R}^{N \times n})$. Hence, the PDE system (1.14) is satisfied for this representative of Du_∞ which in particular makes $\partial f(Du_\infty^*) \mu_\infty$ a well-defined measure (recall that ∂f is a just linear mapping under (1.12)).

Now we deploy the method set out in Remark 17.

Lemma 18. *There exists a mapping $V_\infty \in L^2(\overline{\Omega}, \mu_\infty; \mathbb{R}^{N \times n})$ such that, along a subsequence $(p_j)_1^\infty$ we have*

$$Du_p \mu_p \xrightarrow{*} V_\infty \mu_\infty, \quad \text{in } \mathcal{M}(\overline{\Omega}; \mathbb{R}^{N \times n}),$$

as $p \rightarrow \infty$. Further, for any non-negative continuous function $\Phi \in C(\overline{\Omega} \times \mathbb{R}^{N \times n})$ such that $X \mapsto \Phi(x, X)$ is convex and of quadratic growth at infinity, we have

$$\int_{\overline{\Omega}} \Phi(\cdot, V_\infty) d\mu_\infty \leq \liminf_{p \rightarrow \infty} \int_{\overline{\Omega}} \Phi(\cdot, Du_p) d\mu_p.$$

Proof of Lemma 18. By Lemma 15 and Proposition 9, we have that

$$\sup_{p \in (n/\alpha + 2, \infty)} \int_{\overline{\Omega}} |Du_p|^2 d\mu_p < \infty.$$

In view of this estimate, the conclusion follows by the theory of measure-function pairs of Hutchinson in [25, Sec. 4, Def. 4.1.1, 4.1.2, 4.2.1 and Th. 4.4.2]. \square

In virtue of the above considerations, we obtain the following rather immediate consequence.

Lemma 19. *In the setting of Lemma 18, for any $p \in (n/\alpha + 2, \infty)$ and any fixed $v \in C_0^1(\overline{\Omega}; \mathbb{R}^N)$, we have the estimate*

$$c_0 \int_{\overline{\Omega}} |Dv - V_\infty|^2 d\mu_\infty \leq \int_{\overline{\Omega}} f(Dv) d\mu_\infty - \kappa A_\infty + C_0 \|u_\infty - v\|_{L^\infty(\Omega)}.$$

Proof of Lemma 19. Since by assumption $Dv \in C(\overline{\Omega}; \mathbb{R}^{N \times n})$, we may apply Lemma 18 to $\Phi(x, X) := |Dv(x) - X|^2$, which satisfies the required convexity and continuity requirements. Then, we use the estimate of Corollary 16, together with the facts that $(u_p, A_p) \rightarrow (u_\infty, A_\infty)$ in $C(\overline{\Omega}; \mathbb{R}^N) \times \mathbb{R}$ as $p \rightarrow \infty$ along a sequence, and that $f(Dv) \in C(\overline{\Omega})$, which is the predual space of $\mathcal{M}(\overline{\Omega}) = (C(\overline{\Omega}))^*$. \square

The following result is the most remarkable consequence of the energy estimate of Lemma 19.

Lemma 20. (i) *For any sequence $(v_j)_1^\infty \subseteq C_0^1(\overline{\Omega}; \mathbb{R}^N)$ which satisfies the conditions*

$$\begin{cases} \lim_{j \rightarrow \infty} \|v_j - u_\infty\|_{L^\infty(\Omega)} = 0, \\ \limsup_{j \rightarrow \infty} \|f(Dv_j)\|_{L^\infty(\Omega)} \leq A_\infty, \end{cases}$$

we have that

$$\lim_{j \rightarrow \infty} \int_{\overline{\Omega}} |V_\infty - Dv_j|^2 d\mu_\infty = 0.$$

(ii) If additionally to the above, the sequence $(v_j)_1^\infty$ satisfies

$$\lim_{j \rightarrow \infty} \|Dv_j - Du_\infty\|_{L^1(\Omega)} = 0,$$

then we obtain the additional conclusion

$$\lim_{j \rightarrow \infty} \int_{\Omega} |Du_\infty - Dv_j|^q d\mathcal{L}^n = 0,$$

for any $q \in [1, \infty)$. Hence, for any such sequence $(v_j)_1^\infty$, we have

$$\begin{cases} Dv_j \longrightarrow V_\infty, & \text{in } L^2(\overline{\Omega}, \mu_\infty; \mathbb{R}^{N \times n}), \\ Dv_j \longrightarrow Du_\infty, & \text{in } L^q(\Omega, \mathcal{L}^n; \mathbb{R}^{N \times n}), \end{cases}$$

as $j \rightarrow \infty$, along perhaps a subsequence.

We note that, since $L^q(\Omega, \mathbb{R}^{N \times n})$ is a uniformly convex space when $q \in (1, \infty)$, the assumption of $Dv_j \longrightarrow Du_\infty$ in $L^1(\Omega; \mathbb{R}^{N \times n})$ can actually be replaced by the weaker condition $\|Dv_j\|_{L^q(\Omega)} \longrightarrow \|Du_\infty\|_{L^q(\Omega)}$ for some $q \in (1, \infty)$.

Proof of Lemma 20. (i) It suffices to apply the assumed modes of convergence to the estimate of Lemma 19, and recall that $\mu_\infty(\overline{\Omega}) \leq \kappa^{1-1/p}$, as a result of Lemma 10 and Remark 13.

(ii) By Lemma 4 and (1.5) (shown in Proposition 9), the hypothesis

$$\|f(Dv_j)\|_{L^\infty(\Omega)} \leq \|f(Du_\infty)\|_{L^\infty(\Omega)} + o(1)_{j \rightarrow \infty}$$

implies that $(Dv_j)_1^\infty$ is bounded in $L^q(\Omega, \mathbb{R}^{N \times n})$, for all $q \in [1, \infty]$. Hence, by passing perhaps to a subsequence, we have that $Dv_j \longrightarrow Du_\infty$ in $L^q(\Omega, \mathbb{R}^{N \times n})$ for all $q \in [1, \infty)$ and also $Dv_j \xrightarrow{*} Du_\infty$ in $L^\infty(\Omega, \mathbb{R}^{N \times n})$. Since $Dv_j \longrightarrow Du_\infty$ in $L^1(\Omega; \mathbb{R}^{N \times n})$, by the Vitali convergence theorem and the L^∞ gradient bound, it follows that in fact the convergence is strong in $L^q(\Omega, \mathbb{R}^{N \times n})$ for all $q \in [1, \infty)$. The result ensues. \square

In the next result we use Lemma 20 identify the limit V_∞ as a version of Du_∞ after perhaps modification on a Lebesgue nullset (recall also that $\mathcal{L}^n(\partial\Omega) = 0$).

Corollary 21. *There exists a Borel measurable mapping $Du_\infty^* : \overline{\Omega} \longrightarrow \mathbb{R}^{N \times n}$, which is a version of both $Du_\infty \in L^\infty(\Omega; \mathbb{R}^{N \times n})$ and of $V_\infty \in L^2(\overline{\Omega}, \mu_\infty; \mathbb{R}^{N \times n})$, namely*

$$Du_\infty^* = \begin{cases} Du_\infty, & \mathcal{L}^n\text{-a.e. on } \Omega, \\ V_\infty, & \mu_\infty\text{-a.e. on } \overline{\Omega}. \end{cases}$$

Further, Du_∞^* can be represented as

$$Du_\infty^*(x) = \begin{cases} \lim_{j \rightarrow \infty} D(K^{\varepsilon_j} u_\infty)(x), & \text{if the limit exists,} \\ 0, & \text{otherwise.} \end{cases}$$

along an infinitesimal sequence $(\varepsilon_j)_1^\infty \subseteq (0, 1)$, where $(K^\varepsilon)_{0 < \varepsilon < \varepsilon_0}$ are the regularisation operators of Section 5.

Remark 22. It follows that, if one defines the Borel set

$$G := \left\{ x \in \overline{\Omega} : \nexists \lim_{j \rightarrow \infty} D(K^{\varepsilon_j} u_\infty)(x) \right\},$$

then G is both a \mathcal{L}^n -nullset and a μ_∞ -nullset: $\mathcal{L}^n(G) = \mu_\infty(G) = 0$.

Proof of Corollary 21. Let $(K^\varepsilon)_{0 < \varepsilon < \varepsilon_0}$ be the regularisation operators of Section 5. By Proposition 12, we have $K^\varepsilon u_\infty \in C_c^\infty(\Omega; \mathbb{R}^N)$, therefore the choice $v := K^\varepsilon u_\infty$ in the estimate of Lemma 19 is admissible. Again by Proposition 12 and (1.5) (proved in Proposition 9), we have that

$$\begin{cases} \lim_{\varepsilon \rightarrow 0} \|K^\varepsilon u_\infty - u_\infty\|_{L^\infty(\Omega)} = 0, \\ \limsup_{\varepsilon \rightarrow 0} \|f(D(K^\varepsilon u_\infty))\|_{L^\infty(\Omega)} \leq A_\infty, \\ \lim_{\varepsilon \rightarrow 0} \|K^\varepsilon u_\infty - u_\infty\|_{W_0^{1,1}(\Omega)} = 0. \end{cases}$$

We may now apply Lemma 20 to obtain that, for any infinitesimal sequence $(\varepsilon_j)_1^\infty$ there is a subsequence, symbolised again by $(\varepsilon_j)_1^\infty$, such that for any $q \in [1, \infty)$,

$$\begin{cases} D(K^{\varepsilon_j} u_\infty) \longrightarrow V_\infty, & \text{in } L^2(\overline{\Omega}, \mu_\infty; \mathbb{R}^{N \times n}), \\ D(K^{\varepsilon_j} u_\infty) \longrightarrow Du_\infty, & \text{in } L^q(\Omega, \mathcal{L}^n; \mathbb{R}^{N \times n}), \end{cases}$$

as $j \rightarrow \infty$. By passing perhaps to a further subsequence, we infer that

$$\begin{cases} D(K^{\varepsilon_j} u_\infty) \longrightarrow V_\infty, & \mu_\infty\text{-a.e. on } \overline{\Omega}, \\ D(K^{\varepsilon_j} u_\infty) \longrightarrow Du_\infty, & \mathcal{L}^n\text{-a.e. on } \Omega, \end{cases}$$

as $j \rightarrow \infty$. The conclusion follows by defining the map Du_∞^* as in the statement. The result therefore ensues. \square

We may now establish the satisfaction of the necessary conditions.

Lemma 23. *The quadruple $(u_\infty, A_\infty, \mu_\infty, \nu_\infty)$ satisfies the system of PDEs (1.14), weakly in the dual space $(C_0^1(\overline{\Omega}; \mathbb{R}^N))^*$.*

Proof of Lemma 23. By the proof of Lemma 11, for any fixed $\phi \in C_0^1(\overline{\Omega}; \mathbb{R}^N)$ we have

$$\int_\Omega \partial f(Du_p) : D\phi \, d\mu_p = A_p \int_\Omega \partial g(u_p) \cdot \phi \, d\nu_p.$$

By Proposition 9, we have $A_p \rightarrow A_\infty$ and also $u_p \rightarrow u_\infty$ in $C(\overline{\Omega}; \mathbb{R}^N)$ as $p \rightarrow \infty$ along a sequence. Further, $\partial g(u_p) \rightarrow \partial g(u_\infty)$ in $C(\overline{\Omega}; \mathbb{R}^N)$ as $p \rightarrow \infty$. By Lemma 18 and Corollary 21, we have that

$$Du_p \mu_p \xrightarrow{*} Du_\infty^* \mu_\infty, \quad \text{in } \mathcal{M}(\overline{\Omega}; \mathbb{R}^{N \times n}).$$

Further, by virtue of Lemma 4, ∂f is a linear mapping on $\mathbb{R}^{N \times n}$, therefore

$$\partial f(Du_p) \mu_p \xrightarrow{*} \partial f(Du_\infty^*) \mu_\infty, \quad \text{in } \mathcal{M}(\overline{\Omega}; \mathbb{R}^{N \times n}).$$

The conclusion follows directly by the application of Lemma 10 and the strong-weak* continuity of the duality pairing $C(\overline{\Omega}) \times \mathcal{M}(\overline{\Omega}) \rightarrow \mathbb{R}$. \square

We conclude with establishing that the set whereon the measure μ_∞ concentrates is the set whereon $f(Du_\infty^*)$ is maximised over $\overline{\Omega}$.

Lemma 24. *The next equalities hold true:*

$$\begin{cases} A_\infty = \frac{1}{\kappa} \int_{\overline{\Omega}} f(Du_\infty^*) \, d\mu_\infty, \\ \mu_\infty\text{-ess sup}_{\overline{\Omega}} f(Du_\infty^*) = \sup_{\overline{\Omega}} f(Du_\infty^*) = A_\infty. \end{cases}$$

Further, we have

$$\mu_\infty(\overline{\Omega}) = \kappa, \quad \mu_\infty(\{f(Du_\infty^*) < \Lambda_\infty\}) = 0.$$

Finally, the boundary $\partial\Omega$ is a nullset with respect to the Radon measure $Du_\infty^* \mu_\infty$:

$$\|Du_\infty^* \mu_\infty\|(\partial\Omega) = 0.$$

Proof of Lemma 24. By Lemma 19 for $v := K^\varepsilon u_\infty$, we have

$$0 \leq \int_{\overline{\Omega}} f(D(K^\varepsilon u_\infty)) \, d\mu_\infty - \kappa \Lambda_\infty + C_0 \|u_\infty - K^\varepsilon u_\infty\|_{L^\infty(\Omega)}.$$

By Corollary 21, we have that $D(K^\varepsilon u_\infty) \rightarrow Du_\infty^*$ in $L^2(\overline{\Omega}, \mu_\infty; \mathbb{R}^{N \times n})$ as $\varepsilon_j \rightarrow 0$, because $V_\infty = Du_\infty^*$ μ_∞ -a.e. on $\overline{\Omega}$. Further, by Lemma 4, by Proposition 12 and by the dominated convergence theorem, the above estimate yields as $\varepsilon_j \rightarrow 0$ that

$$\Lambda_\infty \leq \frac{1}{\kappa} \int_{\overline{\Omega}} f(Du_\infty^*) \, d\mu_\infty.$$

On the other hand, recall that by Lemma 10 and Remark 13 we have $\mu_\infty(\overline{\Omega}) \leq \kappa$. Hence, by Proposition 12, Lemma 20 and Hölder's inequality, we obtain

$$\begin{aligned} \Lambda_\infty + o(1)_{j \rightarrow \infty} &\geq \sup_{\overline{\Omega}} f(D(K^{\varepsilon_j} u_\infty)) \\ &\geq \mu_\infty\text{-ess sup}_{\overline{\Omega}} f(D(K^{\varepsilon_j} u_\infty)) \\ &\geq \left(\frac{1}{\kappa} \mu_\infty(\overline{\Omega}) \right) \mu_\infty\text{-ess sup}_{\overline{\Omega}} f(D(K^{\varepsilon_j} u_\infty)) \\ &\geq \frac{1}{\kappa} \int_{\overline{\Omega}} f(D(K^{\varepsilon_j} u_\infty)) \, d\mu_\infty. \end{aligned}$$

By letting $j \rightarrow \infty$, this yields

$$\Lambda_\infty \geq \frac{1}{\kappa} \int_{\overline{\Omega}} f(Du_\infty^*) \, d\mu_\infty.$$

The above estimates establish the claimed integral identity. Further, let $G \subseteq \overline{\Omega}$ be the Borel set of Remark 22. Then, by the definition of Du_∞^* as being equal to zero on G and the fact that $f \geq f(0) = 0$ as a result of (2.1), we have

$$\begin{aligned} \mu_\infty\text{-ess sup}_{\overline{\Omega}} f(Du_\infty^*) &= \sup_{\overline{\Omega} \setminus G} f(Du_\infty^*) \\ &= \max \left\{ \sup_{\overline{\Omega} \setminus G} f(Du_\infty^*), f(0) \right\} \\ &= \max \left\{ \sup_{\overline{\Omega} \setminus G} f(Du_\infty^*), \sup_G f(Du_\infty^*) \right\} \\ &= \sup_{\overline{\Omega}} f(Du_\infty^*). \end{aligned}$$

Arguing similarly for the Lebesgue measure, we obtain

$$\Lambda_\infty = \|f(Du_\infty^*)\|_{L^\infty(\Omega)} = \sup_{\overline{\Omega} \setminus G} f(Du_\infty^*) = \sup_{\overline{\Omega}} f(Du_\infty^*).$$

Therefore, the desired equalities have been established. Further, since $\mu_\infty(\overline{\Omega}) \leq \kappa$ and $f(Du_\infty^*) \leq \Lambda_\infty$ on $\overline{\Omega}$, we deduce also that in fact $f(Du_\infty^*)$ equals its supremum Λ_∞ over $\overline{\Omega}$ and also the measure of $\mu_\infty(\overline{\Omega})$ is full, namely $\mu_\infty(\overline{\Omega}) = \kappa$. Finally, by Lemma 19 for $v =: K^\varepsilon u_\infty$ and by using that $V_\infty = Du_\infty^*$ μ_∞ -a.e. on $\overline{\Omega}$ and that $\text{supp}(K^\varepsilon v) \subseteq \Omega$, we conclude

$$\begin{aligned} c_0 \int_{\partial\Omega} |Du_\infty^*|^2 d\mu_\infty &\leq c_0 \int_{\overline{\Omega}} |Du_\infty^* - D(K^\varepsilon u_\infty)|^2 d\mu_\infty \\ &\leq \int_{\overline{\Omega}} f(D(K^\varepsilon u_\infty)) d\mu_\infty - \kappa \Lambda_\infty + C_0 \|u_\infty - K^\varepsilon u_\infty\|_{L^\infty(\Omega)} \\ &\leq o(1)_{j \rightarrow \infty}. \end{aligned}$$

This implies that

$$\|Du_\infty^* \mu_\infty\|(\partial\Omega) \leq \sqrt{\mu_\infty(\partial\Omega)} \left(\int_{\partial\Omega} |Du_\infty^*|^2 d\mu_\infty \right)^{1/2} = 0.$$

The result ensues. \square

7. Computations for an explicit example

In this section we provide some explicit computations in the case of the ∞ -eigenvalue problem on the ball. Let $n, N \geq 1$ and choose $f := \frac{1}{2}|\cdot|^2$ and $g := \frac{1}{2}|\cdot|^2$ the corresponding Euclidean norms on $\mathbb{R}^{N \times n}$ and \mathbb{R}^N respectively. We also fix $R > 0$ and choose $\Omega := \mathbb{B}_R$, the ball of radius R centred at the origin of \mathbb{R}^n . Then, for any direction $e \in \mathbb{R}^N$ with $|e| = 1$, the directed cone function

$$C_\infty(x) := \left(1 - \frac{|x|}{R}\right)e$$

is a solution to

$$\|DC_\infty\|_{L^\infty(\mathbb{B}_R)} = \inf \left\{ \|Dv\|_{L^\infty(\mathbb{B}_R)} : v \in W_0^{1,\infty}(\mathbb{B}_R; \mathbb{R}^N), \|v\|_{L^\infty(\mathbb{B}_R)} = 1 \right\}.$$

Indeed, we have $C_\infty \in W_0^{1,\infty}(\mathbb{B}_R; \mathbb{R}^N)$ and $\|C_\infty\|_{L^\infty(\mathbb{B}_R)} = 1$, because $0 \leq |C_\infty| \leq 1$ and also $|C_\infty(0)| = 1$. Further, for any $x \in \mathbb{B}_R \setminus \{0\}$ we have $|DC_\infty(x)| = \frac{1}{R}$, which yields

$$\|DC_\infty\|_{L^\infty(\mathbb{B}_R)} = \frac{1}{R}.$$

This value in fact is the infimum over all maps in the admissible class. To see this, fix any $v \in W_0^{1,\infty}(\mathbb{B}_R; \mathbb{R}^N)$ with $\|v\|_{L^\infty(\mathbb{B}_R)} = 1$. By continuity, this means that $0 \leq |v| \leq 1$ and that exists $\bar{x} \in \mathbb{B}_R$ such that $|u(\bar{x})| = 1$. Let $(K^\varepsilon)_{0 < \varepsilon < \varepsilon_0}$ be the family of regularising operators introduced earlier in Section 5. Then, $K_\varepsilon v \in C_c^1(\mathbb{B}_R; \mathbb{R}^N)$ and by standard arguments on viscosity solutions (see e.g. [29, Section 3]) there exists $\bar{x}_\varepsilon \in \mathbb{B}_R$ close to \bar{x} such that $|K^\varepsilon v|$ attains its maximum at \bar{x}_ε and $|K^\varepsilon v(\bar{x}_\varepsilon)| \rightarrow 1$ as $\varepsilon \rightarrow 0$. Then, for any fixed $z \in \partial\mathbb{B}_R$ we have $K^\varepsilon v(z) = 0$ and hence

$$\begin{aligned} 1 + o(1)_{\varepsilon \rightarrow 0} &= |K^\varepsilon v(\bar{x}_\varepsilon) - K^\varepsilon v(z)| \\ &= \left| \int_0^1 D(K^\varepsilon v)(\lambda \bar{x}_\varepsilon + (1-\lambda)z) \cdot (\bar{x}_\varepsilon - z) d\lambda \right| \\ &\leq \|Dv\|_{L^\infty(\mathbb{B}_R)} |\bar{x}_\varepsilon - z|. \end{aligned}$$

By choosing $z := R \frac{\bar{x}_\varepsilon}{|\bar{x}_\varepsilon|}$ if $\bar{x}_\varepsilon \neq 0$ and any $z \in \partial\mathbb{B}_R$ if $\bar{x}_\varepsilon = 0$, we obtain by letting $\varepsilon \rightarrow 0$ that

$$\|Dv\|_{L^\infty(\mathbb{B}_R)} \geq \frac{1}{R}.$$

The above arguments show that the directed cone C_∞ is indeed a vectorial ∞ -eigenfunction.

We now consider the necessary PDEs that C_∞ solves. By invoking [Theorems 1–2](#) and by noting that $\Lambda_\infty = \|DC_\infty\|_{L^\infty(\mathbb{B}_R)} = 1/R$, we see that there exist measures $\mu_\infty, \nu_\infty \in \mathcal{M}(\bar{\mathbb{B}}_R)$ such that

$$-\operatorname{div}(DC_\infty\mu_\infty) = \frac{1}{R}C_\infty\nu_\infty \quad \text{in } \Omega.$$

Since $\nu_\infty(\bar{\mathbb{B}}_R) = 1$ and in this case $\{C_\infty = \sup_{\bar{\mathbb{B}}_R} C_\infty\} = \{0\}$, we deduce that

$$\nu_\infty = \delta_0.$$

Therefore, since $C_\infty\delta_0 = C_\infty(0)\delta_0$, the PDE system reduces to

$$-\operatorname{div}(DC_\infty\mu_\infty) = \frac{1}{R}e\delta_0 \quad \text{in } \Omega.$$

Further, since $DC_\infty = -\frac{1}{R}e \otimes \operatorname{sgn}$, where sgn is the sign function in \mathbb{R}^N , we may compute an explicit measure μ_∞ , which in fact is absolutely continuous on $\bar{\mathbb{B}}_R$. By using the fundamental solutions of the Laplacian Δ

$$\Phi(x) = -\frac{1}{2\pi} \ln |x| \quad \text{for } n = 2, \quad \Phi(x) = \frac{1}{n(n-2)\alpha(n)|x|^{n-2}} \quad \text{for } n \geq 3$$

(where $\alpha(n)$ symbolises the volume of the unit ball in \mathbb{R}^n), which in both cases give

$$D\Phi(x) = -\frac{1}{n\alpha(n)|x|^{n-1}} \operatorname{sgn}(x)$$

and that the system reduces to the single PDE

$$-\operatorname{div}(-\operatorname{sgn} \mu_\infty) = \delta_0 \quad \text{in } \Omega,$$

we obtain that the PDE is satisfied for the absolutely continuous measure

$$\mu_\infty = \frac{1}{n\alpha(n)|\cdot|^{n-1}} \mathcal{L}^n \llcorner_{\mathbb{B}_R}.$$

Remark 25. It is worth noting that, as shown in [\[10\]](#), due to the full rotational symmetry and the homogeneity of the vectorial p -eigenvalue problem, all vectorial p -eigenfunctions are essentially scalar. Even though this is not automatically true for the ∞ -eigenvalue problem, it does carry over to $p = \infty$ at least for those ∞ -eigenfunctions which are constructed as L^p -limits. Nevertheless, this reduction to essentially scalar minimisers is not deducible for the problem [\(1.1\)](#) for general f, g .

Acknowledgements

The author would like to thank Erik Lindgren for various scientific discussions and his expert insights on the ∞ -eigenvalue problem, which took place during an academic visit of the author to the University of Uppsala in late 2019, as well as in various electronic communications thereafter.

References

- [1] G. Aronsson, unpublished note on duality & personal communication with the author.
- [2] G. Aronsson, E.N. Barron, L^∞ Variational problems with running costs and constraints, *Appl. Math. Optim.* 65 (2012) 53–90.
- [3] E.N. Barron, M. Bocea, R. Jensen, Viscosity solutions of stationary Hamilton–Jacobi equations and minimizers of L^∞ functionals, *Proc. Amer. Math.* 145 (12) (2017) 5257–5265.

- [4] E.N. Barron, R. Jensen, Minimizing the L^∞ norm of the gradient with an energy constraint, *Comm. Partial Differential Equations* 30 (2005) 1741, 10-12-1772.
- [5] E.N. Barron, R. Jensen, C. Wang, The Euler equation and absolute minimizers of L^∞ functionals, *Arch. Rational Mech. Anal.* 157 (2001) 255–283.
- [6] E.N. Barron, R. Jensen, C. Wang, Lower semicontinuity of L^∞ functionals, *Ann. I. H. Poincaré AN* 18 4 (2001) 495–517.
- [7] T. Bhattacharya, L. Marazzi, An eigenvalue problem for the infinity-Laplacian, *Electron. J. Diff. Equ.* 2013 (47) (2013) 1–30.
- [8] M. Bocea, V. Nesi, Γ -Convergence of power-law functionals, variational principles in L^∞ , and applications, *SIAM J. Math. Anal.* 39 (2008) 1550–1576.
- [9] G. Bouchitté, G. Buttazzo, L. De Pascale, A p -Laplacian approximation for some mass optimization problems, *J. Optim. Theory Appl.* 118 (2003) 1–25.
- [10] F. Brock, R. Manásevich, On the Rayleigh quotient and the first eigenvalue for some vector-valued variational problems, *Differential Integral Equations* 20 (4) (2007) 429–443.
- [11] T. Champion, L. De Pascale, C. Jimenez, The ∞ -eigenvalue problem and a problem of optimal transport, *Commun. Appl. Anal.* 13 (4) (2009) 547–566.
- [12] T. Champion, L. De Pascale, F. Prinari, Γ -Convergence and absolute minimizers for supremal functionals, *COCV ESAIM: Control Optim. Calculus Variat.* 10 (2004) 14–27.
- [13] E. Clark, N. Katzourakis, B. Muha, Vectorial variational problems in L^∞ constrained by the Navier–Stokes equations, *Nonlinearity* (2022) (in press).
- [14] M.G. Crandall, A visit with the ∞ -Laplacian, in: *Calculus of Variations and Non-Linear Partial Differential Equations*, in: Springer Lecture notes in Mathematics, vol. 1927, CIME, Cetraro Italy, 2005.
- [15] G. Croce, N. Katzourakis, G. Pisante, \mathcal{D} -Solutions to the system of vectorial calculus of variations in L^∞ via the singular value problem, *Discrete Contin. Dyn. Syst.* 37 (2017) 6165, 12-6181.
- [16] B. Dacorogna, Direct Methods in the Calculus of Variations, second ed., in: *Applied Mathematical Sciences*, vol. 78, Springer, 2008.
- [17] J.M. Danskin, The theory of min–max with application, *SIAM J. Appl. Math.* 14 (1966) 641–664.
- [18] A. Ern, J.-L. Guermond, Mollification in strongly Lipschitz domains with application to continuous and discrete De Rham complexes, *Comp. Meth. Appl. Math.* 16 (1) (2016) 51–75.
- [19] L.C. Evans, Partial differential equations, in: *Graduate Studies in Mathematics*, AMS, 2010, 19.1.
- [20] L.C. Evans, Y. Yu, Various properties of solutions of the infinity-Laplacian equation, *Commun. PDE* 30 (2005) 1401, 9-1428.
- [21] I. Fonseca, G. Leoni, Modern methods in the calculus of variations: L^p spaces, in: *Springer Monographs in Mathematics*, 2007.
- [22] A. Garroni, V. Nesi, M. Ponsiglione, Dielectric breakdown: optimal bounds, *Proc. R. Soc. Lond. Ser. A Math. Phys. Eng. Sci.* 457 (2001) (2001).
- [23] M. Giaquinta, L. Martinazzi, An introduction to the regularity theory for elliptic systems, in: *Harmonic Maps and Minimal Graphs*, in: Publications of the Scuola Normale Superiore, vol. 11, Springer, 2012.
- [24] S. Hofmann, M. Mitrea, M. Taylor, Geometric and transformational properties of Lipschitz domains, Semmes-Kenig-Toro domains, and other classes of finite perimeter domains, *J. Geom. Anal.* 17 (4) (2007) 593–647.
- [25] J. Hutchinson, Second fundamental form for varifolds and the existence of surfaces minimising curvature, *Indiana J. Math.* 35 (1) (1986).
- [26] R. Hynd, C.K. Smart, Y. Yu, Nonuniqueness of infinity ground states, *Calc. Var. and PDE* 48 (2013) 545–554.
- [27] P. Juutinen, P. Lindqvist, On the higher eigenvalues for the ∞ -eigenvalue problem, *Calc. Var.* 23 (2005) 169–192.
- [28] P. Juutinen, P. Lindqvist, J. Manfredi, The ∞ -eigenvalue problem, *Arch. Ration. Mech. Anal.* 148 (2) (1999) 89–105.
- [29] N. Katzourakis, An introduction to viscosity solutions for fully nonlinear PDE with applications to calculus of variations in L^∞ , in: *Springer Briefs in Mathematics*, 2015, <http://dx.doi.org/10.1007/978-3-319-12829-0>.
- [30] N. Katzourakis, Generalised solutions for fully nonlinear PDE systems and existence-uniqueness theorems, *J. Differential Equations* 23 (2017) 641–686.
- [31] N. Katzourakis, Inverse optical tomography through PDE-constrained optimisation in L^∞ , *SIAM J. Control Optim.* 57 (6) (2019) 4205–4233.
- [32] N. Katzourakis, An L^∞ regularisation strategy to the inverse source identification problem for elliptic equations, *SIAM J. Math. Anal.* 51 (2) (2019) 1349–1370.
- [33] N. Katzourakis, A minimisation problem in L^∞ with PDE and unilateral constraints, *ESAIM Control Optim. Calc. Var.* 26 (60) (2020) 27.
- [34] N. Katzourakis, R. Moser, Existence, uniqueness and structure of second order absolute minimisers, *Arch. Rational Mech. Anal.* (2018) <http://dx.doi.org/10.1007/s00205-018-1305-6>, published online 06/09/2018.
- [35] N. Katzourakis, E. Parini, The eigenvalue problem for the ∞ -bilaplacian, *NoDEA Nonlinear Differential Equations Appl.* 24 (2017) 68.
- [36] N. Katzourakis, E. Varvaruca, *An Illustrative Introduction To Modern Analysis*, CRC Press / Taylor & Francis, 2017.
- [37] Q. Miao, C. Wang, Y. Zhou, Uniqueness of absolute minimizers for L^∞ -functionals involving Hamiltonians $H(x, p)$, *Arch. Ration. Mech. Anal.* 223 (1) (2017) 141–198.
- [38] R. Moser, H. Schwetlick, Minimizers of a weighted maximum of the Gauss curvature, *Ann. Global Anal. Geom.* 41 (2) (2012) 199–207.
- [39] F. Prinari, E. Zappale, A relaxation result in the vectorial setting and power law approximation for supremal functionals, *J. Optim. Theory Appl.* 186 (2020) 412–452.

- [40] A.N. Ribeiro, E. Zappale, Existence of minimisers for nonlevel convex functionals, *SIAM J. Control Opt.* 52 (5) (2014) 3341–3370.
- [41] E. Zeidler, *Nonlinear Functional Analysis and Its Application III: Variational Methods and Optimization*, Springer-Verlag, 1985.