Western North Pacific tropical cyclone model tracks in present and future climates


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Western North Pacific Tropical Cyclone Model Tracks in Present and Future Climates

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Abstract

Western North Pacific tropical cyclone (TC) model tracks are analyzed in two large multimodel ensembles, spanning a large variety of models and multiple future climate scenarios. Two methodologies are used to synthesize the properties of TC tracks in this large data set: cluster analysis and mass moment ellipses. First, the models’ TC tracks are compared to observed TC tracks’ characteristics, and a subset of the models is chosen for analysis, based on the tracks’ similarity to observations and sample size. Potential changes in track types in a warming climate are identified by comparing the kernel smoothed probability distributions of various track variables in historical and future scenarios using a Kolmogorov-Smirnov significance test. Two track changes are identified. The first is a statistically significant increase in the north-south expansion, which can also be viewed as a poleward shift, as TC tracks are prevented from expanding equatorward due to the weak Coriolis force near the equator. The second change is an eastward shift in the storm tracks that occur near the central Pacific in one of the multimodel ensembles, indicating a possible increase in the occurrence of storms near Hawaii in a warming climate. The dependence of the results on which model and future scenario are considered emphasizes the necessity of including multiple models and scenarios when considering future changes in TC characteristics.

1. Introduction

There is a large body of research aiming to understand how tropical cyclones’ (TCs) characteristics are influenced by climate change (Knutson et al., 2010; Walsh et al., 2016). Most studies have focused on changes in global TC frequency and intensity in a warming climate (Camargo, 2013, Knutson et al., 2015, Murakami et al., 2014). As computational resources have increased and global climate models’ ability to simulate TCs has improved (Camargo & Wing, 2016), analyses of other aspects of TC characteristics, including regional studies, have gained momentum in the modeling community (Dwyer et al., 2015; Scoccimarro et al., 2014; Villarini & Vecchi, 2012).

A TC’s landfall location depends on its track. There is large element of inherent randomness (from a climate perspective) in each TC’s track, as it is a function of the steering winds, which can be highly variable on a range of time scales. Some tracks can diverge from the historical record, as in the case of Hurricane Sandy (Hall & Sobel, 2013). Nevertheless, climatologically there are typical track types that occur in each TC basin. The possibility that there may be changes in the properties of these typical TC tracks due to climate change is of great interest due to the possibility of changes in landfall occurrence. However, in order for these projections of track changes to be credible, they need to be statistically significant and robust across a large number of models and climate change scenarios.

We focus here on TC tracks over the western North Pacific (WNP) basin. The WNP, climatologically, is the region with the largest number of TCs per year. Typhoons in the WNP can have large impacts in many Asian countries including the Philippines, China, Taiwan, Japan, Vietnam, and South Korea. A tragic example of the large...
impacts of a landfalling TC in this region was supertyphoon Haiyan, which devastated the Philippines in 2013 (Lander et al., 2014; Lin et al., 2014).

Over the last several decades, there has been a poleward shift in the average latitude of TC lifetime maximum intensities globally (Kossin et al., 2014). This shift is very robust in the WNP and is projected to continue through the end of the century (Kossin et al., 2016). This poleward shift is expected to cause systematic shifts in the areas at greatest TC risk in the region. On the other hand, Lin and Chan (2015) noticed a decrease in the typhoon destructive potential in the Asia Pacific region and linked it to changes in the Pacific subtropical high, which is strongly related to TC tracks. Mei and Xie (2016) noticed an increase in the observed intensities of the TCs making landfall in Asia since late 1970s. More recently, Daloz and Camargo (2017) found a significant poleward shift in the mean genesis position over the Pacific basins, associated with a poleward shift in the genesis indices in the region. While Liang et al. (2017) showed a connected poleward shift in typhoon-induced rainfall over Taiwan.

Currently, there is no clear consensus on the projections of track changes in this region. While in some models there is a poleward (northward in the WNP) shift (Wu et al., 2014), in others there is an eastward shift toward the central North Pacific (Li et al., 2010; Mori et al., 2013; Murakami et al., 2011; Yokoi et al., 2013), a combination of both (Colbert et al., 2015; Murakami et al., 2012; Roberts et al., 2015; Zhao & Held, 2012), or even a southeastward shift (Manganello et al., 2014). Given these results, it is important to consider a uniform statistical approach across multimodel data sets to this problem, so that we can investigate the robustness and statistical significance of track changes in the WNP under global warming.

Our analysis here considers the WNP tracks in current and future climates in two multimodel data sets. The first data set is the U.S. CLIVAR Hurricane Working Group (HWG), with contributions from multiple modeling groups. Each modeling group performed high-resolution (0.25° to 1.25°) global climate model simulations using the same forcings for the current climate, as well as for highly idealized future climate change scenarios. Various aspects of the HWG simulations have been analyzed in the literature, and a summary of these results appeared in Walsh et al. (2015). Of particular interest are the results of Daloz et al. (2015), who analyzed the TC tracks over the North Atlantic basin, using a similar methodology as that applied here to the WNP.

The second multimodel data set considered here is that from the Fifth Coupled Model Intercomparison Project (CMIP5) (Taylor et al., 2012). Fourteen models were analyzed in the historical and one warming scenario, namely the Representative Concentration Pathway 8.5 (RCP8.5). Most CMIP5 global climate models have low horizontal resolution (1.2° to 3.0°), and the TC activity climatology in these models have well-known biases, such as TC intensities lower than observations (Camargo, 2013). Despite these biases, it is possible to obtain useful information from the TC projections from the CMIP5 models as shown in Camargo (2013), Tory et al. (2013), Tang and Camargo (2014), and Kossin et al. (2016).

In addition to the TC tracks obtained by detecting tropical cyclone-like features directly in the model output, we also include in our analysis TC synthetic tracks obtained by a statistical-dynamical downscaling methodology (Emanuel et al., 2008) using the large-scale environmental fields simulated by the models as inputs. Synthetic tracks have been generated using this method for a subset of the models from the HWG (Daloz et al., 2015) and CMIP5 (Emanuel, 2013; Dwyer et al., 2015) data sets.

Although there are many papers analyzing possible track changes in the WNP due to climate change, this is the first time that a comprehensive analysis is performed using the same methodology in two large multimodel data sets, as well as synthetic tracks generated from these data sets by statistical-dynamical downscaling.

Our analysis of the TC tracks will be based on two statistical methods. The first is a cluster analysis, which has been extensively applied to observed (Camargo et al., 2007a, 2007b, 2008; Kossin et al., 2010) and model tracks (Camargo, 2013; Daloz et al., 2015). The second is a method previously applied to North Atlantic TC tracks (Nakamura et al., 2009) which synthesizes multiple track characteristics into a few parameters.

By using these two methodologies across two large multimodel data sets, we determine which type of track changes occur most robustly under climate change. Before we examine the climate change question, though, we will use the same methods to determine the capabilities of these models to reproduce the climatological characteristics of observed tracks in the WNP.
Table 1

<table>
<thead>
<tr>
<th>Type</th>
<th>Name</th>
<th>Abbreviation</th>
<th>SST</th>
<th>CO₂</th>
</tr>
</thead>
<tbody>
<tr>
<td>HWG</td>
<td>Control</td>
<td>ctl</td>
<td>climatology</td>
<td>present</td>
</tr>
<tr>
<td>HWG</td>
<td>plus 2K</td>
<td>p2K</td>
<td>clim. + 2K</td>
<td>present</td>
</tr>
<tr>
<td>HWG</td>
<td>2 × CO₂</td>
<td>CO₂</td>
<td>climatology</td>
<td>2x present</td>
</tr>
<tr>
<td>HWG</td>
<td>plus 2K &amp; 2 × CO₂</td>
<td>p2KCO₂</td>
<td>clim. + 2K</td>
<td>2x present</td>
</tr>
<tr>
<td>MRI HWG</td>
<td>Present</td>
<td>pres</td>
<td>present</td>
<td>present</td>
</tr>
<tr>
<td>MRI HWG</td>
<td>A1B SST</td>
<td>FSST</td>
<td>future</td>
<td>present</td>
</tr>
<tr>
<td>MRI HWG</td>
<td>A1B CO₂</td>
<td>FCO₂</td>
<td>future</td>
<td>future</td>
</tr>
<tr>
<td>MRI HWG</td>
<td>plus 1.83K &amp; A1B CO₂</td>
<td>p2KFCO₂</td>
<td>pres. + 1.83K</td>
<td>future</td>
</tr>
<tr>
<td>CMIP5</td>
<td>Historical</td>
<td>hist</td>
<td>coupled</td>
<td>observed</td>
</tr>
<tr>
<td>CMIP5</td>
<td>RCP8.5</td>
<td>RCP8.5</td>
<td>coupled</td>
<td>8.5W by 2100</td>
</tr>
</tbody>
</table>

Note. The HWG simulations are forced with fixed SST (climatological or climatology plus 2K) and CO₂ values (present climate or twice present climate), for the present (Control) and idealized future simulations (plus 2K, 2x CO₂, plus 2K and 2x CO₂). The CMIP5 historical and future projection RCP8.5 are coupled simulations. These simulations are described in detail in Walsh et al. (2015) and Taylor et al. (2012), respectively.

The observed and model data are described in section 2. Section 3 covers our methods, sections 4 and 5 present the results for the historical and future scenarios, respectively, and we summarize those results in section 6.

2. Data and Model Simulations

We analyzed WNP TC tracks from two multimodel data sets. The first is that from the U.S. CLIVAR HWG intercomparison. The HWG multimodel data set consists of a set of highly idealized experiments using a suite of high-resolution global and regional climate models with the same forcings, most importantly prescribed CO₂ and sea surface temperatures (SSTs) (Walsh et al., 2015), inspired by Yoshimura and Sugi (2005) and Held and Zhao (2011). These idealized experiments were chosen in order to gain a better understanding of the response of TC activity to different forcings. Here we consider four different experiments: (i) a control simulation forced with climatological seasonally varying SSTs and sea ice concentrations (1985–2001) and atmospheric gas concentrations from 1992 (called “ctl”); three idealized future simulations, consisting of (ii) a uniform addition of 2K to the control experiment SSTs (plus 2K or “p2K”); (iii) a doubling of the CO₂ concentration (CO₂) with the same SSTs; and (iv) 2K added to the SSTs and a doubling of CO₂ (p2KCO₂). A summary of these simulations is given in Table 1. Many aspects of these simulations have already been examined (Camargo et al., 2016; Horn et al., 2014; Patricola et al., 2014; Scoccimarro et al., 2014; Shaevitz et al., 2014; Villarini et al., 2014; Wehner et al., 2014), but their focus was not in the WNP TC tracks, as considered here. The HWG models included in our analysis are listed in Table 2. The TC tracks were generated by each modeling group, using their standard tracking routines, and also given in Table 2.

In the case of the MRI model (H8), the simulation designs are not exactly the same as those used in the HWG simulations with the other models, but they are close enough that we decided to incorporate this model in our analysis nonetheless. The MRI simulations are similar to those described in Sugi et al. (2012). For the present climate, the MRI model is forced with monthly observed SST for the period 1979–2003, instead of monthly climatological SST, i.e., the SST varies from year to year, instead of having the same value in a given calendar month and location in all years. The MRI team defined future SST (FSST) and future CO₂ (FCO₂) scenarios based on the average SST and greenhouse gas changes projected by phase 3 of the Coupled Model Intercomparison Project (CMIP3) data set in the period 2075–2100 for the A1B scenario (Meehl et al., 2007). The methodology for the construction of FSST and FCO₂ is explained in Sugi et al. (2012), Murakami and Wang (2010), and Murakami et al. (2011). Three future simulations were performed with the MRI using different SST and CO₂ forcings as follows: (i) future SST (FSST) and current climate CO₂, (ii) present climate SST and future climate CO₂ (FCO₂), and (iii) 1.83K added uniformly to the present observed SST and future CO₂ (p2KFCO₂). These simulations were constructed to examine the effect of greenhouse gases and CO₂ separately, as done in the other simulations of the HWG multimodel ensemble.
Table 2
HWG Models' Characteristics, References for Models and Tracking Schemes, and Number of Simulation Years in Each Scenario

<table>
<thead>
<tr>
<th>Model Name</th>
<th>Resolution</th>
<th>Reference</th>
<th>Tracking Scheme</th>
<th># Years</th>
</tr>
</thead>
<tbody>
<tr>
<td>CAM5.1 LR</td>
<td>H1L</td>
<td>Wehner</td>
<td>Vitart/Prabhat</td>
<td>24</td>
</tr>
<tr>
<td>CAM5.1 HR</td>
<td>H1</td>
<td>Wehner</td>
<td>Vitart/Prabhat</td>
<td>16</td>
</tr>
<tr>
<td>CMCC/ECHAM5</td>
<td>H2T</td>
<td>RockSocccimmaro</td>
<td>Vitart/Walsh</td>
<td>9</td>
</tr>
<tr>
<td>CMCC/ECHAM5</td>
<td>H2</td>
<td>RockSocccimmaro</td>
<td>Vitart/Zhao</td>
<td>9</td>
</tr>
<tr>
<td>FSU</td>
<td>H3</td>
<td>LaRow</td>
<td>Vitart/Zhao</td>
<td>5</td>
</tr>
<tr>
<td>GFS</td>
<td>H4</td>
<td>Saha</td>
<td>Vitart/Zhao</td>
<td>20</td>
</tr>
<tr>
<td>GISS</td>
<td>H5</td>
<td>Schmidt</td>
<td>Camargo and Zebiak</td>
<td>20</td>
</tr>
<tr>
<td>HadGEM3 LR</td>
<td>H6L</td>
<td>Schmidt</td>
<td>Hodges/Bengtsen</td>
<td>20</td>
</tr>
<tr>
<td>HadGEM3 MR</td>
<td>H6M</td>
<td>Schmidt</td>
<td>Hodges/Bengtsen</td>
<td>20</td>
</tr>
<tr>
<td>HadGEM3 HR</td>
<td>H6</td>
<td>Schmidt</td>
<td>Hodges/Bengtsen</td>
<td>10</td>
</tr>
<tr>
<td>HiRAM</td>
<td>H7</td>
<td>Zhao</td>
<td>Vitart/Zhao</td>
<td>20</td>
</tr>
<tr>
<td>MRI</td>
<td>H8</td>
<td>Mizuta/Murakami</td>
<td>Murakami</td>
<td>25</td>
</tr>
</tbody>
</table>

Note. LR, Low Resolution; MR, Medium Resolution; HR, High Resolution. References: Wehner, Wehner et al. (2015); Prabhat, Prabhat (2012); RockSocccimmaro, Roeckner et al. (2003) and Scoccimarro et al. (2011); Walsh, Walsh (1997); LaRow, LaRow et al. (2008); Vitart, Vitart et al. (2003); Saha, Saha et al. (2014); Zhao, Zhao et al. (2009); Schmidt, Schmidt et al. (2014); Camargo and Zebiak, Camargo and Zebiak (2002); Walters, Walters et al. (2011); HB, Hodges (1995) and Bengtsen et al. (2007a, 2007b); Mizuta and Murakami, Mizuta et al. (2012) and Murakami et al. (2012); and Murakami, Murakami et al. (2012).

We also considered CMIP5 models and simulations. These include the historical runs and one future scenario, RCP8.5, in which greenhouse gas concentrations reach relatively high values in the later years of the 21st century. Only one ensemble member was analyzed for each CMIP5 model and scenario. The models and TCS considered here are the same as those included in Camargo (2013) and Tang and Camargo (2014). The TCS were tracked using the Camargo-Zebiak tracking algorithm (Camargo & Zebiak, 2002). The WNP TCS in a subset of these models have already been discussed in Kossin et al. (2016). The list of the CMIP5 models included in our analysis is given in Table 3. The horizontal resolutions in the CMIP5 models are overall much lower than those in the HWG models. It is well known that low-resolution global climate models are able to generate TC-like structures with many similarities to those of observed TCs (Bengtsen et al., 1982; Camargo et al., 2005;)

Table 3
List of the CMIP5 Models Analyzed, Including References and Their Horizontal Resolution

<table>
<thead>
<tr>
<th>Model Name</th>
<th>Resolution</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>CanESM2</td>
<td>M1</td>
<td>2.9°</td>
</tr>
<tr>
<td>CCSM4</td>
<td>M2</td>
<td>1.2°</td>
</tr>
<tr>
<td>CSIRO-Mk3.6.0</td>
<td>M3</td>
<td>1.9°</td>
</tr>
<tr>
<td>FGOALS-g2</td>
<td>M4</td>
<td>3.0°</td>
</tr>
<tr>
<td>GFDL-CM3</td>
<td>M5</td>
<td>2.5°</td>
</tr>
<tr>
<td>GFDL-ESM2M</td>
<td>M6</td>
<td>2.5°</td>
</tr>
<tr>
<td>HadGEM2-ES</td>
<td>M7</td>
<td>1.9°</td>
</tr>
<tr>
<td>INM-CM4.0</td>
<td>M8</td>
<td>2.0°</td>
</tr>
<tr>
<td>IPSL-CM5A-LR</td>
<td>M9</td>
<td>3.7°</td>
</tr>
<tr>
<td>MIROC-ESM</td>
<td>M10</td>
<td>2.8°</td>
</tr>
<tr>
<td>MIROCS</td>
<td>M11</td>
<td>1.4°</td>
</tr>
<tr>
<td>MPI-ESM-LR</td>
<td>M12</td>
<td>1.9°</td>
</tr>
<tr>
<td>MRI-CGCM3</td>
<td>M13</td>
<td>1.2°</td>
</tr>
<tr>
<td>NorESM1-M</td>
<td>M14</td>
<td>2.5°</td>
</tr>
</tbody>
</table>

Note. TCS are tracked using the Camargo-Zebiak tracking routine (Camargo & Zebiak, 2002), as described in Camargo (2013).
Camargo & Wing, 2016; Manabe et al., 1970). However, these TC-like structures are weaker and larger than observed storms or from high-resolution climate models such as the HWG multimodel data set. By including the CMIP5 models, however, we are able to span a broader range of future scenarios and models in our analysis, and we judged this sufficient motivation to do so.

The tracking routines used in the HWG and CMIP5 are very similar. They look for features in the model output with a minimum sea level pressure, maximum low-level vorticity and wind speed, and a warm core. All CMIP5 models used the same tracking algorithm, but with thresholds dependent on model resolution (Camargo, 2013). In contrast, each modeling group applied their own tracking scheme to the HWG models (Shaevitz et al., 2014). In the case of the HWG models Horn et al. (2014) showed that the differences in TC frequency due to tracking algorithm decrease as model resolution increases and TC intensity increases. We examined some specific cases for HWG model tracks, similar to what was done in Daloz et al. (2015), and we could not find any dependence of our results on the tracking routine considered.

In addition to the TC tracks from the explicit simulations from the HWG and the CMIP5 models, we also analyzed tracks produced by statistical-dynamical downscaling from a subset of these models. The downscaling uses the method developed by Emanuel et al. (2006) and Emanuel (2006). The main benefit of this downscaling technique is that it can generate a very large number of synthetic TC tracks with realistic intensities based on environmental fields from reanalyses and climate models. This technique has been successfully applied to generate TC tracks from both reanalysis (Emanuel, 2010) and climate models (Emanuel et al., 2008) and has been coupled with storm surge models (Lin et al., 2012).

<table>
<thead>
<tr>
<th>Name</th>
<th>Type</th>
<th>Original Model</th>
</tr>
</thead>
<tbody>
<tr>
<td>dH1</td>
<td>HWG</td>
<td>CAM5.1 LR</td>
</tr>
<tr>
<td>dH2</td>
<td>HWG</td>
<td>CMCC/ECHAM5</td>
</tr>
<tr>
<td>dH5</td>
<td>HWG</td>
<td>GISS</td>
</tr>
<tr>
<td>dH7</td>
<td>HWG</td>
<td>HiRAM</td>
</tr>
<tr>
<td>dM2</td>
<td>CMIP5</td>
<td>CCSM4</td>
</tr>
<tr>
<td>dM5</td>
<td>CMIP5</td>
<td>GFDL-CM3</td>
</tr>
<tr>
<td>dM7</td>
<td>CMIP5</td>
<td>HadGEM2-ES</td>
</tr>
<tr>
<td>dM11</td>
<td>CMIP5</td>
<td>MIROC5</td>
</tr>
<tr>
<td>dM12</td>
<td>CMIP5</td>
<td>MPI-ESM-LR</td>
</tr>
<tr>
<td>dM13</td>
<td>CMIP5</td>
<td>MRI-CGCM3</td>
</tr>
</tbody>
</table>

Note. The downscaled models are the same as in Daloz et al. (2015) and Emanuel (2013). The names of the downscaled models correspond to the original model names (Tables 2 and 3).
The Emanuel’s downscaling technique is described in detail in Emanuel (2006) and Emanuel et al. (2006); here we only give a brief summary. First, synthetic track origin points are generated by seeding randomly the smoothed space-time observed probability distribution function of tropical cyclone genesis. The survival of these seeds depends on its environment. Once the storm is generated, it moves according to the environmental winds vertically averaged over a deep layer of the troposphere, with a correction for the “beta drift” (Holland, 1983), similar to the well-known “beta and advection model” (Marks, 1992). Once the track is generated, the Coupled Hurricane Intensity Prediction System (CHIPS) (Emanuel et al., 2004) is run along each track and determines the storm intensity, as well as when the storm dissipates. The environmental fields necessary to generate the synthetic tracks used here are from the CMIP5 and HWG model simulations.

The CMIP5 synthetic tracks analyzed here have been previously discussed in Emanuel (2013), Dwyer et al. (2015), and Kossin et al. (2016) and were generated from a subset of the CMIP5 models above. Similarly, synthetic TC tracks were generated from a subset of the HWG models, as discussed in Daloz et al. (2015) for the case of the North Atlantic. The list of downscaled models is given in Table 4. Tables 5 and 6 show the numbers of TC tracks in each model and scenario analyzed here.

There are two important caveats in our analysis that should be clearly stated. The first is that when comparing the CMIP5 and HWG explicit tracks, the differences between the HWG and CMIP5 simulations are convolved with the differences in model resolution, which affects TC simulation. The second is that, while the CMIP5 simulations are coupled, the HWG are forced with fixed SSTs; therefore, the HWG experiments cannot enforce surface energy balance, which could have potential consequences when simulating TCs, similar to the issues...
due to SST bias in the coupled simulations. Therefore, there is no reason to expect that the track changes in the HWG experiments should be consistent with those in the CMIP5 simulations.

We compared the model TC data with WNP observed TC tracks from the Joint Typhoon Warning Center best-track data set for the period 1950–2013 (Chu et al., 2002; JTWC, 2017).

3. Methods

3.1. Cluster Analysis

We use a cluster analysis method that has been extensively used to analyze TC tracks, both in observations (Camargo et al., 2007a, 2007b, 2008; Kossin et al., 2010; Ramsay et al., 2012) and models (Camargo, 2013; Daloz et al., 2015). This method is described in detail in Gaffney (2004) and was first applied to extratropical cyclone tracks (Gaffney et al., 2007). The cluster technique is based on a mixture of polynomial regression models (quadratic here), which are used to fit the shape of the TC tracks. The log likelihood is a goodness of fit metric for probabilistic models. Here the best fit is obtained by maximizing the likelihood that these polynomials fit the data, in this case the longitude and latitude of the tracks. Each model is described by a set of parameters, including regression coefficients and a noise matrix.

The strength of the cluster analysis technique is that it easily fits tracks of different lengths. As is typical in cluster analysis, however, the number of clusters is not uniquely determined but must be specified a priori. Here we use the same number of clusters that was chosen for observed WNP typhoon tracks, i.e., seven (Camargo et al., 2007a, 2007b). By choosing the same number of clusters in models and observations, we can make a direct comparison.

Each model track is assigned to a specific cluster. In the case of the explicit model tracks, there are cases in which there are not many storms per model and scenario (a typical bias of low-resolution models). Therefore, in order to increase the data sample size used in the cluster analysis in each case, we considered the tracks of all scenarios simultaneously for each model as an input of the cluster algorithm. Once each track is assigned to a specific cluster, we can identify to which scenario it belongs.

3.2. Track Moments

A method to distill track shape and length down to a few physically relevant parameters was developed by Nakamura et al. (2009). The entire track shape and length are taken into account to define mass moments of the open curve that defines a storm track. These moments can be used to summarize the statistical characteristics of the storm tracks. The centroid is the first mass moment defining the longitude (X) and latitude (Y) of the center of mass of an individual track or collection of tracks. In the case of an individual track, this centroid lies in the interior of the curve, but not on the curve itself. This first moment determines the location of the effective center of gravity of the individual track or group of tracks. The second mass moments are a measure of the shape of the track or tracks considered. They are defined by the variance or the average squared differences of the weighted distances from the centroid and can be expressed geometrically as a covariance ellipse. The variance is then represented by the orientation and length of the principal axes of the ellipse and is a measure of the extent of the tracks in three directions X, Y, and XY. By analyzing the location of the centroids and the shape of the ellipses, one is able to synthesize a large amount of information about the tracks in a very simplified manner. For instance, a rounded variance ellipse implies that the variance in directions X and Y is very similar, while the tilt of the ellipse points to the dominant direction of the track. This method was applied to the North Atlantic hurricane tracks in Nakamura et al. (2009), where it is described in detail.

Here we use the ellipses for two purposes: first, to compare the model tracks to the observed ones and second, to determine the existence of shifts in model tracks under climate change scenarios. The strength of this method is that it uses a simple feature to represent the characteristics of the tracks, either for the whole basin or in each cluster, which makes the comparison with observations and analysis of tracks’ shifts simpler than using many tracks or track density.

3.3. Statistical Significance of Track Changes

We tested various characteristics of the tracks to determine if their differences are statistically significant in present and future climates. In order to do that, first a kernel smoothing function estimator (KE) was applied to the distributions of variables in the analysis. KE can increase the signal-to-noise ratio by making visible the signal that matches the size and shape of the KE. We used the Matlab2012 default KE which employs a normal kernel with an optimized bandwidth. Use of the KE before testing ensures that the continuous distribution of
a variable is tested rather than a difference in sampling. Future distributions are estimated at the same points along the axis of the 20C distributions. The future distributions are then renormalized by multiplying by the ratio of the future KE by the 20C KE.

The Kolmogorov-Smirnov (KS) test is then applied to the control and future scenarios to determine if they are from the same underlying probability distributions at the 0.1 level. The KS test is nonparametric and compares the location and shape of the empirical cumulative distribution functions of the two samples. Once statistical significant changes in the full PDF are identified, the type of the change (e.g., westward/eastward or larger/smaller) across the multimodel ensembles is examined based on the distribution mean. In order for a track change to be considered statistically significant and robust at least half of the models in each of the multimodel data sets are required to have the same type of statistically significant shift.

4. Present Climate Tracks

4.1. Observations

In Camargo et al. (2007a, 2007b) cluster analysis was applied to the observed WNP TC tracks for the period 1950–2005. Here we summarize an updated version of their analysis for the period 1950–2013. The tracks (in grey), genesis positions (red circles), and track ellipses (in black) for all clusters (a–g) and all TCs (h) are shown in Figure 1.

The clusters were originally labeled in order of occurrence (Camargo et al., 2007a, 2007b), from the most populated cluster A (361 TCs) to the least populated cluster G (117 TCs). Clusters D and E had a very similar number of storms in the original analysis, 178 and 175 TCs, respectively. In the updated version, cluster D (207 TCs) has slightly fewer TCs than cluster E (216 TCs). Clusters A, C, and E are dominated by recurving TCs, while clusters B, D, and F TCs are mostly straight moving, and G has a combination of both. These clusters strongly depend on the storms’ genesis positions. Some track types are modulated by the El Niño–Southern Oscillation (ENSO): Cluster E TC tracks occur more often in eastern Pacific El Niño events, Cluster G in central Pacific or Modoki El Niño seasons, and Cluster A in La Niña events (Camargo et al., 2007b). Furthermore, TC tracks in clusters A, B, and E occur more often when the Madden-Julian Oscillation is active over the western North Pacific basin.

The slopes and sizes of the variance ellipses, as well as their centroid locations, emphasize the characteristics of the different clusters in Figure 1. Straight-moving clusters D and F have very elongated ellipses, while recurring clusters ellipses are more rounded. The slopes of the ellipses differ among the recurring clusters as well. The ellipse of cluster C has a centroid north of 20°N and northeastward slope, while the ellipses of cluster E and G have centroids south of 20°N and tilt in the northwestward direction.

4.2. Present Climate

The first question we want to examine is whether the models are able to reproduce the observed tracks in the current climate. Given the high number of models, it is impossible to show the tracks of all models and scenarios here, so only the tracks of a few chosen models are shown in Figure 2. On the left are tracks from the explicit models, while on the right are the tracks of the corresponding downscaled models. Figures 2a and 2c show HWG model tracks, with CMIP5 model tracks in Figures 2e and 2g for the control and historical simulations, respectively. The centroid of the observed tracks is located near 138°E and 20°N, and the models of each type reproduce this well. The explicit models match the slight southeast to northwest tilt of the observed tracks, while the downscaled tracks have a distinct southwest to northeast tilt. In the tracks this tilt is reflected as a predominately eastward vs. westward movement. For instance, model dH2 in Figure 2d has more downscaled tracks above 30°N than the corresponding explicit tracks (H2) in Figure 2c, enhancing the southwest to northeast tilt of the recurring tracks. The explicit model ellipses are smaller both because of the shorter lifetime of tracks as in the case of model H2, as well as the much smaller sample size of the data. There are many more tracks of the downscaled models (see Tables 5 and 6), allowing a wider variance, as the ellipses’ variance increases with frequency. Ideally, we would have similar sample sizes; however, given the huge computational resources necessary to generate more explicit tracks, this is not possible, and we consider in our analysis all tracks available from all cases. Furthermore, the differences between the explicit and downscaled ellipses could include a contribution from their different termination criteria, as the downscaled tracks allow for extratropical transition taking the storms to higher latitudes than the explicit tracks.

We compare the mass moment ellipses of all the models’ tracks (shown in Figure 3) with the observations (Figure 1h). The explicit HWG models have higher horizontal resolution and are more closely grouped than are
Figure 1. Western North Pacific observed tracks for the period 1950–2013. (a–g) The tracks (in grey) in individual clusters based on the classification of Camargo et al. (2007a, 2007b). The initial positions are marked in red circles. The mean mass moment ellipses are shown in black, with the centroids marked with a black cross.

Some of the CMIP5 explicit models have mass moments that are significantly differently shaped than those in observations, indicating tracks that are not realistic, as was seen for the Atlantic and eastern North Pacific in Camargo (2013). This indicates, in general, that the higher horizontal resolutions of the HWG models lead to more realistic tracks or could be a result of the inexistence of SST biases, as the HWG simulations are forced with fixed climatological SSTs. It is interesting to notice, though, that the downscaled HWG and CMIP5 models have ellipses with very consistent sizes and shapes. The southwest to northeast tilt in the downscaled tracks ellipses occurs in all but one of the models (dH1).
Figure 2. Western North Pacific model tracks (grey), genesis (red circles), and mass moment ellipses and centroids (black) for the current climate in selected models. (a, c, e, g) Tracks from the explicit models. (b, d, f, h) The corresponding downscaled models. HWG (CMIP5) models are shown in Figures 2a and 2c (Figures 2e and 2g) in the control (historical) simulations. Two hundred randomly selected tracks are shown in each panel.

Some of the models have an unrealistically low number of tracks in the present and/or future climates. We need a reasonable sample size in order for the cluster analysis to yield statistically significant results. Similar to what was done in Camargo (2013) and Kossin et al. (2016), we exclude the models with very few tracks from the analysis. The models that fall in this category are MIROC-ESM (M10, total of 43 tracks), NorESM1 (M14, total of 51 tracks), and CAM5.1 LR (H1L, total of 115 tracks) (see Table 6).

We performed a few sensitivity tests on subsets of the model tracks as well. The first test was to examine the role of horizontal resolution in the WNP tracks of the HadGEM3 model, which was available in three different
resolutions: H6L, H6M, and H6 (see Table 2). There were no significant differences in the mass moment ellipses among these different versions (not shown). Therefore, for the rest of our analysis we considered only the version with the highest horizontal resolution (H6). Even the lowest resolution version of this model has a higher resolution, though, than all the CMIP5 models. This seems to indicate that models with resolutions as low as the CMIP5 models tend to have unrealistic tracks, as indicated by the comparison of Figure 3c and Figures 3a, 3b, and 3d. Once the model resolution is above a certain threshold (in this case 1°), using even higher resolutions will not lead to further improvements in the track characteristics. This issue should be further investigated using more models with multiple horizontal resolutions.

We also compared the tracks obtained by different tracking routines for the model CMCC/ECHAM5 (H2T and H2; not shown). Although the number of tracks generated in each case is different, the overall characteristics of the tracks do not depend on the tracking routine, similar to the result obtained in Daloz et al. (2015) for the North Atlantic tracks. Therefore, for the rest of our analysis we will only consider model H2.

We applied the cluster analysis to the remaining models, i.e., excluding M10, M14, H1L, H2T, H6L, and H6M. A test to judge model fitness is the similarity of the model tracks to the seven observed clusters. For a model to be considered well suited for this analysis, identification of at least four of the seven observed clusters was required. In order to do that, we compared the ellipses of the models’ and observed clusters. Primarily, the maximum overlapping area of the observed and model ellipses was used to determine to which observed cluster the model cluster corresponded. Second, geographic location and ellipse tilt were taken into consideration. Of the 12 explicit CMIP5 models considered here, only 6 models passed these criteria, namely models M1, M2, M3, M7, M10, and M11. In contrast, all HWG models examined and all of the downscaled CMIP5 and HWG models passed this test. These results corroborate our previous conclusion that high-resolution models generate more realistic model tracks.
The resulting clusters can be seen in Figures 4–6 for tracks from one model of each type, i.e., explicit CMIP5, explicit HWG, and downscaled (from CMIP5). As could be expected from our discussion above, the CMIP5 clusters have some track types that do not occur in reality (Figure 4). Both the HWG (Figure 5) and the CMIP5 downscaled (Figure 6) cluster tracks are more realistic and more similar to observations, even though some clear biases and differences with observed clusters can still be noted. For instance, both models have problems reproducing the South China Sea storms (straight-moving tracks in observed clusters B and D) (Figure 1). In any case, the large improvement that can be achieved in model tracks by using either higher horizontal resolution or downscaling techniques is very clear in these figures.
Figure 5. Western North Pacific model tracks in individual clusters for HWG model H7 in the present climate simulation. Two hundred randomly selected tracks are shown in each panel.

5. Future Climate
5.1. Cluster Occurrence

The next question we examine is whether there are statistically significant changes in the tracks in the future climate scenarios compared to the historical climate. In addition to assessing statistical significance, we want to determine which changes are robust across many models. We first consider changes in the occurrence of a cluster in the future. Do specific track types become more or less common in the future, and if so, are these changes robust across models?

No statistically significant changes in frequency in the future scenarios were found for the HWG explicit model tracks using the rank sum test at the 0.1 level for all clusters. The rank sum test was chosen as it can be used for testing significance of small populations of unknown distributions. We repeated the same statistical test with
Figure 6. Western North Pacific model tracks in individual clusters for the downscaled CMIP5 model dM12 in the present climate simulation. Two hundred tracks are shown in each panel.

5.2. Track Changes

Next we examine possible changes in the characteristics of the tracks in the future. These changes could be related to shifts in the tracks, or tracks’ shape or length. In order to test those possibilities we applied a Kolmogorov-Smirnov (KS) test in present and future climate distributions for each characteristic of the tracks (e.g., longitude of the ellipse centroid), to determine if they belong to different probabilistic distributions.

the CMIP5 explicit model tracks and the HWG and CMIP5 downscaled tracks. None of these models showed a statistically significant change in the cluster assignment occurrence in future climates, as shown in Figure 7. We also examined whether the total number of storms in the WNP in each model was statistically different in the future and present climates, and again, no model passed the rank sum significance test, even though there is an increase in the number of tracks in the downscaled CMIP5 models as was shown in Emanuel (2013).
Figure 7. Percentage of storms assigned to each cluster per model and scenario for the HWG explicit tracks. Clusters not corresponding to observed clusters are marked with a star. None of the models showed a statistically significant change in the cluster assignment occurrence in future climates.

For a change on a specific direction, e.g., northward or eastward, to be considered statistically significant for a specific cluster or the whole basin, it needs to pass the KS test at the 0.1 level for at least half of the models available for that type of model (HWG or CMIP5) for that cluster, or six or more models for the whole basin. The number six was chosen as it corresponds to half of the number of CMIP5 models (explicit and downscaled) and HWG models (explicit and downscaled) considered in our analysis. However, as discussed above, we could not identify all clusters in all models; therefore, the number of models necessary for significance test in specific clusters needs to take that into account.

As an example, we show in Figure 8 the ellipse centroid X kernel distributions for cluster E in the CO2 and control simulations in selected HWG models, as well as cluster F in the RCP85 and historical simulations in selected CMIP5 and downscaled CMIP5 models. Eastward and westward shifts in the means of the distributions can be clearly seen. Some distributions show shifts of the peak westward (model H1), while in others shifts occur in the tails of the distribution (model H7), and in still others shifts are found in both peak and tails (model H6). A similar analysis was performed for all models, clusters, and scenarios for various characteristics.
of the distributions, namely the locations of the centroid ellipses (centroids $X$ and $Y$), the variances of the ellipses (variances $X$, $Y$, and $XY$), their seasonalities, and track lengths.

The variance in the direction $X$ is a measure of the west to east extent of the tracks. The variance in direction $Y$ is a measure of the south to north extent, and the variance in the direction $XY$ is a measure of the tilt, described as a southwest to northeast or positive tilt and as southeast to northwest or negative tilt extent. These three
Figure 9. Track ellipses in cluster A for selected models that have a statistically significant increase in the variance of $Y$, for (a–d) HWG and (e–j) CMIP5 models.

directional variances have by far the most number of significant changes in the future distributions when compared with the control or historical simulations. As an example of our analysis, Figure 9 shows that there are changes in cluster A, with significant changes in the variances of $Y$.

When all tracks in the basin are considered together, there is a net northward movement, in particular in the RCP85 scenario, and a net eastward movement of the straight-moving tracks. However, only in one scenario the changes in ellipse characteristics are statistically significant, namely all tracks in p2K scenario (variance $X$ and variance $Y$), with no statistically significant change for the other scenarios. This could potentially be
Table 7

<table>
<thead>
<tr>
<th>Model</th>
<th>A</th>
<th>C</th>
<th>E</th>
<th>G</th>
</tr>
</thead>
<tbody>
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<td>1N</td>
<td>2N</td>
<td>3N</td>
<td>1N</td>
</tr>
<tr>
<td>H2</td>
<td>1N</td>
<td>2N</td>
<td>3N</td>
<td>2N</td>
</tr>
<tr>
<td>H3</td>
<td>1N</td>
<td>2N</td>
<td></td>
<td>1N</td>
</tr>
<tr>
<td>H4</td>
<td>1N</td>
<td>2N</td>
<td>3N</td>
<td>1N</td>
</tr>
<tr>
<td>H5</td>
<td></td>
<td>2N</td>
<td>1N</td>
<td></td>
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<tr>
<td>H7</td>
<td>3N</td>
<td></td>
<td></td>
<td>3N</td>
</tr>
<tr>
<td>dH1</td>
<td></td>
<td></td>
<td>2N</td>
<td>3N</td>
</tr>
<tr>
<td>dH2</td>
<td>1N</td>
<td></td>
<td>3N</td>
<td></td>
</tr>
<tr>
<td>M1</td>
<td></td>
<td></td>
<td>4N</td>
<td></td>
</tr>
<tr>
<td>M2</td>
<td></td>
<td>4N</td>
<td></td>
<td></td>
</tr>
<tr>
<td>M3</td>
<td>4N</td>
<td></td>
<td></td>
<td>4N</td>
</tr>
<tr>
<td>M7</td>
<td></td>
<td></td>
<td>4N</td>
<td></td>
</tr>
<tr>
<td>M11</td>
<td>4N</td>
<td></td>
<td></td>
<td>4N</td>
</tr>
<tr>
<td>M12</td>
<td></td>
<td>4N</td>
<td></td>
<td>4N</td>
</tr>
<tr>
<td>dM2</td>
<td>4N</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
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<td>4N</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>dM7</td>
<td>4N</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>dM12</td>
<td>4N</td>
<td></td>
<td></td>
<td>4N</td>
</tr>
</tbody>
</table>

Note. Future scenarios p2K, CO2, p2KCO2, and RCP85 are indicated as 1, 2, 3, and 4 in the table.

because changes in one track type cancels changes in other track types. Therefore, in order to examine this possibility, we need to consider track changes in specific clusters.

Given the very large number of models, clusters, and scenarios analyzed, only the statistically significant and robust results from our analysis will be discussed here. The most dominant recurving track type (cluster A) has an increase in the variance of \( Y \), which is statistically significant in two HWG scenarios (p2K and CO2) and in the RCP85 CMIP5 scenario. This is consistent with the northward movement noticed for all the tracks in the basin noted above, given that TCs do not form very close to the equator. Table 7 shows the models and scenarios that have a significant increase in variance of \( Y \) for the recurving clusters A, C, E, and G. In contrast, the straight-moving cluster D has a smaller variance in \( Y \) in the HWG scenarios, as well as the straight-moving cluster F in the RCP85 scenario. Overall, significant changes in the N-S direction of the tracks were the most frequent in our analysis, though not always consistent across the HWG and CMIP5 data sets.

Another interesting result is that the tracks in cluster F, which are westward straight moving and can originate in the central Pacific, have an eastward shift in centroid \( X \) for the CMIP5 RCP85 scenario (5 out of 11 models), as well as shorter life-span (5 out of 11 models), as shown in Table 8. Furthermore, some of the HWG models have a decrease of variance in \( X \) (6 out of 11 models) and a decrease in the life-span (6 out of 11 models). As cluster F tracks are straight moving from west to east, both these changes would also result in a net eastward displacement of these tracks. Taking all three changes (centroid \( X \), variance in \( X \), and life-time) into account, the eastward shift in cluster F is clear, though not statistically significant when only considering centroid \( X \) changes. As cluster F has genesis locations very close to the date line, this eastward shift would lead to a higher occurrence of central Pacific storms in the future, as previously discussed in the literature (Colbert et al., 2015; Li et al., 2010; Mori et al., 2013; Murakami et al., 2011, 2012; Roberts et al., 2015; Yokoi et al., 2013; Zhang et al., 2017). This track type is also modulated by the central Pacific or Modoki ENSO. In recent years, there have been very active central Pacific seasons (e.g., Sobel et al., 2016), perhaps with a contribution from anthropogenic climate change (Murakami et al., 2015, 2017). Cluster G, which can also affect Hawaii, is also the only cluster which has consistent and statistically significant changes for \( X \) and \( Y \) variances for HWG and CMIP5 scenarios.
Table 8
Statistical Significant Changes (0.1 Level) in Centroid X, Variance of X, and Life-Span in Future Scenarios Compared With the Present Climate in Cluster F

<table>
<thead>
<tr>
<th>Model</th>
<th>Variance X</th>
<th>Life-Span</th>
<th>Model</th>
<th>Centroid X</th>
<th>Life-Span</th>
</tr>
</thead>
<tbody>
<tr>
<td>H1</td>
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<td>1S 2S 3S</td>
<td>M1</td>
<td>4S</td>
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</tr>
<tr>
<td>H2</td>
<td>1S 2S 3S</td>
<td>1S 3S</td>
<td>M2</td>
<td>4E</td>
<td>4B</td>
</tr>
<tr>
<td>H3</td>
<td>3S</td>
<td>1B 2S 3S</td>
<td>M11</td>
<td>4E</td>
<td>4S</td>
</tr>
<tr>
<td>H5</td>
<td>1S 3S</td>
<td></td>
<td>M12</td>
<td>4E</td>
<td></td>
</tr>
<tr>
<td>H6</td>
<td>1B 2B</td>
<td>1B 2B</td>
<td>dM2</td>
<td>4E</td>
<td></td>
</tr>
<tr>
<td>H7</td>
<td>1B 2B</td>
<td>1S 2S 3S</td>
<td>dM5</td>
<td>4W</td>
<td>4S</td>
</tr>
<tr>
<td>H8</td>
<td>1S 2S 3B</td>
<td>2S 3B</td>
<td>dM7</td>
<td>4E</td>
<td>4B</td>
</tr>
<tr>
<td>dH1</td>
<td>2S</td>
<td></td>
<td>dM11</td>
<td>4W</td>
<td></td>
</tr>
<tr>
<td>dH5</td>
<td>1S 3S</td>
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<td>dM12</td>
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<td>dM13</td>
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<td>4S</td>
</tr>
<tr>
<td>H4</td>
<td>⋆</td>
<td>⋆</td>
<td>M7</td>
<td>⋆</td>
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</tr>
</tbody>
</table>

Note. Variance of X and life-span are labeled B for bigger and S for smaller. Centroid of X is labeled E for East and W for West. Also shown in the table with a star are the models for which cluster F could not be identified.

In the WNP the variance of XY plays a large role in landfall potential. The main landmass in the basin is located to the west and northwest. The recurving track shapes of A, C, E, and G tilt toward land when moving from southeast to northwest (negative tilt) and away from land when moving southwest to northeast (positive tilt). In two of the HWG scenarios (p2K and p2KCO2), there is an eastward shift in cluster A, the most dominant track type. In contrast, in the CMIP5 models, there is a larger tilt (variance XY) in the RCP85 scenario in three of the clusters (A, B, and F), with the corresponding tracks, therefore, having a tendency for moving away from land. While the types of shifts are different in both multimodel groups, they lead to a similar consequence.

The location of lifetime maximum intensity (LMI) is another metric of interest. Kossin et al. (2014) showed that in observations this metric is less sensitive to nonmeteorological data issues. In observations there is a poleward shift in the LMI in some regions, in particular the WNP (Kossin et al., 2014, 2016), and this poleward shift in the WNP is projected to continue in the future under anthropogenic climate change (Kossin et al., 2016).

In the case of the dominant cluster A in CMIP5 there were five models with a statistically significant LMI eastward shift. This eastward shift in the CMIP5 models’ cluster A is coherent with the ellipses’ eastward shift discussed above. Furthermore, in our analysis overall (including significant and nonsignificant cases) there were 24 cases (cluster and scenario) of a LMI northward shift out of 47 possible cases, including all of the CMIP5 cases. However, in spite of being a clear dominant shift in the northward direction, very few were statistically significant, including when all tracks in the basin are considered. This northward LMI shift is in qualitative agreement with Kossin et al. (2016). It should be noted though that the chosen subset of CMIP5 models in Kossin et al. (2016) is different from the one here, as different criteria were applied. Second, here we used a kernel smoother prior to constructing a probability distribution function and KS statistical test, while in Kossin et al. (2016) the probability distribution functions of the latitude of LMI were constructed with the raw model output.

5.3. Environmental Field Changes
In the previous section we found two primary robust track changes: a poleward shift and an increase in Central Pacific tracks. Both of these changes are coherent with large-scale environmental changes in the models.

There is large body of literature discussing projections of a poleward shift in multiple aspects of the climate system under global warming, mainly in extratropical clouds and storm tracks (e.g., Barnes & Polvani, 2013; Chen & Held, 2007; Ts Elioudis et al., 2016; Yin, 2005), associated with the weakening and poleward expansion of the Hadley cell under global warming (Lu et al., 2007; Vecchi & Soden, 2007). Kossin et al. (2014) showed that the observed LMI poleward shift could be related to changes in the large-scale environment over the past 30 years. Kossin et al. (2014) found that changes in vertical wind shear and potential intensity—the
latter being the theoretical maximum intensity that a TC can achieve under specified environmental conditions (Emanuel, 1988)—have resulted in an expansion in the regions most favorable for TC development. Similarly, in the CMIP5 multimodel mean there is an increase in potential intensity in the whole Northern Hemisphere, a decrease in the vertical wind shear in the northern part of the basin, and an increase in the genesis potential index (Camargo, Emanuel, & Sobel, 2007; Emanuel & Nolan, 2004) in the northern part of the basin (see Camargo, 2013, Figures 12–14), which leads to a poleward expansion of the region favorable for TC genesis and intensification. This favorable region also expands into the central North Pacific, making that region more prone to the occurrence of TCs.

Similar analysis of the HWG multimodel ensemble environmental fields is currently in progress and will be the topic of a future publication. Results from the Goddard Institute for Space Studies (GISS) model show that there is an increase in the potential intensity in the western and central North Pacific for the p2K and p2KCO2 scenarios, accompanied by a decrease of the vertical wind shear and an increase in the tropical cyclone genesis index (Camargo et al., 2014; Tippett et al., 2011) in the eastern part of the basin, leading to an expansion of the area that is favorable for TC occurrence poleward and eastward (Camargo et al., 2016, Figures 10, 11, and 13).

Another metric of the environment’s favorability for TC occurrence and intensification is the ventilation index, which combines vertical wind shear (between 850 and 250 hPa), potential intensity, and entropy deficit (defined using the ratio of the differences of the saturated and moist entropy value at 700 hPa, and the sea surface and boundary layer) (Tang & Emanuel, 2012).

In the CMIP5 models there is a general tendency toward an increase in the seasonal ventilation index with warming in most basins, including the deep tropical region of the western North Pacific, which would inhibit both tropical cyclogenesis and intensification (Tang & Emanuel, 2014). In the CMIP5 multimodel mean this increase has a maximum around 10°N and 160°W, decreasing poleward and eastward of there. This change pattern would lead to a reduction of TC activity in the southern part of the basin and an increase poleward. There is also a decrease in the ventilation index in the central North Pacific, helping to explain the increase of TC activity near Hawaii. In summary, the large-scale environment in the CMIP5 projections and in the HWG GISS model simulations are coherent with the poleward and eastward track shifts discussed above.

6. Conclusions

We analyzed TC tracks in the Western North Pacific (WNP) basin in two large multimodel ensembles. These ensembles span a variety of model types (low and high horizontal resolution models, models forced with fixed SST, and coupled models) and tracks (explicit and downscaled). We used two primary methodologies to examine the tracks’ characteristics: a cluster analysis and mass moment ellipses. We applied these methods first to compare the model tracks with observed tracks, and second to examine if there are changes in the tracks in a warming climate that are statistically significant and robust across the ensembles. The impact of tracking methodologies on our analysis was explored, and our results do not depend on the tracking method for the cases analyzed. Furthermore, it should be noted that changes in genesis locations cannot be separated from the track changes by this methodology, as the genesis locations are inherently part of the detected tracks and the thresholds used in the different tracking algorithms.

The HWG models’ explicit tracks are much more similar to observed tracks than are the CMIP5 explicit tracks. This indicates that, all else equal, higher horizontal resolution yields more realistic tracks. However, an improvement with resolution was not apparent when comparing the tracks from three versions of an HWG model in three resolutions (even the lowest resolution of this model has a finer resolution than the CMIP5 models), with no additional modifications in the model. The downscaled tracks have a northeastward bias which is present in both the HWG and CMIP5 downscaled model tracks, indicating that these biases were not dependent on the models’ large-scale environments but rather appear to be features of the downscaling methodology.

We examined many characteristics of WNP tracks to determine if there were statistically significant and robust changes in future scenarios. There is an increase in variance of Y or south to north extent of the range over which the tracks occur for several models and clusters. As WNP tropical cyclones are bound on the southern end by the vanishing of the Coriolis parameter at the equator, this can be interpreted as a northern shift of the WNP TC tracks. This northern shift is not statistically significant at a particular point, such as the mean (centroid) or the LMI, but is very robust in the variance or extent of the model tracks.
There were also many models and scenarios that show eastern and northeastern shifts. As the WNP basin is bound on the west side by the Asian landmass, an extension in the variance of $X$ can be interpreted as an eastern movement and an extension in the variance of $XY$ as a northeastward movement. However, in most cases, the shifts in the centroid location are too small to be statistically significant, even when the variance shifts are statistically significant.

Some of the track changes described here have been previously noticed in the literature, to the extent that they are apparent in the statistics of the set of all WNP tracks. Here we pinpoint which track types, as defined by cluster analysis, are involved in specific track shifts. In some clusters, there is an increase in the variance in the latitudinal direction, while in others there is an eastward shift.

For the most frequent track type, recurving cluster A, while the centroid shifts are small, there is an increase in the south-north extent of the tracks with warming in both the HWG and CMIP5 simulations, effectively corresponding to a northward shift in the tracks. This is an important result, as cluster A has impacts throughout the region and occurs more commonly in La Niña events. Shifts in cluster A tracks could lead to significant changes in the landfall occurrences, as discussed in Kossin et al. (2016).

Another interesting case is the straight-moving Cluster F, which has an eastward mean shift in the centroid for CMIP5 models, which could lead to more storms in the Central Pacific and Hawaii. The other cluster with potential influence in Hawaii is the recurving cluster G. While there was no significant mean centroid location change for cluster G, the variance in both longitudinal and latitudinal directions increased in two of the HWG scenarios, which could be interpreted as an eastward (toward Hawaii) shift in the storms’ preferred formation region accompanied by a poleward shift in recurrance when compared to the twentieth century control simulation.

Changes in the large-scale environment in the CMIP5 multimodel mean and in the GISS model in the HWG simulation.

Changes in the large-scale environment in the CMIP5 multimodel mean and in the GISS model in the HWG simulation. Our results highlight the complexity of potential track changes in future climates, with different shifts occurring simultaneously for different track types. Furthermore, these track shifts are model and scenario dependent, highlighting the value of considering multiple models and scenarios when inferring robust changes in TC tracks in future climates. The upcoming multi-resolution multimodel simulations planned for CMIP6 will be a good opportunity to explore robustly the future track changes using high-resolution coupled models (Haarsma et al., 2016).

References


