

Large-scale industrial cloud perturbations confirm bidirectional cloud water responses to anthropogenic aerosols

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1 2 3	Large-scale industrial cloud perturbations confirm bidirectional cloud water responses to anthropogenic aerosols								
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10									
11	Key Points:								
12 13	• Satellite observations confirm aerosol-induced decreases in cloud droplet size in large areas compared to nearby less polluted areas								
14 15	• Aerosol-induced cloud water increases and decreases compensate each other at large spatial scales similarly to ship-track-like perturbations								
16 17	• On average, Twomey effect is more important than the effect of cloud water changes for the aerosol radiative forcing of the Earth's climate								

19 Abstract

20 Aerosols offset a poorly quantified fraction of anthropogenic greenhouse gas warming, and the 21 aerosol impact on clouds is the most uncertain mechanism of anthropogenic climate forcing. Here, observations of a relatively weak average response of liquid cloud water to aerosol 22 perturbations are extended to much larger areas than in previous studies, with the polluted cloud 23 24 areas covering hundreds by hundreds of kilometers. Polluted clouds detected in satellite images at the global anthropogenic air pollution hot spot of Norilsk, Russia, and at other various major 25 aerosol source regions show close compensation between aerosol-induced cloud water increases 26 and decreases. In the sampled Norilsk cloud perturbations the decrease in LWP offsets 3 % of 27 the radiative forcing through the Twomey effect on average. Weak cloud water response on 28 average in large polluted areas is in very good agreement with previous results based on 29 observations of small-scale ship-track-like industrial cloud perturbations, helping to reduce the 30 uncertainty associated with the anthropogenic aerosol impacts on clouds. 31

32

33 Plain Language Summary

34 It is unknown to what extent the global cooling effect of anthropogenic aerosols offsets the warming effect of anthropogenic greenhouse gases. The strength of the aerosol climate cooling 35 effect exerted through changes in the properties of clouds is especially uncertain. This hinders 36 better estimates of Earth's climate sensitivity to anthropogenic radiative forcing and more 37 38 reliable projections of future climate. It has been previously found that the average aerosolinduced cloud water change is relatively weak in smaller-scale ship-track-like polluted cloud 39 tracks. Here we analyze satellite observations of much larger-scale polluted cloud areas, with the 40 polluted cloud areas covering hundreds by hundreds of kilometers. Polluted clouds over Norilsk, 41 Russia, and over other various major aerosol source regions show close compensation between 42 43 aerosol-induced cloud water increases and decreases. Large scale polluted cloud areas indicate that the effect that aerosols have on cloud droplet sizes has a stronger impact on Earth's climate 44 45 than the effect caused by the cloud water changes. These results help to reduce the uncertainty associated with the anthropogenic aerosol impacts on clouds and Earth's climate. 46

47 0305 Aerosols and particles

48 1640 Remote sensing

- 49 3311 Clouds and aerosols
- 50 Aerosol-cloud interaction
- 51 Aerosol radiative forcing
- 52 Cloud water response
- 53

54 **1 Introduction**

Aerosols, through directly scattering and absorbing radiation and through acting as cloud condensation nuclei, have a cooling effect on the Earth's climate. The weakly constrained influence of aerosols on Earth's climate dominates the uncertainty in anthropogenic impacts on climate (Boucher 2013). Moreover, the limited knowledge of the radiative forcing induced by aerosols since preindustrial time hinders better estimates of climate sensitivity to radiative forcing from the observational record (Stevens et al., 2016; Bellouin et al., 2019).

Radiative forcing of climate through aerosol-cloud interactions is much more uncertain than aerosol-radiation interactions (Bellouin et al., 2019). Aerosols increase cloud droplet number concentration (CDNC) and decrease the size of cloud droplets and thereby raise the cloud albedo, an effect called the Twomey effect (Twomey et al., 1974). Increased CDNCs lead to cloud adjustments resulting in changes in the cloud water content and horizontal extent of clouds. The radiative forcing through cloud adjustments is especially uncertain (Bellouin et al., 2019). Here we focus on aerosol-induced changes in cloud water content.

It was previously postulated that aerosols unidirectionally increase cloud water content through 68 reduced precipitation due to decreased collision-coalescence efficiency of smaller cloud droplets 69 70 (Albrecht 1989). The assumption of unidirectionally increased liquid water path (LWP) caused by reduced precipitation is still used in general circulation models (GCMs) today (Quaas et al., 71 72 2009; Ghan et al., 2016; Mulcahy et al., 2018; Gettelman et al., 2019). However, this assumption has been strongly challenged by recent observational studies (e.g. Toll et al., 2019; Malavelle et 73 74 al., 2017). Aerosol perturbations can enhance the evaporation of cloud water and enhance entrainment of dry air that results in reduced LWP (Ackerman et al., 2004; Bretherton et al., 75 2007, Small et al., 2009; Hill & Feingold 2009). 76

Recent lines of evidence for average LWP response to anthropogenic aerosols are still
conflicting (Toll et al., 2019; Gryspeerdt et al., 2019; McCoy et al., 2019; Rosenfeld et al., 2019;

Malavelle et al., 2017). Analysis of relationships between CDNC and LWP indicate a considerable increase (McCoy et al., 2019) or decrease (Gryspeerdt et al., 2019) in LWP on average, depending on the analysis method. McCoy et al. (2019) estimated that the increase in LWP causes radiative forcing -1 W/m². In strong contrast with this, Gryspeerdt et al. (2019) estimated that decrease in LWP off-sets 62% of the radiative forcing by the Twomey effect.

84 The most direct approach to study aerosol-cloud interactions is to study temporal or spatial anomalies in cloud properties that are directly induced by aerosols (Toll et al., 2019). Malavelle 85 et al. (2017) found no significant change in LWP in the case of the eruption of the 2014 86 Holuhraun volcano compared to the years preceding the eruption. Toll et al. (2019) compared the 87 88 properties of the ship-track-like polluted cloud tracks to the properties of the nearby unpolluted clouds. These ship-track-like polluted cloud tracks are quasi-linear polluted cloud lines, where 89 90 cloud droplet size is decreased compared to the nearby unpolluted clouds. Toll et al. (2019) found good agreement between LWP changes in the ocean-based volcano and ship tracks and 91 land-based industry and fire tracks. Toll et al. (2019) estimated that on average, the decrease in 92 LWP offsets 29% of the radiative forcing by the Twomey effect, which is a relatively weak 93 94 offset compared to the estimates by McCoy et al. (2019) and Gryspeerdt et al. (2019).

A challenge to the representativity of cloud responses obtained by studies based on small-scale 95 pollution tracks is that mesoscale circulation could modulate the LWP response in pollution 96 97 tracks (Mülmenstädt & Feingold, 2018; Possner et al., 2018) The width of polluted cloud tracks studied by Toll et al. (2019) was limited to tens of kilometers and they sampled only a limited 98 number of larger-scale cloud perturbations in regions of Moscow, Russia and Kazakhstan. Here 99 we extend their analysis of polluted cloud tracks and analyze LWP responses to aerosols in 100 101 Norilsk, Russia and a variety of other regions with large-scale aerosol-induced gradients in cloud droplet size. All the analyzed data is unique to this study. The polluted cloud areas studied here 102 103 cover hundreds by hundreds of kilometers. We evaluate the level of agreement between LWP 104 responses in small-scale pollution tracks and large-scale aerosol-induced cloud perturbations.

105 **2 Methods**

We analyze the LWP responses to aerosols by directly comparing the properties of polluted clouds to those of the nearby unpolluted clouds following Toll et al. (2019) while focusing on large-scale aerosol perturbations on clouds (Fig. 1 and 2). First, we visually detect large-scale polluted areas on composite Terra Moderate Resolution Imaging Spectroradiometer (MODIS) satellite images from National Aeronautics and Space Administration (NASA) Global Imagery Browse Services (GIBS). In these composite images, MODIS bands corresponding to wavelengths $0.459-0.479 \mu m$, $1.628-1.652 \mu m$ and $2.105-2.155 \mu m$ are used. Polluted clouds stand out due to their enhanced near-infrared reflectance (Fig. 1 and 2).

114 After polluted clouds were identified in the images from NASA GIBS, polluted areas were 115 logged, using 2.1 µm band reflectance from Terra and Aqua MODIS retrievals. We identified polluted clouds visually as areas with enhanced reflectance on the 2.1 µm band images. 116 117 Enhanced 2.1 µm reflectance results from aerosol-induced decreases in cloud droplet radii (Coakley et al., 1987). In each case, the polluted cloud was sampled at least from 4 different 118 119 directions; if possible, from the intercardinal directions. For each direction, we manually drew a line along a horizontal gradient in near-infrared reflectance (from unpolluted clouds into polluted 120 clouds). The length of the line depends on the spatial scale of polluted clouds and on the strength 121 of the contrast between polluted and unpolluted clouds. Then we classified pixels in a 60 km 122 123 wide segment around the gradient-line as polluted or unpolluted (Fig. 3) following Toll et al. 124 (2019). We calculated the mean reflectance within the first 20% of the line length, where pixels with lower near-infrared reflectance were situated. Pixels are classified as polluted if their 125 reflectance is two standard deviation above this value and they are situated in the last 40 % of the 126 line length (Fig 3). Because of the 2-sigma criterion, 38 data tracks were discarded, because there 127 128 was not enough contrast between polluted and unpolluted clouds to include them in the analysis. 129 This way we can be confident that we are looking at aerosol perturbations on clouds. We studied polluted clouds at the SO₂ pollution hot spot of the nickel processing site in the city of Norilsk in 130 Russia, and in various continents at major aerosol source regions (Fig. 4). The sulfur dioxide 131 emissions for Norilsk have been estimated to be over 2 Mt per year by Carn et al. (2004). With 132 global anthropogenic SO₂ emissions in the order of 100 Mt per year (Smith et al., 2011), this 133 makes Norilsk an extraordinarily strong localized source of SO₂. The other regions where 134 polluted clouds have been studied include major industrial regions in Europe, Eastern United 135 States and Eastern Asia. In addition, a few cases where smoke from wildfires have caused 136 137 changes in cloud properties have been analyzed. These observations sample a wider geographical

area compared to large-scale cloud perturbations in Moscow area, Russia and Kazakhstanstudied by Toll et al. (2019).

We collected 1164 observations of polluted clouds for the Norilsk area, with sampled dates 140 141 ranging from 2000 to 2017. In addition, we collected 99 observations for various regions for the period of 2012 to 2018 (Fig. 4). The observations from Norilsk are quite evenly distributed over 142 143 the summer months: from the end of May until the middle of September (Fig. 5). At the latitude of Norilsk, low-level liquid-water clouds are observed mostly only during this warmer time of 144 145 the year. Non-Norilsk cases are quite evenly distributed over the whole year. Norilsk, being an isolated pollution hot spot, provided suitable observations of pollution-induced steep gradients in 146 147 cloud droplet size throughout the time series in the warm season (Fig. 5). There are fewer observations for other locations due to more polluted background conditions, which make the 148 polluted cloud areas dimmer. In addition, identifying large scale polluted cloud areas is more 149 difficult compared to identifying ship-track-like perturbations. Meteorological conditions or the 150 amount of pollution are probable reasons for the more numerous observations from Norilsk than 151 from other isolated factories. As we have much fewer observations for non-Norilsk areas, the 152 153 statistics for these other regions are not as robust as for Norilsk and we concentrate in the 154 analysis only on the data from Norilsk. Still, the analysis of non-Norilsk cases provides additional physical insights, as they show clear bidirectional LWP responses (Table 1). 155

156 After classifying satellite pixels as polluted or unpolluted for each segment, we calculate segment-average cloud properties for polluted and unpolluted clouds. For this, we used MODIS 157 cloud products MOD06_L2 (Terra) and MYD06_L2 (Aqua) (Platnick et al., 2017). The 2.1-µm 158 159 near-infrared channel-based cloud properties were used. To ensure that only low-level liquidwater clouds are studied, only pixels with a single layer (cloud multilayer flag = 1) and low-level 160 clouds (cloud top pressure less than 500 hPa) were included. Pixels for which the cloud phase 161 162 determined by infrared observations was identified as ice or mixed-phase, and those with ice 163 cloud retrievals were excluded. In order to exclude weak cloud perturbations, we only retained cases where the cloud droplet effective radius was decreased by more than 2 µm. This is a 164 relatively strong decrease in cloud droplet size, compared to the average cloud droplet effective 165 radius of 16 µm observed in unperturbed clouds. In Norilsk, 13 data tracks were filtered out 166 because of the 2 µm threshold. It did not have any impact on the mean values in Table 1. 167

To compare meteorological conditions under which the polluted cloud areas were sampled in 168 Norilsk and other areas, MODIS-retrieved cloud top height (CTH) is used. Lower tropospheric 169 stability (LTS) was calculated as the difference between the potential temperature at 700 hPa and 170 the surface. The data for these temperatures and for relative humidity (RH) at 700 hPa was taken 171 from ERA-Interim global atmospheric reanalysis (Dee et al., 2011) We calculated the latitude 172 and longitude of the middle point of the perturbation area and then we defined the area as 173 latitude ± 0.5 degree and longitude ± 0.5 degree. We chose the time that was closest to that of the 174 MODIS observation. 175

176

177 **3 Results**

178 We detected cloud perturbations through the near-infrared signature of changes in cloud droplet effective radius (R_{eff}). The frequency distributions of R_{eff} for polluted and unpolluted clouds 179 180 reveal nearly distinct distributions (Fig. 6), the R_{eff} of the polluted clouds is smaller than 12 µm in 97% of cases. In unpolluted clouds, the Reff is smaller than 12 µm in 13% of cases. Aerosol 181 pollution decreased the radius of cloud droplets on average by 50%, from 15.9 µm down to 7.9 182 µm. Such strong decreases in Reff means we are analyzing very strong cloud perturbations, where 183 we can be confident that aerosols have impacted clouds. These strong decreases in R_{eff} contribute 184 to increased COD and albedo in polluted clouds compared to the unpolluted clouds (Fig. 7). 185

186 In agreement with Toll et al. (2017) and Toll et al. (2019), we found that LWP of individual clouds can both significantly increase or decrease as a response to aerosol pollution (Fig. 7). 187 Some of the clouds nearly evaporated, while in other cases the unpolluted LWP was multiplied 188 by up to 8 times. Toll et al. (2019) explained that meteorological conditions control whether 189 LWP increases or decreases in an individual case. Based on Toll et al. (2019) LWP tends to 190 increase in lower, thinner and precipitating clouds and in clouds below moist air and tends to 191 decrease in higher, thicker and non-precipitating clouds and in clouds below dry air. The relative 192 contributions of logarithmic LWP and Reff changes to the relative change in COD are given by 193

194

$$\Delta \ln(COD) = \Delta \ln(LWP) - \Delta \ln(R_{eff}). \tag{1}$$

While by construction (Equation 1) the logarithmic changes in LWP and in R_{eff} have the same 196 weight on the relative change in COD, the logarithmic LWP changes are much broader than the 197 changes in R_{eff}. Because of that, in most cases, changes in LWP dominate the changes in COD 198 and changes in Reff are of secondary importance for COD changes. However, the changes in Reff 199 dominate on average, because the changes in LWP closely cancel out each other (Fig. 7). The 200 201 average COD was increased by 80% from the average unpolluted value in Norilsk (Table 1). However, in 16% of cases COD was decreased, meaning a decrease in cloud albedo as well (Fig. 202 8). In those cases, the decrease in R_{eff} increases COD, but the decrease in LWP is so strong that 203 COD decreases overall. 204

205 The frequency distribution of relative magnitudes of LWP increases and decreases reveals very close compensation between LWP increases and decreases, both in terms of frequency and 206 magnitude (Fig. 7). On average, LWP decreases by 10% in the polluted clouds compared to the 207 nearby unpolluted clouds (Table 1). Also, the frequency distributions of polluted and unpolluted 208 LWP, while largely overlapping, show slightly more frequent values of lower LWP for polluted 209 clouds (Fig. 6). The frequency distribution of $-\Delta \ln (COD)/\Delta \ln (R_{eff})$ (Equation 1) shows that in 210 211 individual cases the relative contribution of LWP changes to COD changes is up to four times 212 stronger than the relative contribution through decreased R_{eff} (Fig 8). But the average value of $-\Delta \ln (COD)/\Delta \ln (R_{eff})$ is 0.97, which is quite close to the value of 1 that indicates no change in 213 LWP on average. 214

The polluted clouds were sampled under a rather wide range of meteorological conditions (Fig. 215 9). Even considering the Norilsk cases alone gave that wide range of meteorological conditions 216 217 but adding non-Norilsk cases extended the range further. Relative humidity was lower for non-Norilsk cases, with an average value of 31 %, compared to 52 % at Norilsk. The average lower 218 tropospheric stability was 16.7 K for non-Norilsk cases, and 13.7 K for Norilsk. The cloud top 219 220 was slightly higher on average for non-Norilsk cases with a mean value of 2380 m, compared to 221 2200 m at Norilsk. For large-scale cases the dependence of cloud water response on meteorological conditions is noisy so studying meteorological dependence requires a larger 222 number of observations and more automated methods of track detection. 223

224 **4 Discussion and conclusions**

We analyzed cloud responses to large-scale aerosol perturbations. The areal extent of the polluted cloud areas detected in MODIS satellite images extended to hundreds by hundreds of kilometers (Fig 1 and 2). Most of the analyzed clouds originated from the aerosol pollution hot spot of nickel processing factories in Norilsk, Russia. We demonstrated that such large-scale aerosol-induced cloud perturbations exist in various regions (Fig 4).

230 Our analysis of large-scale cloud perturbations supports the close compensation between aerosolinduced cloud water increases and decreases that was previously found in smaller-scale polluted 231 232 cloud tracks and a limited number of larger-scale polluted cloud areas (Toll et al., 2017; Toll et al., 2019). On average, liquid cloud water response is relatively weak both in the Norilsk area 233 234 and for non-Norilsk cases collected for various aerosol sources around the world. Still, in individual cases, there can be strong increases or decreases in LWP. The large-scale gradients in 235 cloud droplet size at major aerosol sources analyzed here confirm the existence and importance 236 of the Twomey effect in various regions. Moreover, as the average change in cloud water is 237 small, our analysis supports the dominance of the Twomey effect over the effect of LWP 238 response in the radiative forcing as found in the smaller-scale polluted cloud tracks (Toll et al., 239 2017; Toll et al., 2019). Our analysis of large-scale cloud perturbations for Norilsk gives an 240 241 average value of 0.97 for the sensitivity $-\Delta \ln(\text{COD})/\Delta \ln(R_{\text{eff}})$, meaning that the decrease in LWP offsets 3% of the radiative forcing through the Twomey effect. Although the estimate of 3% is 242 much smaller than the previous estimate of 29% based on smaller-scale pollution tracks by Toll 243 et al. (2019), the variability in LWP responses is too large to assess whether that difference is 244 245 statistical or due to differences in cloud adjustment processes. Nevertheless, in both cases adjustments are a small fraction of the initial forcing. 246

The existence of large-scale areas with decreased cloud droplet radii induced by industrial 247 pollution highlights the importance of the Twomey effect in aerosol forcing. The limited number 248 249 of observations means that they are unlikely to be representative of the globally averaged LWP 250 response. However, the large-scale perturbations studied here are probably more representative of the global average than the smaller-scale polluted clouds that have been used before, so it will 251 be useful to collect a large number of larger-scale perturbations. This study strengthens the 252 conclusion of previous pieces of evidence (Toll et al., 2017; 2019; Malavelle et al. 2017) that 253 rapid adjustments in LWP only provide a relatively weak contribution to the radiative forcing of 254

aerosol-cloud interactions. Importantly, a weak average change in LWP does not rule out a
strong increase in cloud fraction in response to anthropogenic aerosols (Rosenfeld et al., 2019),
so strong global cooling effect caused by cloud adjustments is still possible. Further work will
analyze the cloud fraction responses to aerosols in addition to LWP responses.

In the case of smaller-scale polluted cloud tracks like in Toll et al. (2019), the polluted clouds 259 260 can be linked to a single aerosol point source. Linking polluted clouds to a single source of air pollution is more difficult in the case of larger-scale cloud perturbations. In the Norilsk area, it 261 262 was possible to link polluted clouds to nickel production factories thanks to the strong contrast in cloud droplet radii between the polluted and nearby unpolluted clouds. In other regions, we were 263 not able to pin-point a single pollution source responsible for the cloud perturbation in each case. 264 Instead, multiple aerosol sources or even larger industrial regions were most probably 265 responsible for the decreased cloud droplet radii. Still, there could be other factors contributing 266 to differences in cloud properties. We cannot entirely exclude the potential contribution of urban 267 heat islands or differences in surface characteristics in urban areas compared to the nearby rural 268 areas to the differences in cloud properties but note that the observed reduction in cloud droplet 269 270 effective radius follows our expectations of the physics of the Twomey effect. Aerosol above 271 clouds can impact satellite retrievals (Peers et al., 2019), and this can potentially have some impact on our analyses. 272

273 Our finding of a weak average LWP change in response to aerosols strongly disagrees with the assumption of universally increased LWP used in global climate models (Quaas et al., 2009, 274 Ghan et al., 2016; Mulcahy et al., 2018; Gettelman et al., 2019). In addition to adding to existing 275 276 pieces of evidence challenging the unidirectional LWP increases assumed in GCMs (Malavelle 277 et al., 2017; Toll et al., 2019), the large-scale aerosol-induced cloud perturbations studied here are especially useful in a GCM context because they cover the area of several grid boxes of a 278 279 typical current GCM. Our analysis of large-scale polluted cloud areas indicates that the 280 differences between LWP responses in models and observations are not due to scale issues. The satellite observations of polluted clouds analyzed here can help to improve physical 281 parameterizations used in GCMs and lead to more reliable projections of the future climate. 282 Although the total number of sampled large-scale cloud perturbations is still limited, these 283 observations could be used for process-scale studies about aerosol impacts on clouds. The 284

number of the polluted cloud areas could be increased in the future using machine learning
methods to detect polluted clouds in the satellite images automatically (Yuan et al., 2019).

287

288 **5 Acknowledgments and data availability**

This study was funded by the Estonian Research Council personal research funding grant 289 PSG202.The RGB images (MODIS channels 3-6-7) used for the visual detection of polluted 290 clouds from https://worldview.earthdata.nasa.gov/ were used. The MODIS timestamps and 291 locations of the studied cloud perturbations are available at http://datadoi.ee/handle/33/190. The 292 MODIS cloud products MYD06_L2 from Aqua and MOD06_L2 from Terra used in this study 293 294 are available from the Atmosphere Archive and Distribution System (LAADS) Distributed 295 Active Archive Center (DAAC), https://ladsweb.nascom.nasa.gov/. The temperature and relative humidity data used in this study is available from ERA-Interim global atmospheric reanalysis, 296 297 https://www.ecmwf.int/en/forecasts/datasets/reanalysis-datasets/era-interim.

298 Author contributions

VT designed the study. HT identified the polluted cloud areas in the satellite images and analyzed the observations. All authors contributed to the writing of the manuscript.

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Figure 1. Examples of polluted clouds at Norilsk as seen from MODIS near-infrared composite 384 satellite images. Polluted clouds are shown in grey-white colors and unpolluted clouds in yellow-385 brown colors. Green color that can be seen from the cloud-free areas is vegetation. Red color 386 indicates the presence of ice or snow. The aerosols inducing the polluted cloud area originate 387 from Norilsk factories, which are marked with a red dot. (a) Image was taken on August 26, 388 2006. The image covers area bounded by 83.3°E and 88.2°E in longitude and 65.3°N and 69.6°N 389 in latitude. The maximum length and width of the track are 511 km and 145 km. (b) Image was 390 taken on June 27, 2000. The image covers area bounded by 86.8°E and 97.5°E in longitude and 391 63.9°N and 69.9°N in latitude. The Maximum length and width of the track are 415 km and 215 392 km. 393



Figure 2. Further examples of polluted clouds. Polluted clouds are shown in grey-white colors 395 and unpolluted clouds in yellow-brown colors. Red dots mark approximate locations of aerosol 396 sources that induce the polluted cloud areas. Only parts of the sources are shown for illustration. 397 (a) Pollution downwind of urban and industrial sources in Europe, March 19, 2016. The image 398 399 covers area bounded by 0.5°E and 7.9°E in longitude and 49.2°N and 53.1°N in latitude. The maximum length and width of the track are 330 km and 130 km. (b) Clouds polluted by wildfire 400 401 smoke in Russia, September 30, 2016. The image covers area bounded by 97.6°E and 106.2°E in longitude and 57°N and 64°N in latitude. The maximum length and width of the track are 320 402 km and 566 km 403





Figure 3. Classification of pixels as polluted and unpolluted. (a) A line was drawn on the 2.1-406 407 µm reflectance image, starting from the unpolluted clouds with lower reflectance and ending in the polluted clouds with elevated reflectance. A 60-km wide segment around the line was 408 analyzed. (b) Pixels in this segment were classified as polluted (red) or unpolluted (blue). The 409 green pixels are not included in the analysis. (c) The blue line is the mean reflectance within the 410 first 20% of the line length from the starting point, i.e. within the unpolluted clouds. The red line 411 is two standard deviations above the blue line. Pixels are classified as polluted (red) if their 412 reflectance is above the red line and situated in the last 40% of the track, and classified as 413 unpolluted (blue), if their reflectance is under the red line and in the first 40% of the track. 414 415



416417 Figure 4. The locations of analyzed polluted clouds.



Figure 5

421 Seasonal distribution of observations in Norilsk. All Norilsk cases are included in this figure 422 (there were no cases from October until the middle of May).



Figure 6. Frequency distributions of cloud droplet effective radius (R_{eff}), liquid water path
(LWP) and cloud optical depth (COD) for polluted and unpolluted clouds in Norilsk.

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Figure 7. (b) Susceptibility of cloud optical depth (*COD*) to liquid water path (*LWP*) changes in Norilsk. The logarithmic changes in cloud droplet effective radii (R_{eff}) for individual tracks are given in color. The dashed line is the *COD* susceptibility to *LWP* changes if there were no changes in R_{eff} . (a) Frequency distribution of Δln (*LWP*).



Figure 8. Frequency distribution for $-\Delta ln$ (COD)/ Δln (R_{eff}) in Norilsk, where COD is cloud optical depth and R_{eff} is cloud droplet effective radius. The bin width is 0.5. The mean value of $-\Delta ln$ (COD)/ Δln (R_{eff}) is 0.97. Liquid water path is increased in polluted clouds if this ratio is larger than 1 and decreased otherwise. If this ratio is less than than 0, then the COD and the cloud albedo is decreased in the polluted clouds. The values of zero and one are marked with the blue dashed lines. The cloud albedo was decreased in 16.4% of cases. 44% of cases are right of the 1 line.





Figure 9. Meteorological conditions for cases with polluted clouds: lower tropospheric stability
(LTS) [K], cloud top height (CTH) [m], relative humidity (RH) [%] at 700 hPa.

452 **Table 1.** Average cloud droplet effective radius (R_{eff}), liquid water path (LWP) and cloud optical

depth (COD) of polluted and unpolluted clouds. All cases include observations both from
 Norilsk and non-Norilsk cases. Standard deviation is given in the parenthesis.

454 Norilsk and non-Norilsk cases. Standard deviation is given in the parenthesis.455

	Norilsk cases (1164)			Non-Norilsk cases (99)			All cases (1263)		
	Unpolluted	Polluted	Fractional	Unpolluted	Polluted	Fractional	Unpolluted	Polluted	Fractional
	area	area	change	area	area	change	area	area	change
R _{eff}	15.9 (4)	7.9 (2)	-0.5	14.4 (3)	8.4 (2)	-0.4	15.8 (4)	7.9 (2)	-0.5
LWP	142.0 (80)	125.6	-0.1	184.5 (79)	141.0	-0.2	145.3 (81)	126.8	-0.1
		(74)			(71)			(74)	
COD	14.1 (8)	25.6 (15)	+0.8	21.6 (12)	26.8 (12)	+0.2	14.6 (8)	25.7 (15)	+0.8

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Figure 1.





Figure 2.





Figure 3.



C)



Pixel classification

Figure 4.



Figure 5.



Figure 6.



Figure 7.



Figure 8.



Figure 9.





Norilsk

Non-Norilsk cases

